

SCENE STATISTICS AND DIVISIVE NORMALIZATION

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VNIVERSITAT
D VALÈNCIA

SPAIN

<http://isp.uv.es>

Workshop on Computational Models for Visual Image Processing 2021

https://www.cfp.upv.es/formacion-permanente/curso/taller-modelos-computacionales-procesamiento-visual-imagenes_71578.html

So far (in previous talks)...

FACTS:

METHODS:

APPLICATIONS:

So far (in previous talks)...

FACTS:

- Cone Sensitivities & Adaptation _____ (Stockman)
- LMS noisy response _____ (Wandell)
- Tristimulus colorimetry _____ (Huerfias)
- Contrast Sensitivity _____ (Mantiuk)
- Opponent Color Spaces & CAMs } - (Fairchild)
- Spatial Masking

METHODS:

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METHODS:

- o Psychophysics _____ (Darraga & Garcia-Perez)
- o Display Calibration _____ (Murdoch)
- o Data Analysis _____ (Camacho)

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METHODS:

- o Psychophysics _____ (Darraga & Garcia-Perez)
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- o Data Analysis _____ (Camacho)

- ## APPLICATIONS:
- Perceptually Rated Images _____ (Pedersen)

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YES, THE VISUAL BRAIN BEHAVES THAT WAY...

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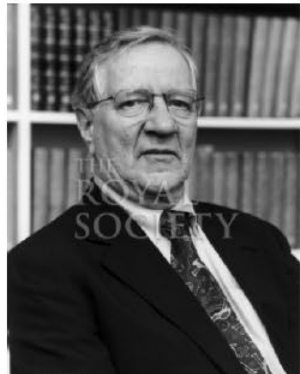
WHY?

OUTLINE:

- ① The WHY question
- ② One example: empirical models
- ③ Information theory tools
- ④ Natural scenes
- ⑤ The two sides of Efficient Coding
- ⑥ Open issues

OUTLINE:

BARLOW



①

The WHY question

②

One model

③

Info. theory tools

SPCA
RBIG

④

Natural scenes

⑤

The two sides of Efficient Coding

⑥

Open issues

Martinez et al. **PLOS** 2018

<https://isp.uv.es/code/visioncolor/vistamodels.html>

Malo & Gutiérrez **Network** 2006

Laparra et al. **Neural Comp.** 2012

Laparra et al. **IEEE J. Sel. Top. Sign. Proc.** 2015

Laparra et al. **IEEE Trans. Neur. Nets.** 2011

<https://isp.uv.es/RBIG4IT.htm>

https://isp.uv.es/data_color.htm

Gutmann, Laparra, Hyvarinen & Malo **PLOS** 2014

Laparra & Malo **Front. Neurosci.** 2015

Gomez-Villa et al. **Vision Res.** 2020

Malo & Simoncelli **IEEE Trans. Im. Proc.** 2006

Malo & Laparra **Neural Comp.** 2010

Gómez-Villa et al. **J. Neurophysiol.** 2020

Malo **J. Math. Neurosci.** 2020

Martinez et al. **PLOS** 2017

Martínez et al. **Front. Neurosci.** 2019

Li, Gómez, Bertalmío & Malo **Submitted JoV.** 2021

Bertalmío et al. **Scientific Reports** 2020

Esteve et al. **Arxiv.** 2020

①

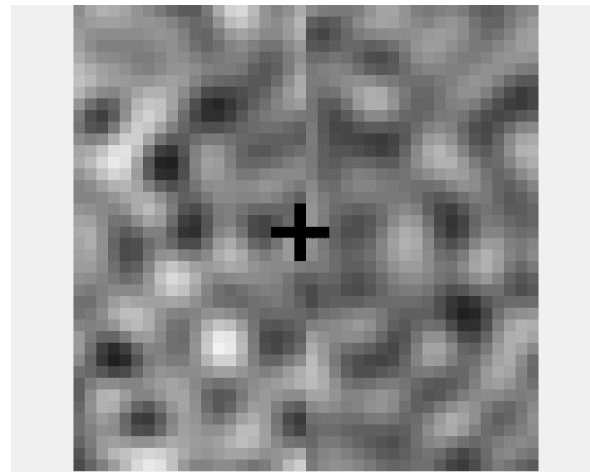
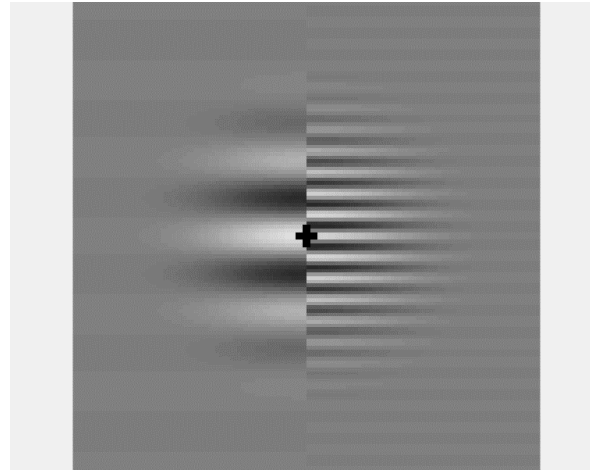
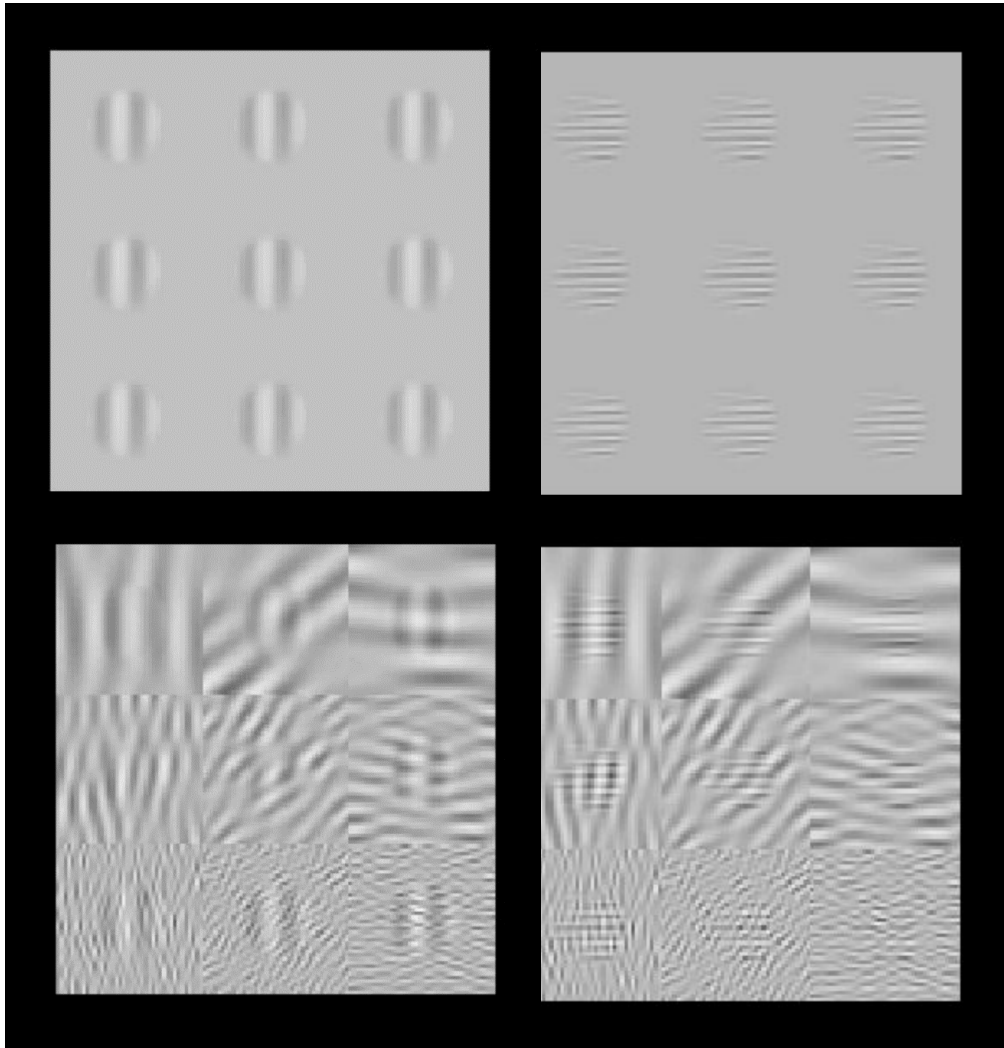
ONE EXAMPLE:

Frequency sensors and non-linearities
Image-computable models

- Different behaviors described by A SINGLE MODEL
- Linear Sensors + Divisive Normalization
- Empirical image-computable models

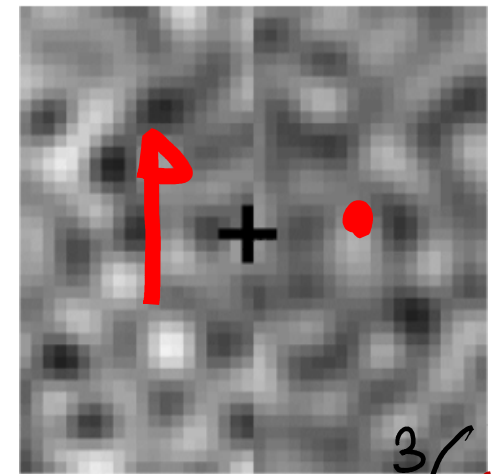
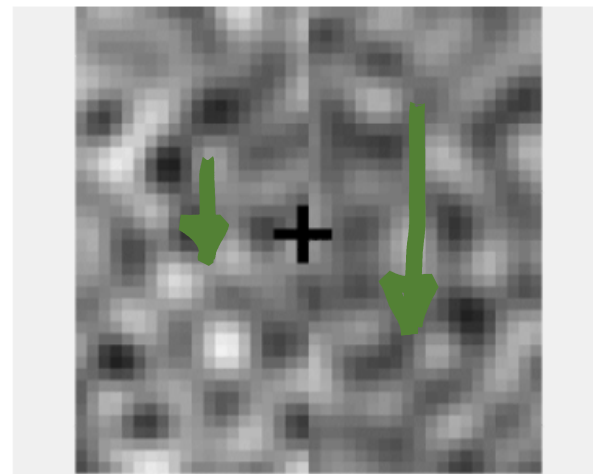
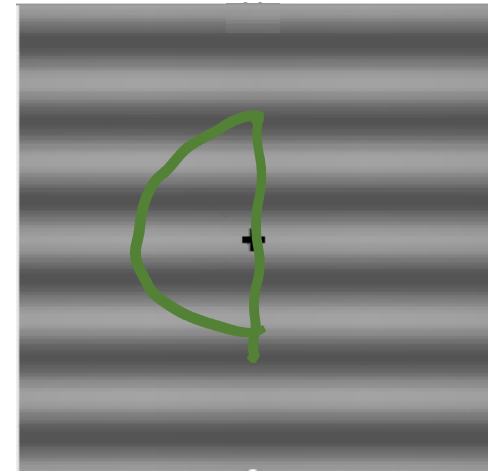
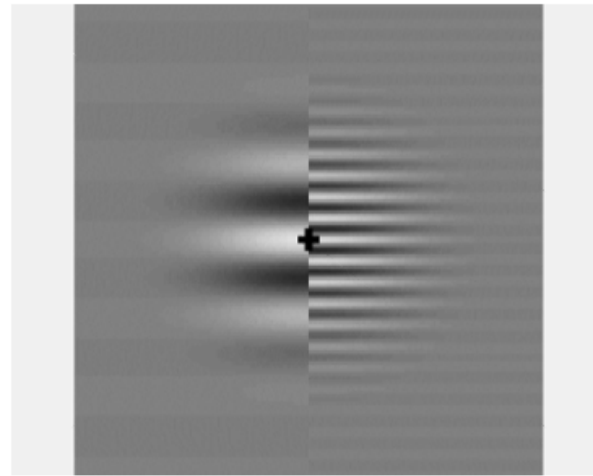
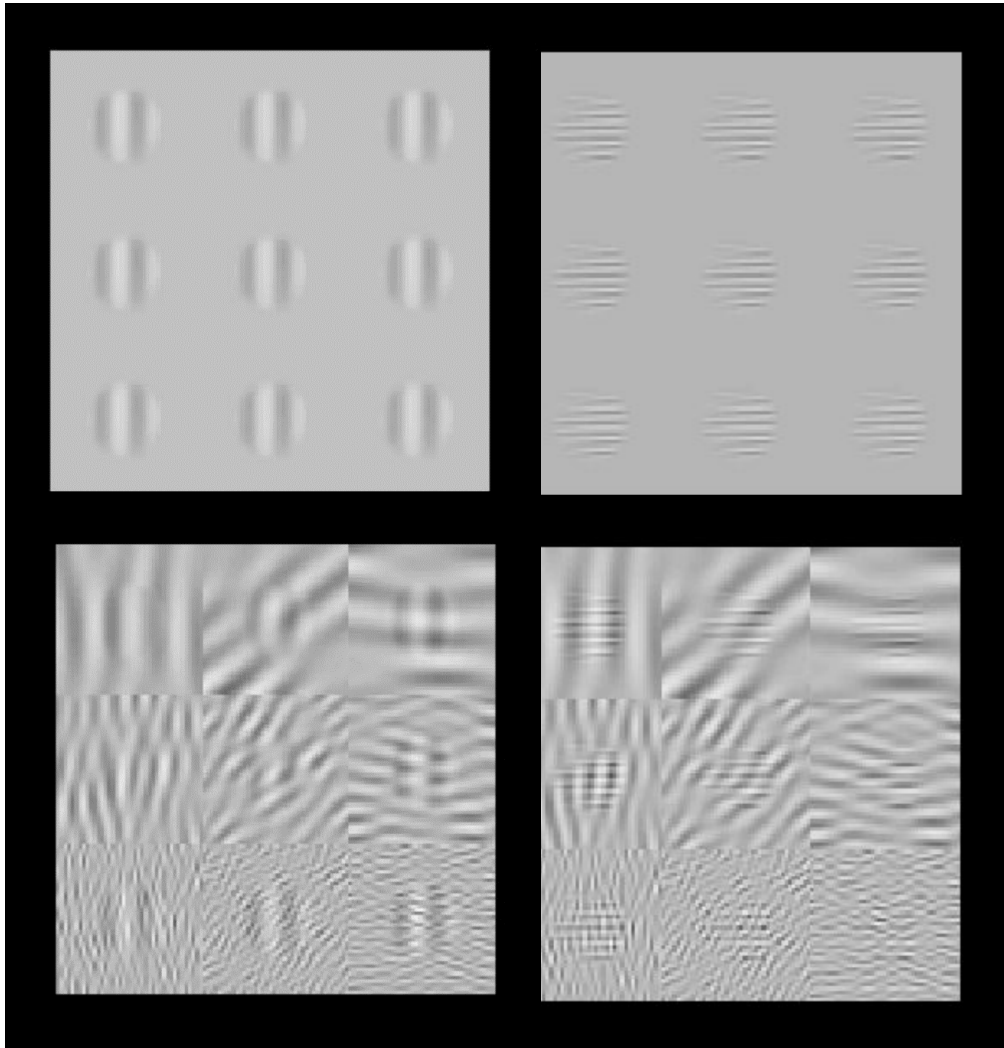
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Frequency sensors and non-linearities
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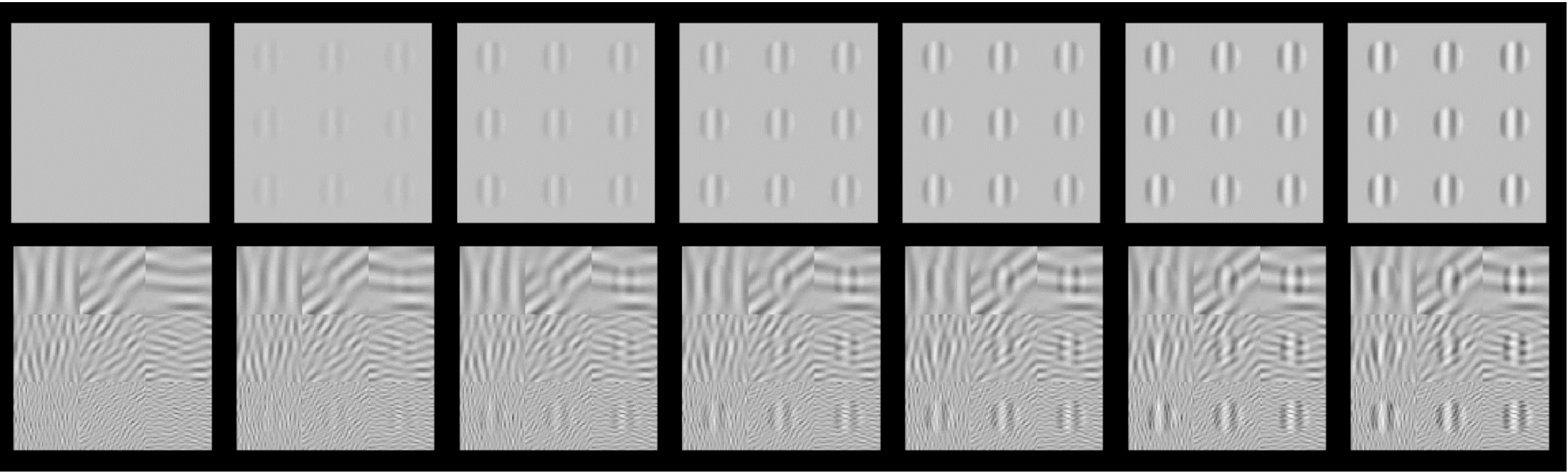
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Frequency sensors and non-linearities
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NO BACKGROUND

SIMILAR
BACKGROUND

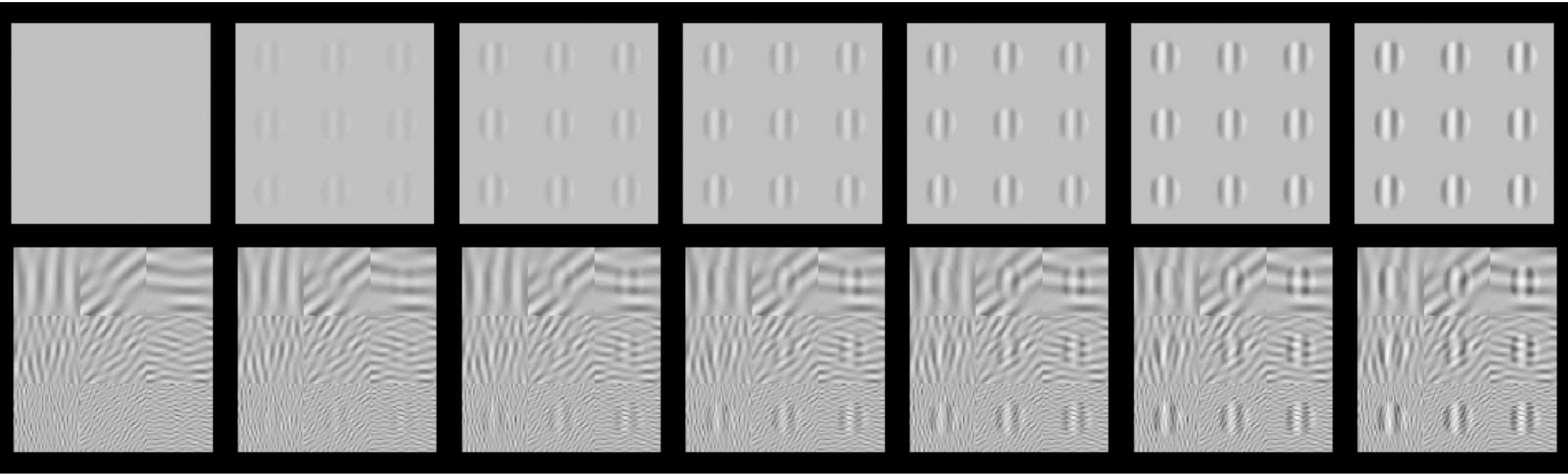
DIFFERENT
BACKGROUND

Martinez et al. Front. Neurosci 2019

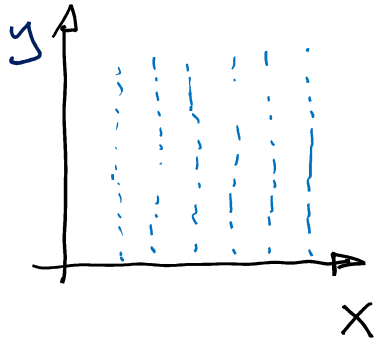
Watson & Solomon JOSA 1997 ^{4/} 41

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Frequency sensors and non-linearities
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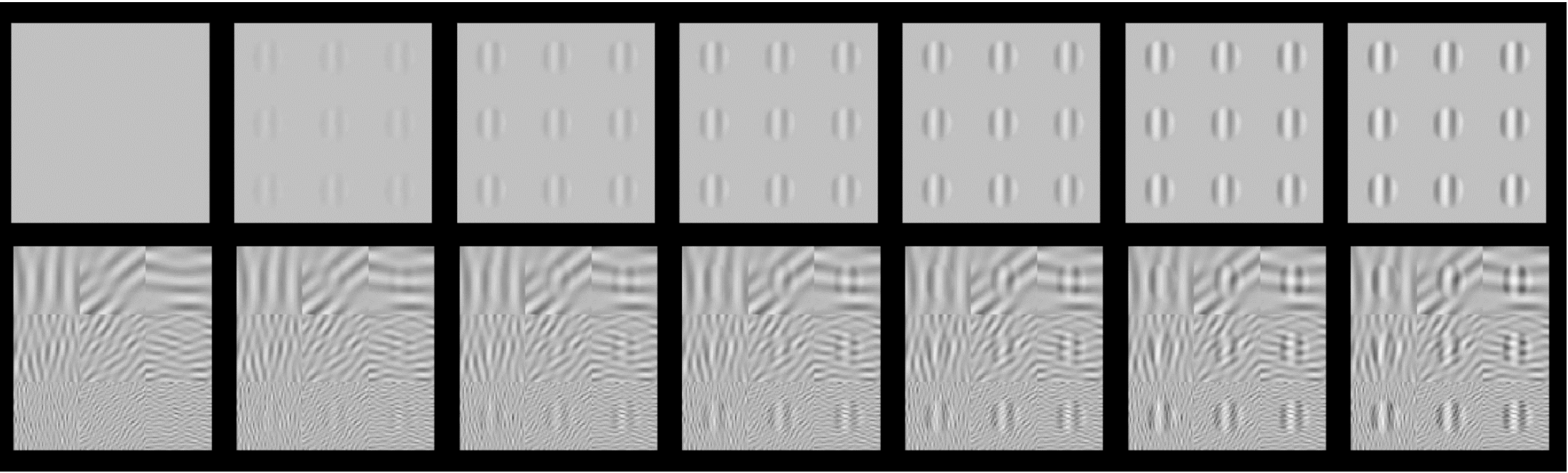
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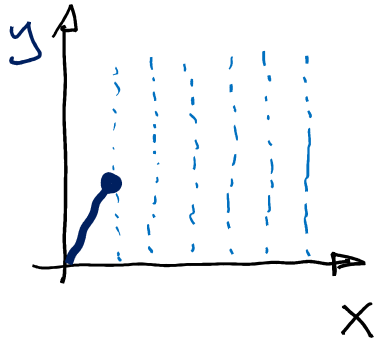
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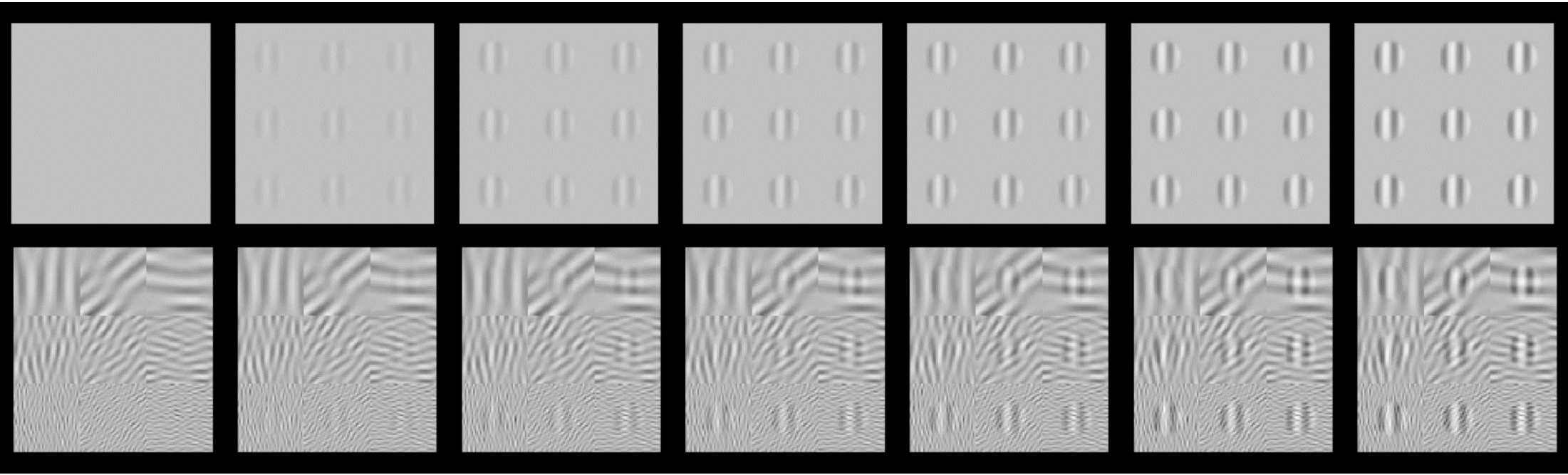
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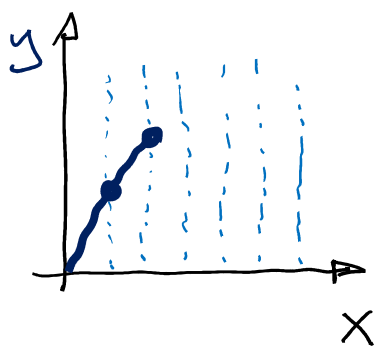
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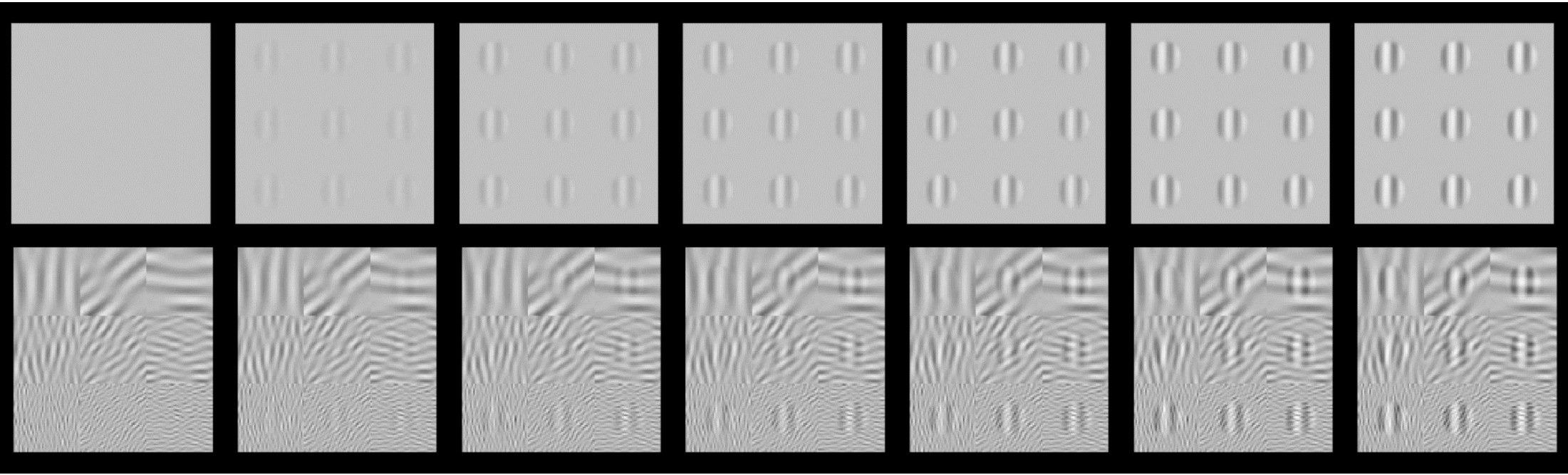


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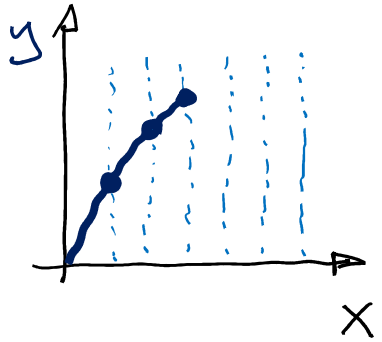
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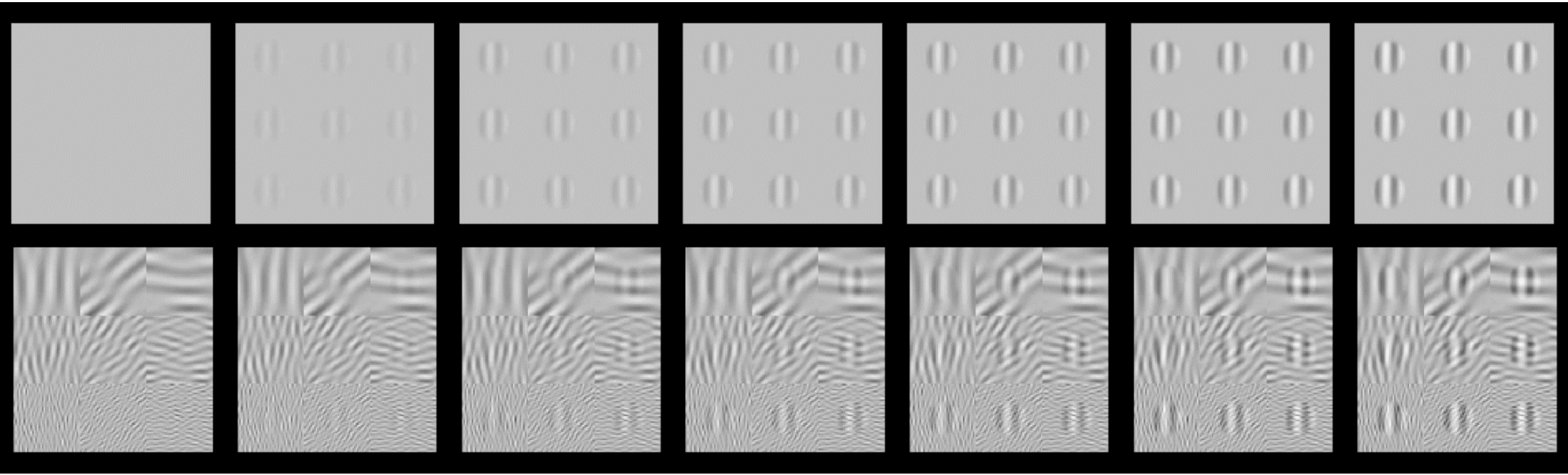
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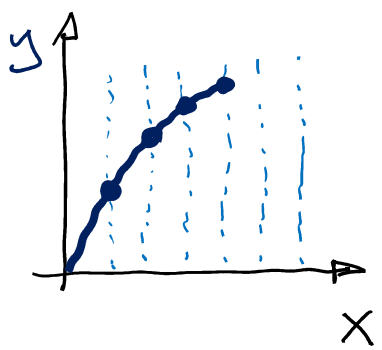
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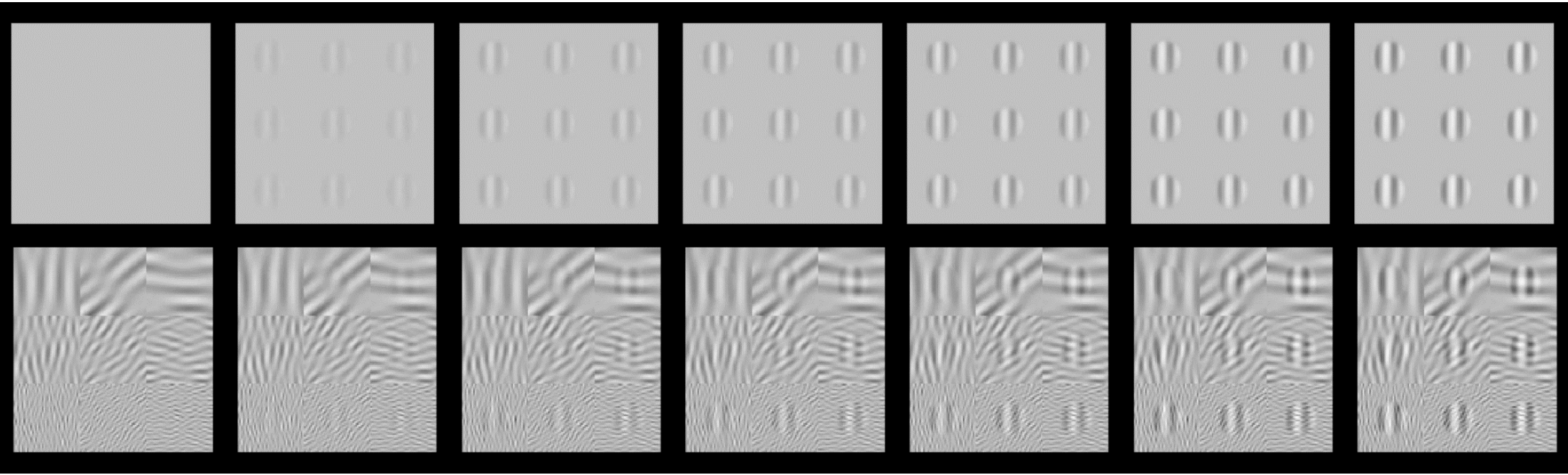
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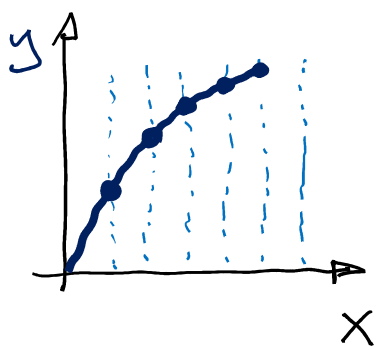
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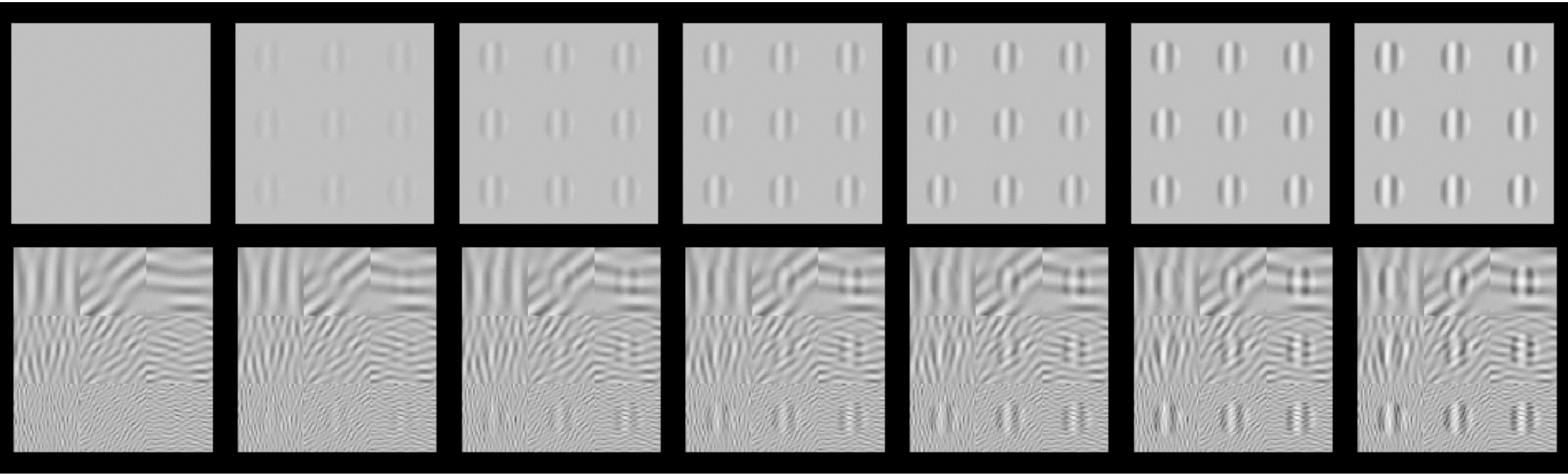
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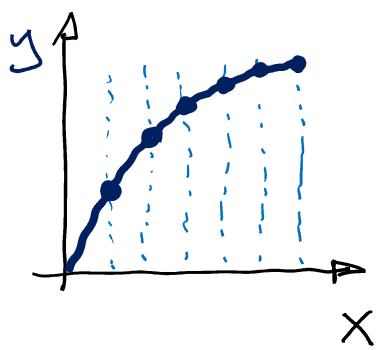
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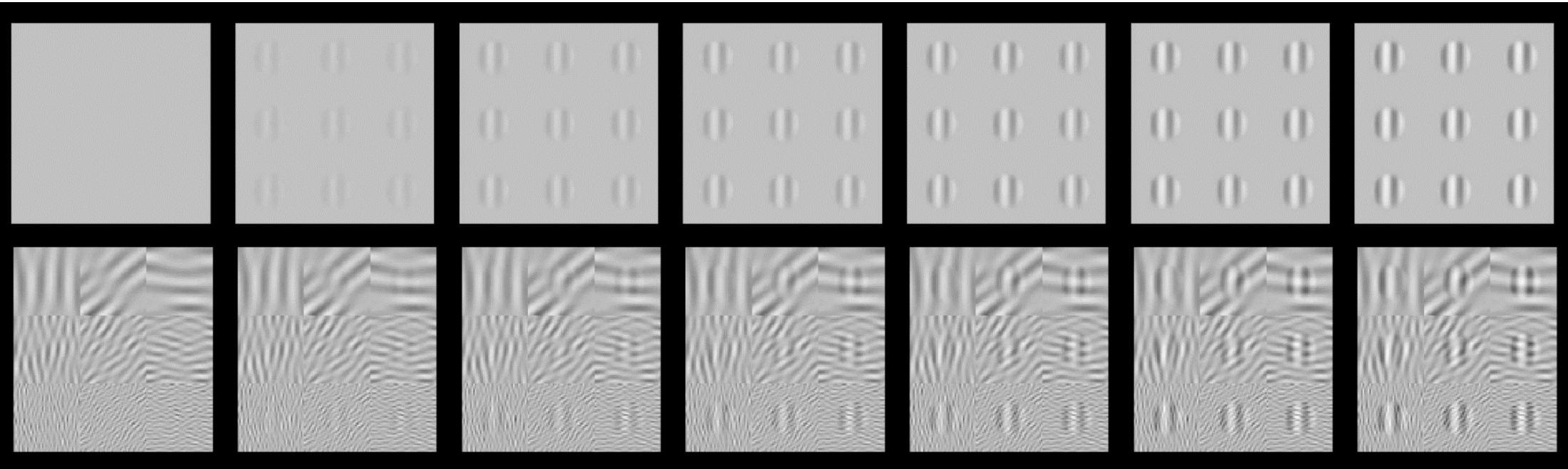
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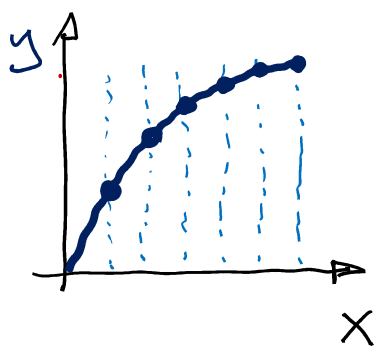
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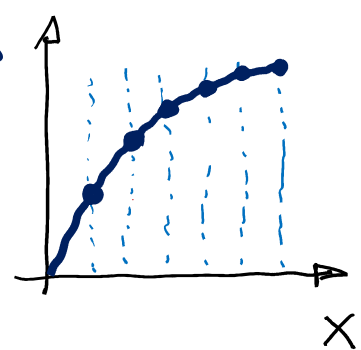


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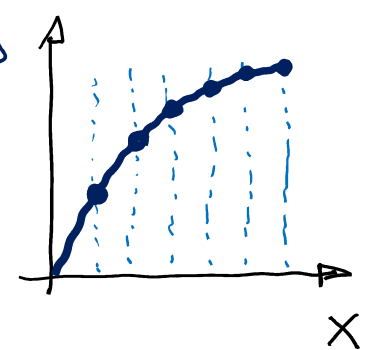
SIMILAR BACKGROUND

$$f \sim f'$$



DIFFERENT BACKGROUND

$$f \neq f'$$

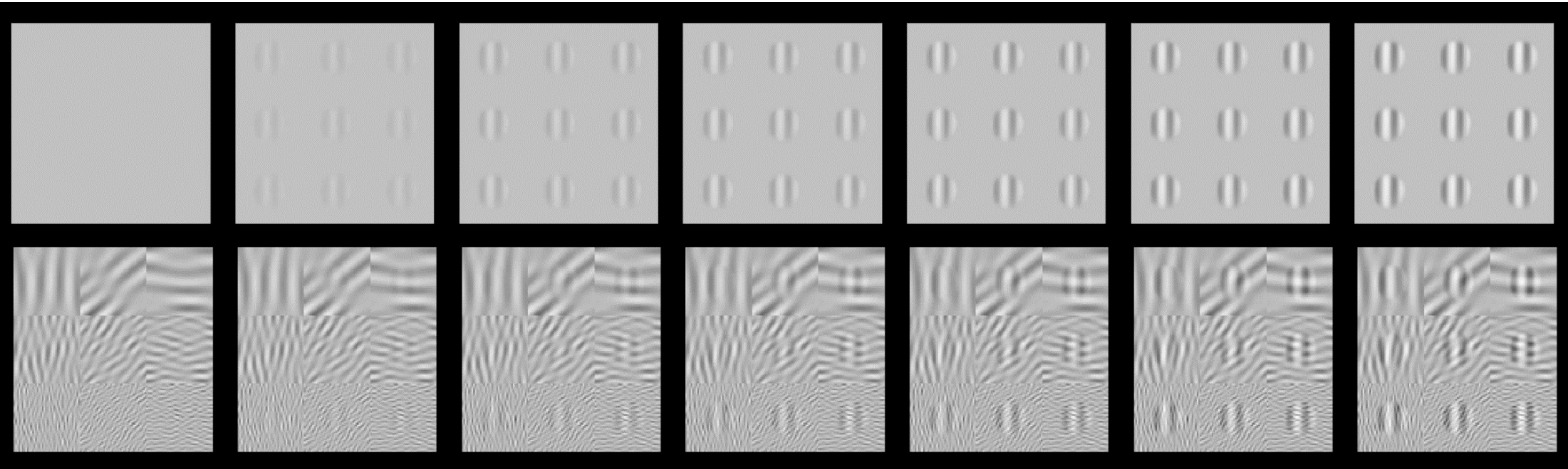


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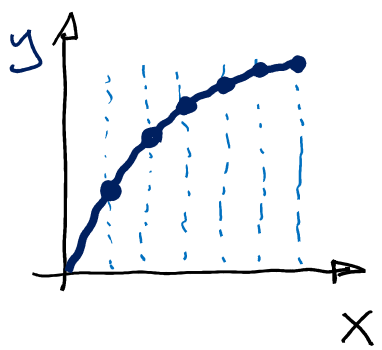
Watson & Solomon JOSA 1997

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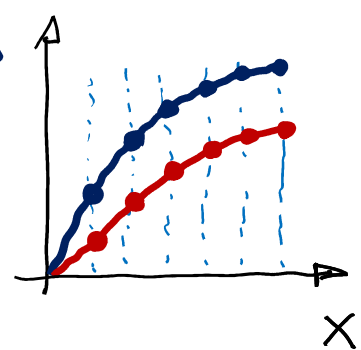


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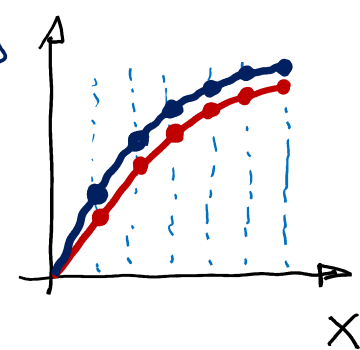
SIMILAR BACKGROUND

$f \sim f'$
increase c'



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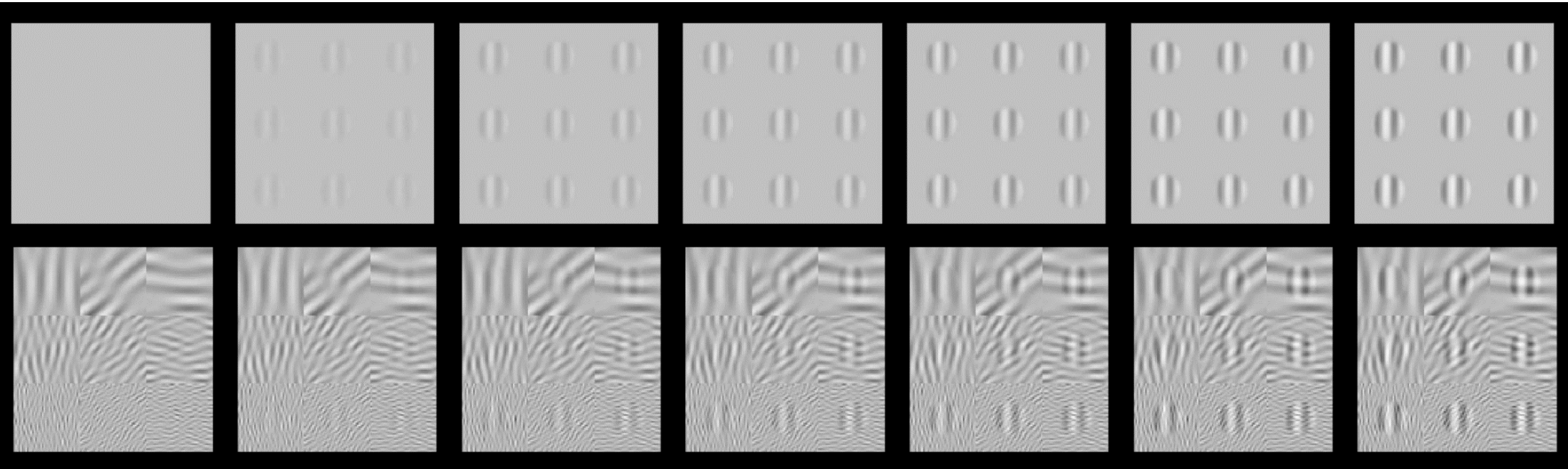


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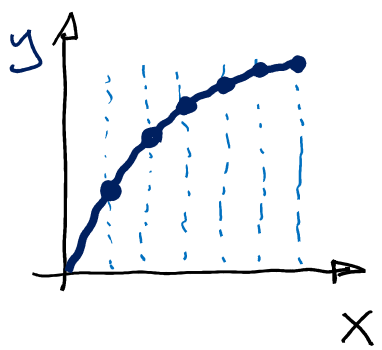
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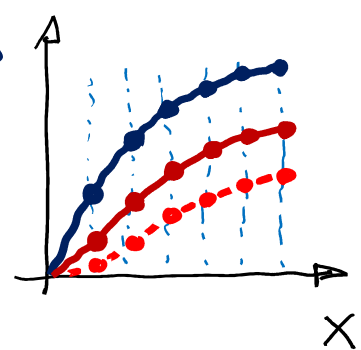


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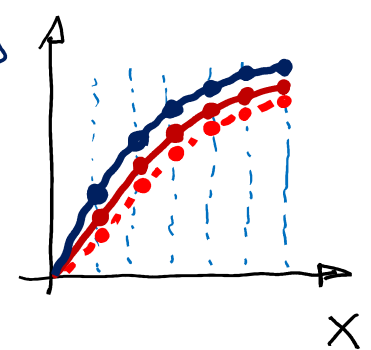
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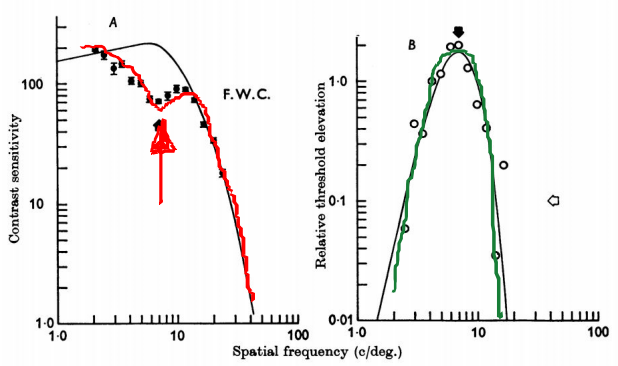
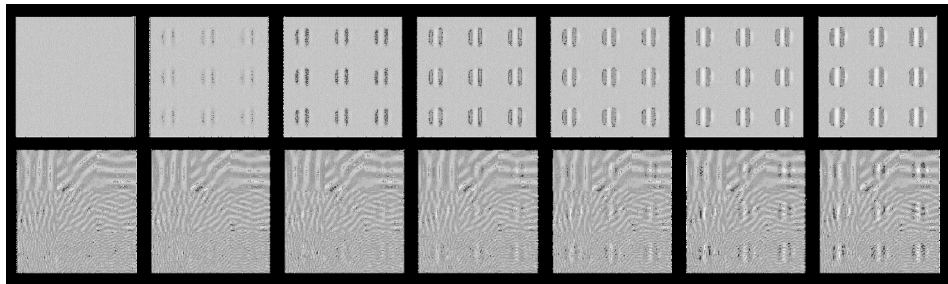


Martinez et al. Front. Neurosci 2019

Watson & Solomon JOSA 1997

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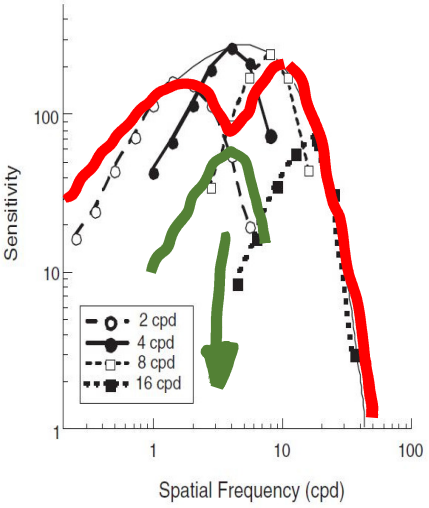
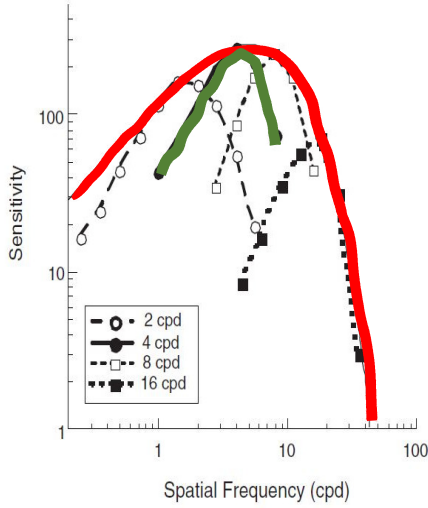
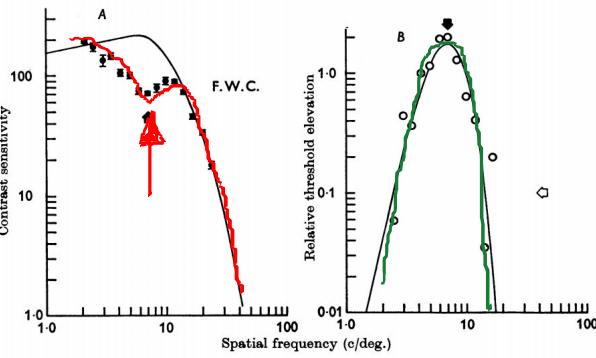
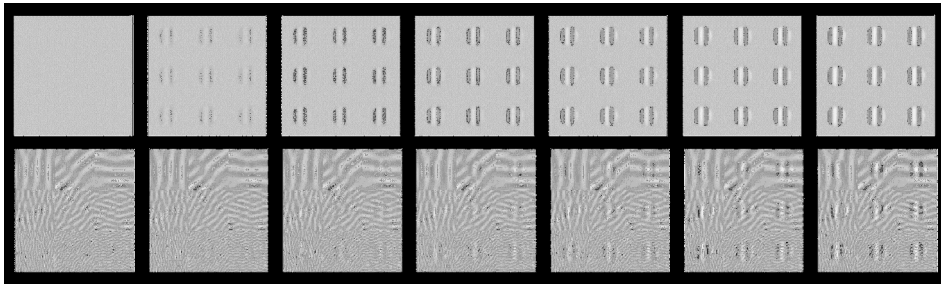
Text-fig. 6. The effect of adapting at 7.1 c/deg. A. The continuous curve from Text-fig. 5 is reproduced. The filled circles and vertical bars are the means and s.e. ($n = 6$) for re-determinations of contrast sensitivity at a number of spatial frequencies while F.W.C. was continuously adapting to a grating of 7.1 c/deg., 1.5 log. units above threshold. The exact procedure is described in the text.

B. The depression in sensitivity due to adaptation at 7.1 c/deg. is plotted, with open circles, as relative threshold elevation against spatial frequency. The vertical difference between each point and the smooth curve in Text-fig. 6A is the ratio of sensitivity before and after adaptation. The relative threshold elevation is the anti-logarithm of this difference minus 1, so that no change in threshold would give a value of zero on the ordinate. The continuous curve is the function $[e^{-f^2} - e^{-(2f)^2}]^2$, fitted by eye to the data points. The filled arrows show the adapting frequency of 7.1 c/deg. The open arrow marks the value on the ordinate for a threshold elevation equivalent to $2\sqrt{2}$ times an average s.e. for determining contrast sensitivity.

Blakemore & Campbell J. Physiol. 69

① ONE EXAMPLE:

Frequency sensors and non-linearities
Image-computable models



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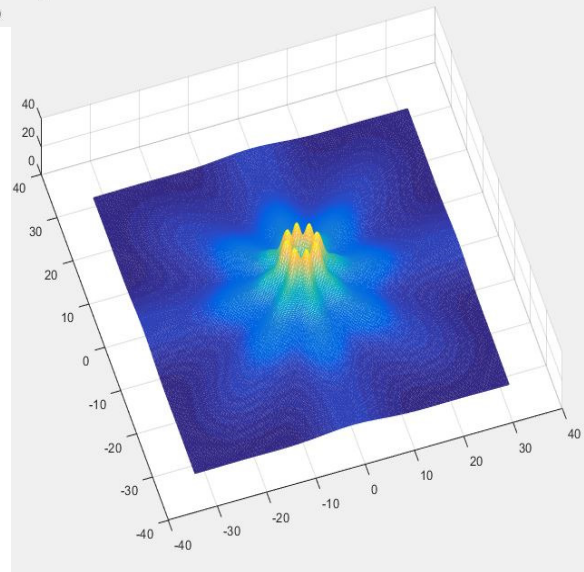
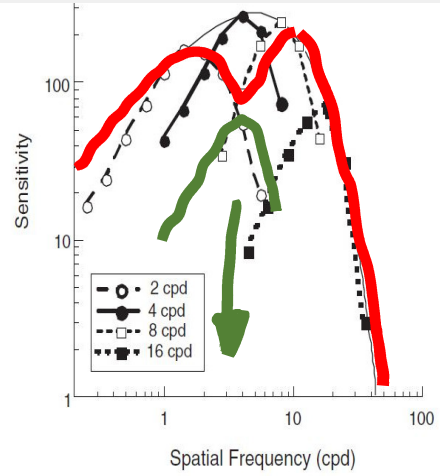
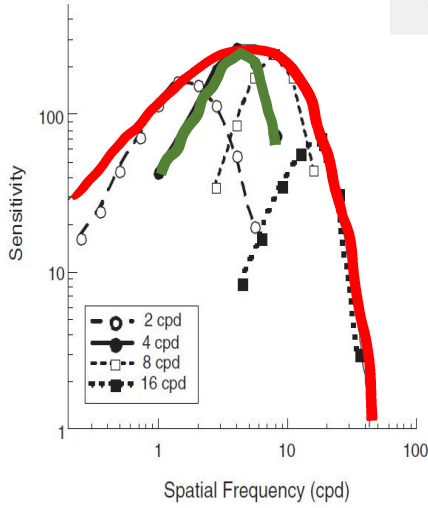
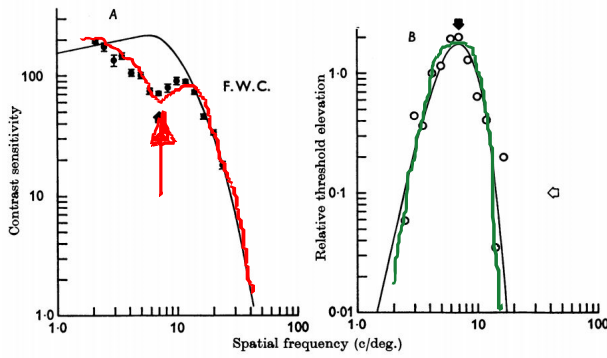
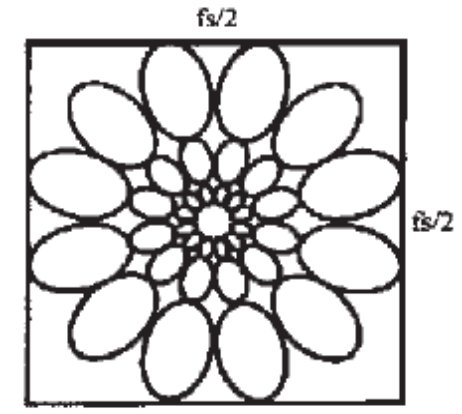
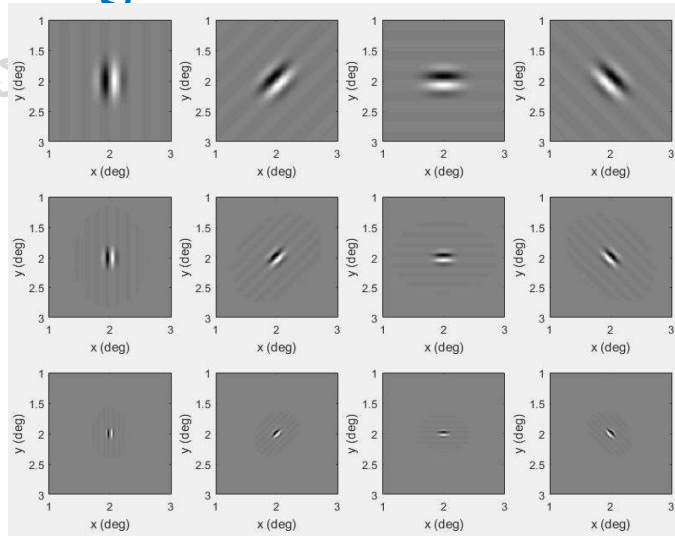
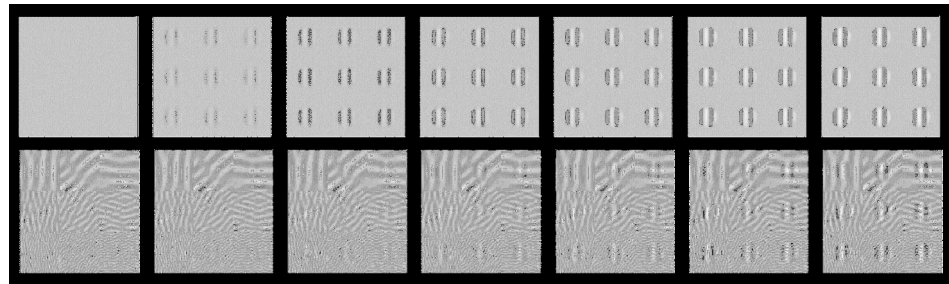
Sensitivity loss
in mechanism

Blakemore & Campbell J. Physiol. 69

① ONE EXAMPLE:

Frequency sensors and non-linearities

Image



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Sensitivity loss in mechanism

Blakemore & Campbell J. Physiol. 69

① ONE EXAMPLE:

Frequency sensors and non-linearities
Image-computable models DIVISIVE NORMALIZATION



LINEAR

$$C = L \cdot X$$

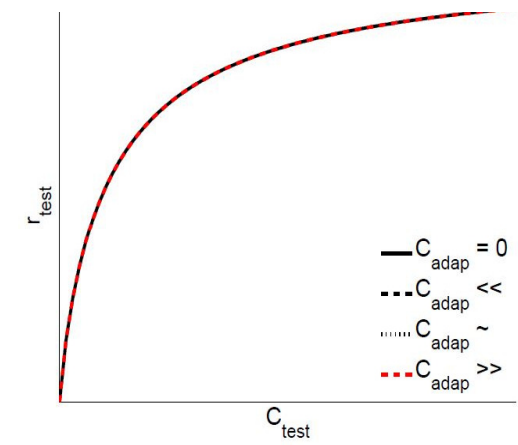
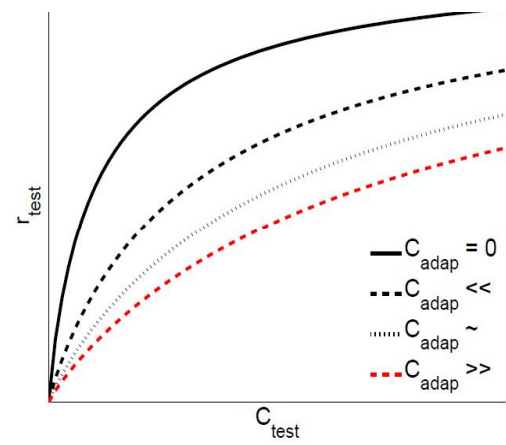
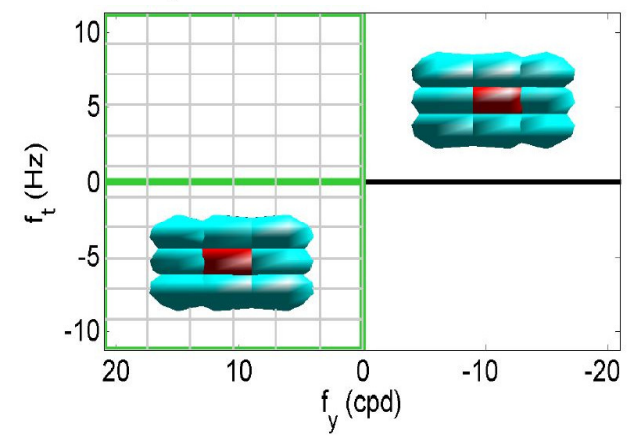
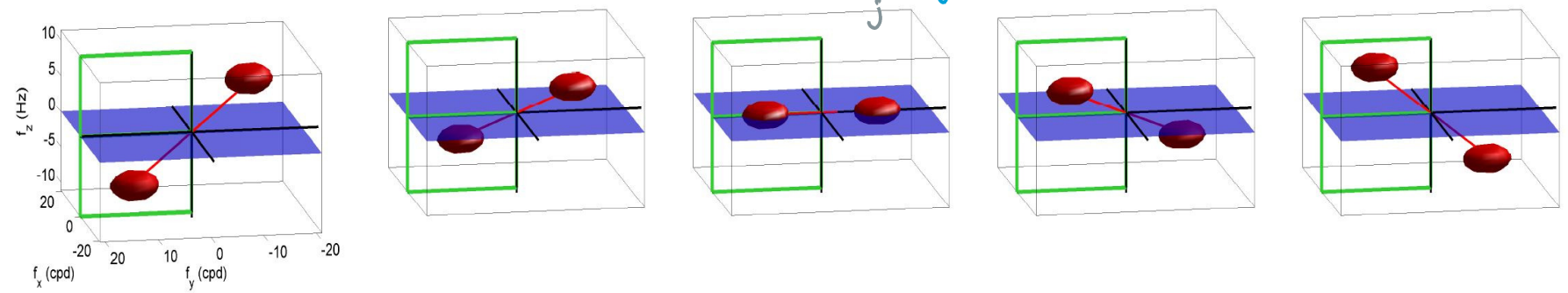
NON-LINEAR

$$y_i = \frac{c_i^r}{b_i + \sum_j H_{ij} c_j^r}$$

Heeger & Carandini 94

Carandini & Heeger 12

Simoncelli & Heeger 98

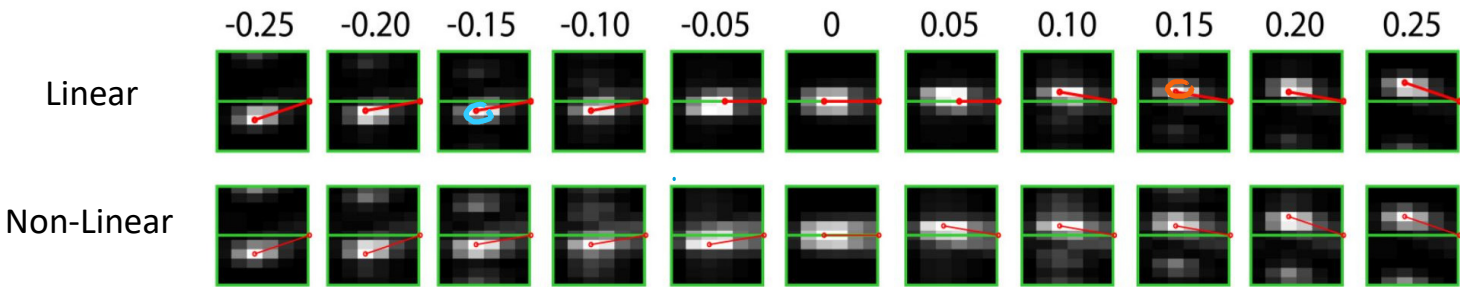
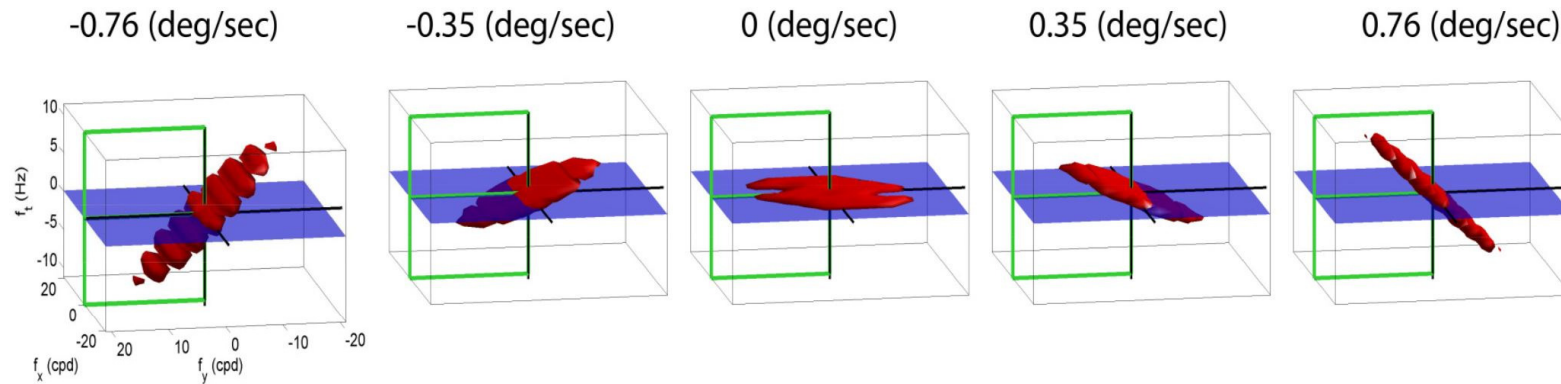


Laparra & Malo Front. Neurosci. 2015

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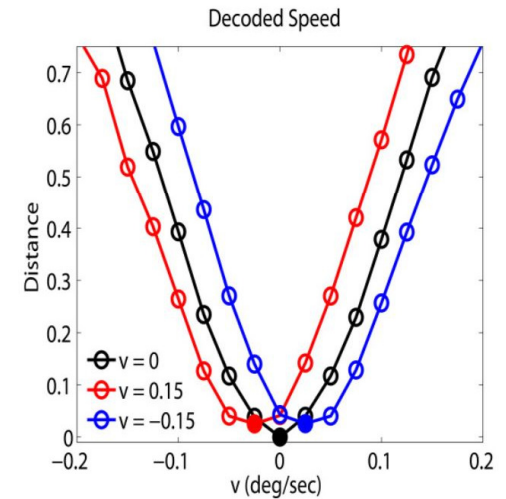
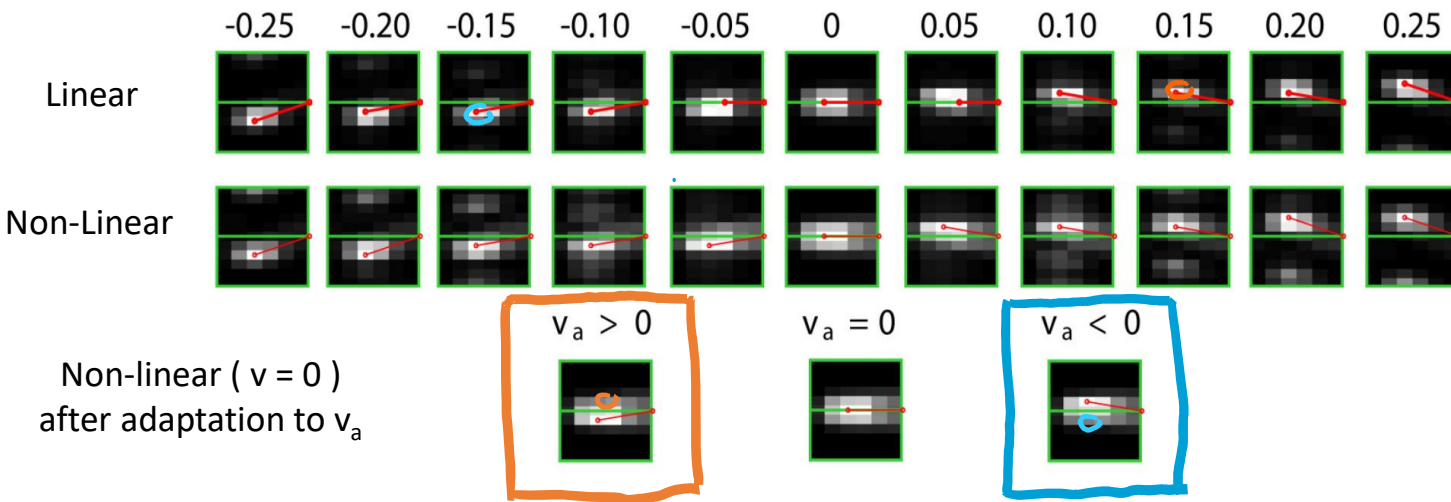
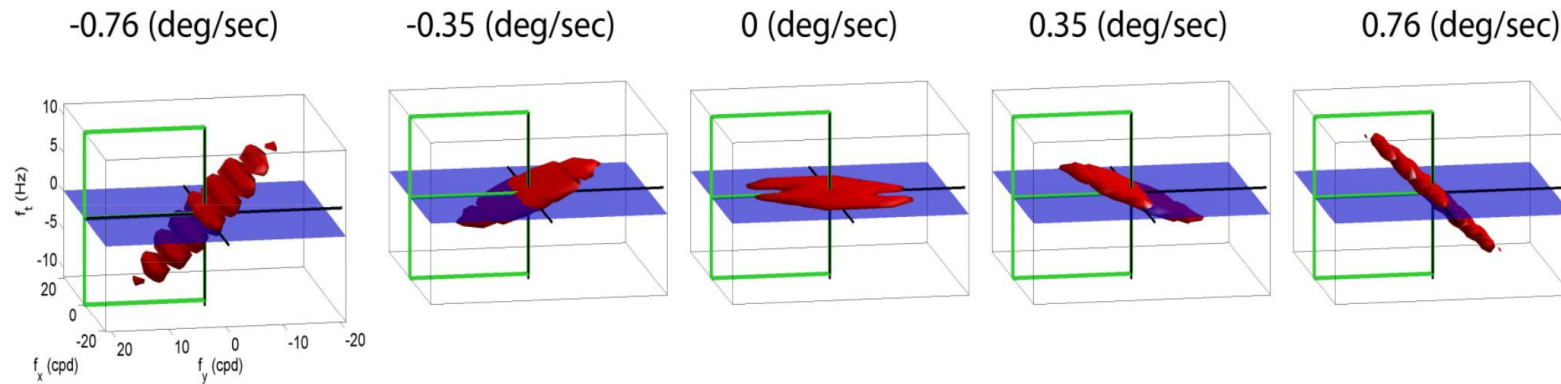
Frequency sensors and non-linearities
Image-computable models DIVISIVE NORMALIZATION



①

ONE EXAMPLE :

Frequency sensors and non-linearities
Image-computable models DIVISIVE NORMALIZATION

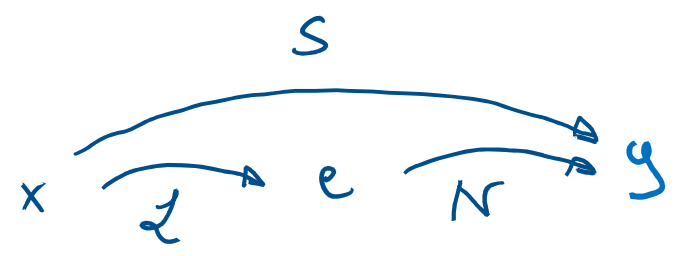


Laparra & Malo Front. Neurosci. 2015

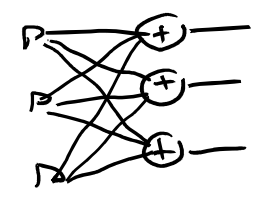
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Frequency sensors and non-linearities
 Image-computable models DIVISIVE NORMALIZATION

BIOL. Carandini & Heeger Nat. Rev. Neurosci 12
 Schütt & Wichmann J. Vision 17
 MATH. Martinez, Malo et al. PLOS ONE 18
<https://isp.uv.es/code/visioncolor/vistamodels.html>

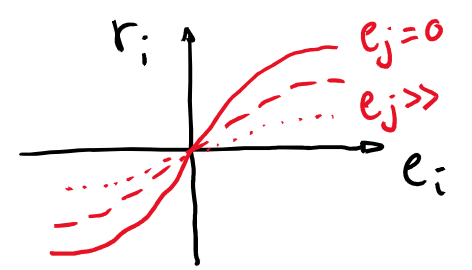


② $e = W \cdot x$



e = linear response
 b = semisaturation
 H = interaction kernel
 k = constant \rightarrow dyn. range

③ $y = k \cdot \frac{e}{b + H \cdot e}$



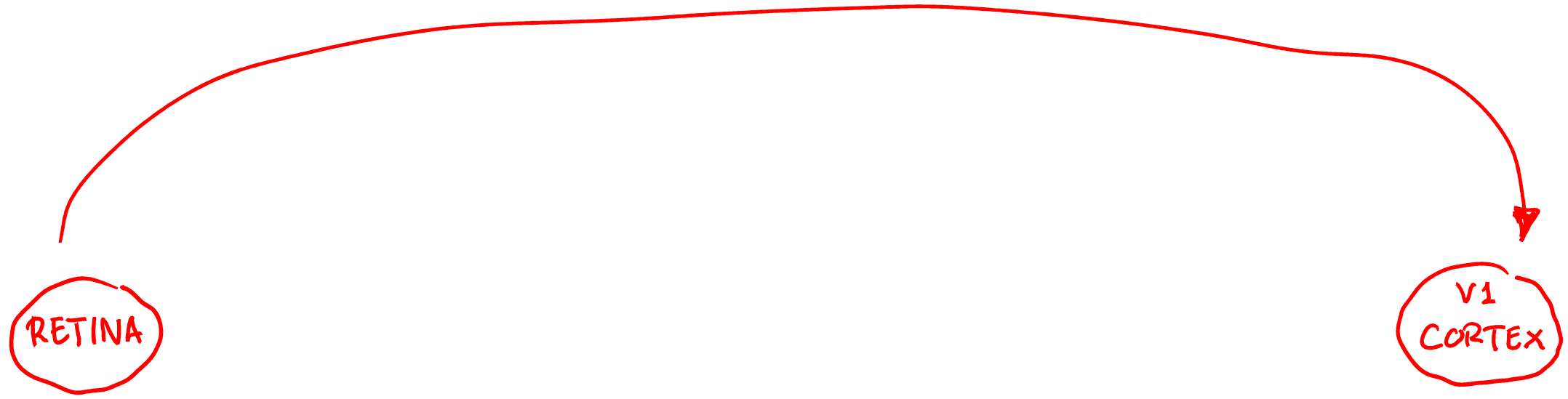
Masking and adaptation

$\nabla_x S \sim [I - D_{r(x)} H] \cdot D_e \cdot W \Rightarrow M = \nabla_x S^T \nabla_x S$ **NON DIAGONAL!**
INPUT DEPENDENT!

① ONE EXAMPLE:

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Image-computable models

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Schütt & Wichmann J. Vision 17
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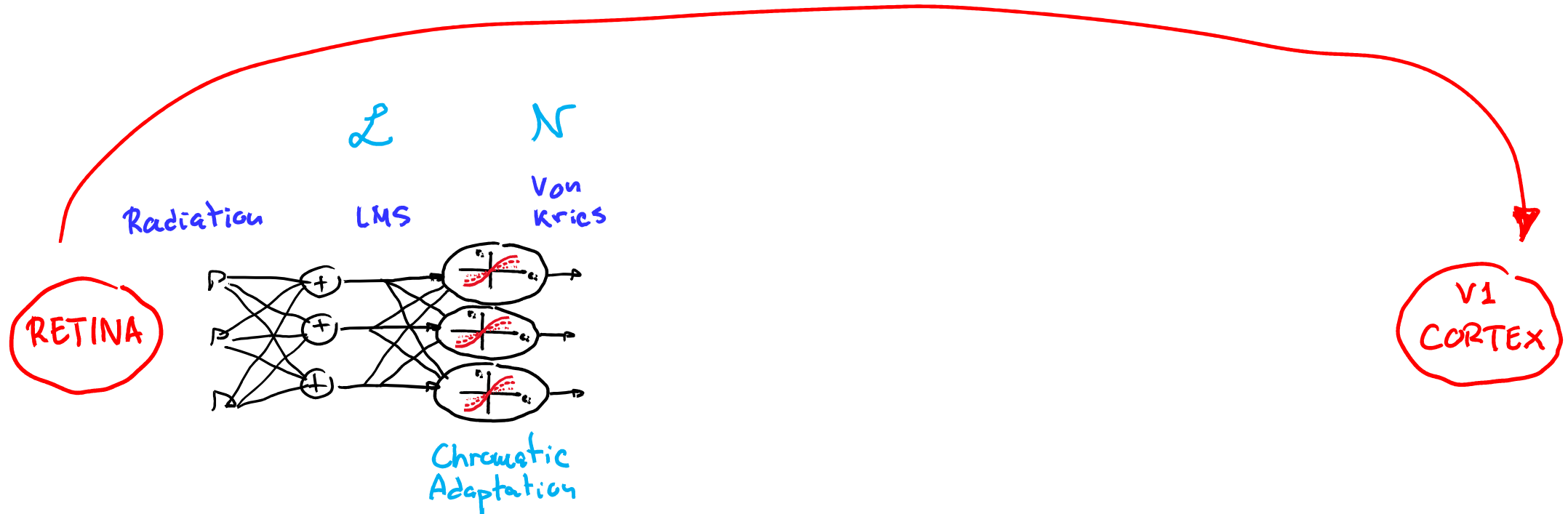
Gomez et al. J. Neurophysiol. 2020
Malo J. Math. Neurosci. 2020

(Wilson-Cowan)
(Divisive Normaliz.)

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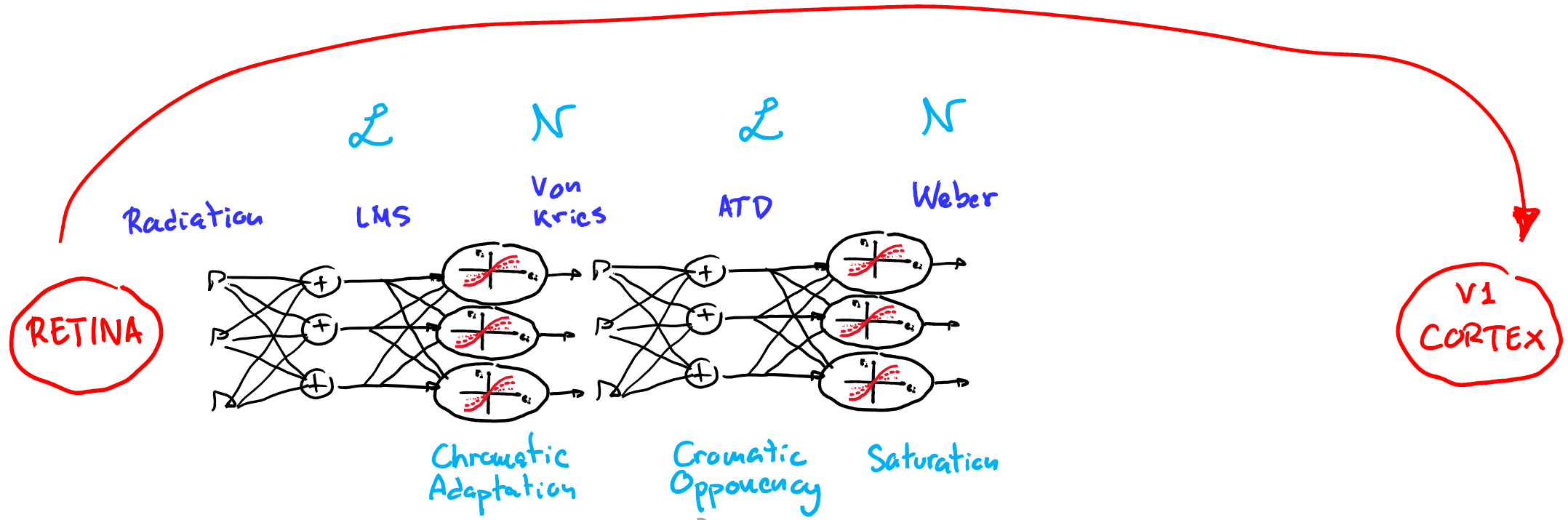


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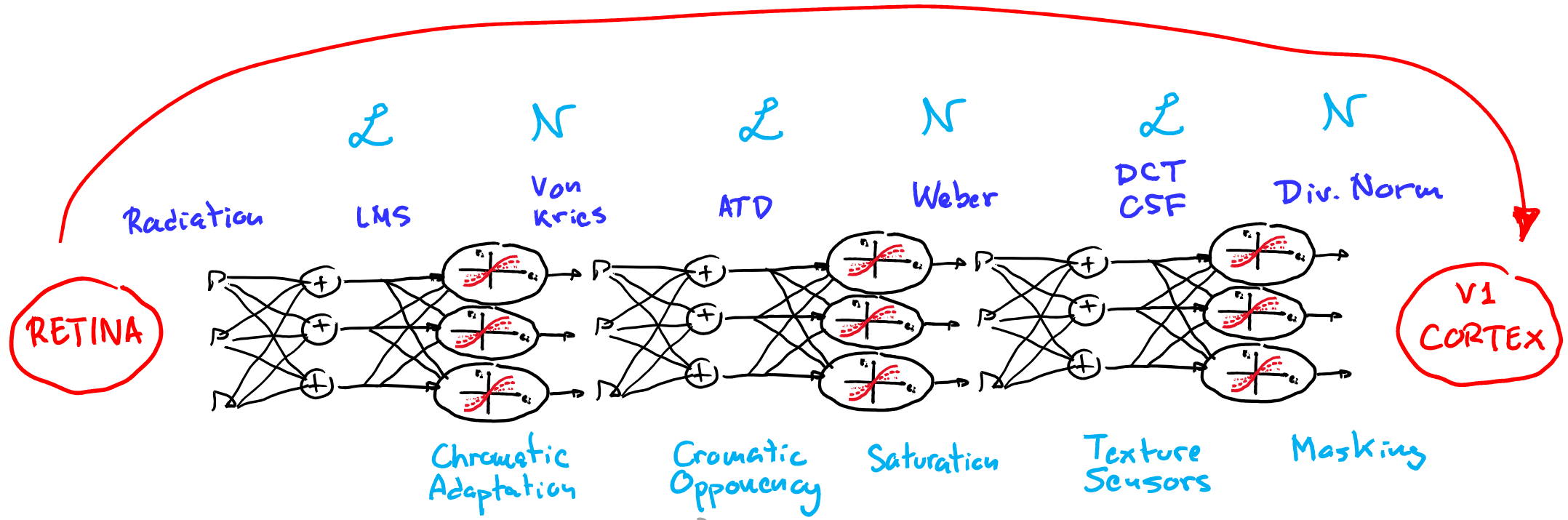


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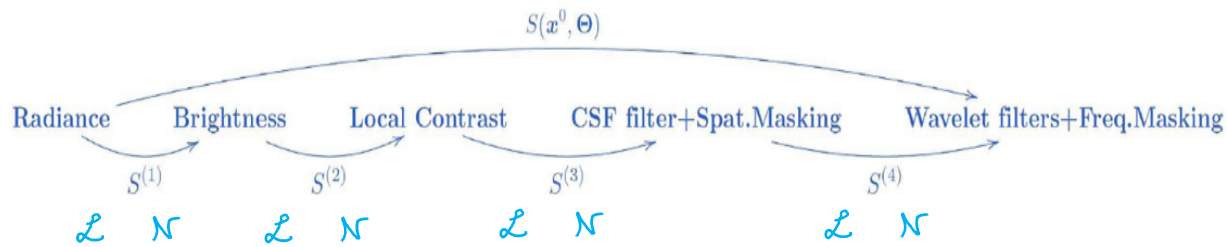
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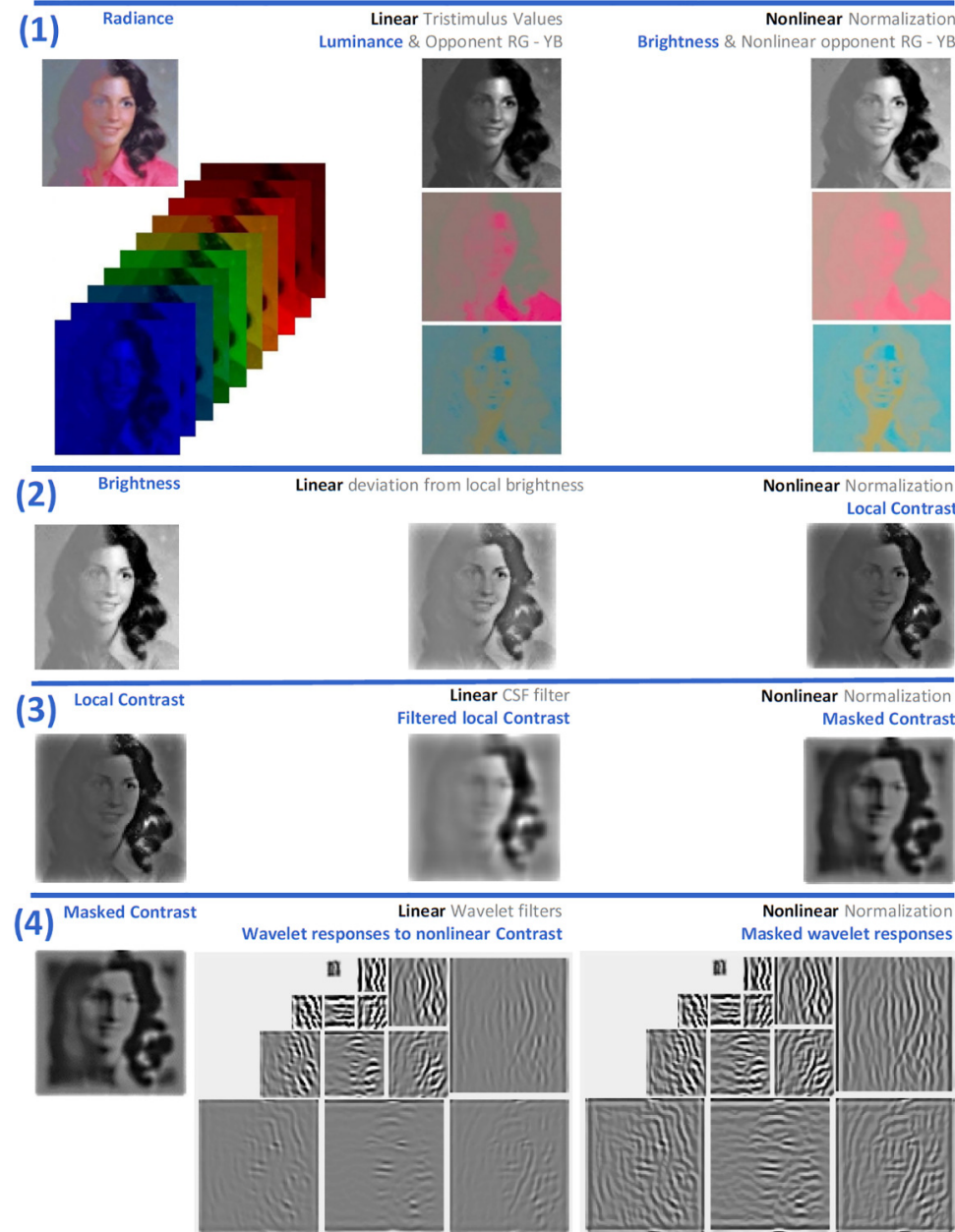
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① ONE EXAMPLE :



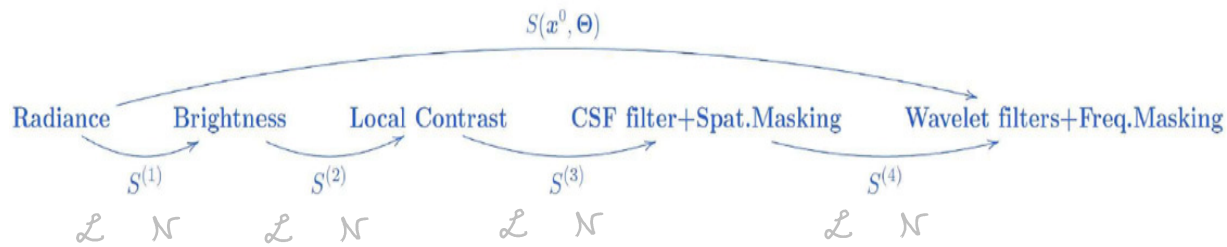
<https://isp.uv.es/code/visioncolor/vistamodels.html>
 Martinez, Malo et al. PLOS ONE 18

- Derivatives } Metrics
- New Psychophysics
- Inverse Decoding - Stimuli



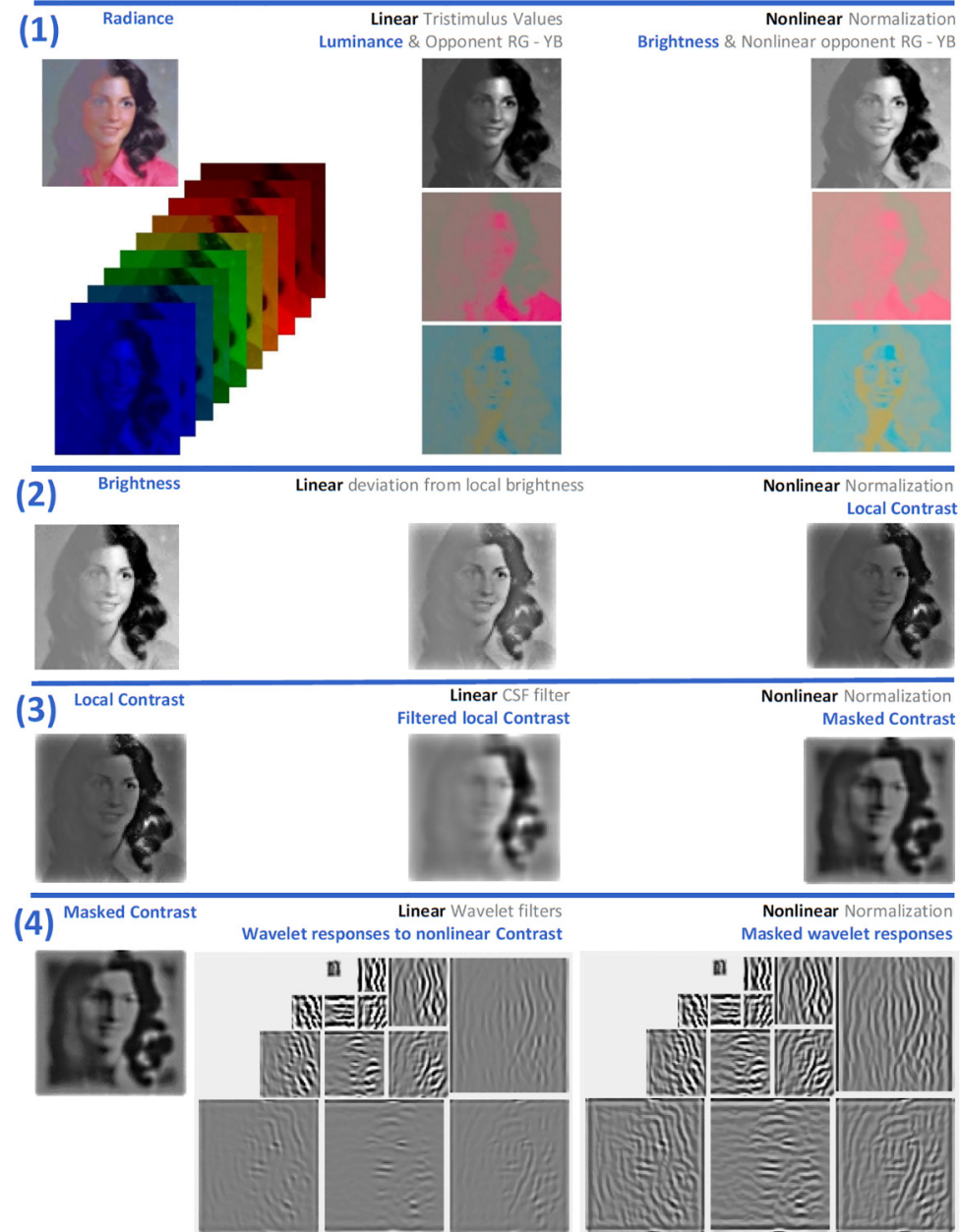
① ONE EXAMPLE :

WHY?

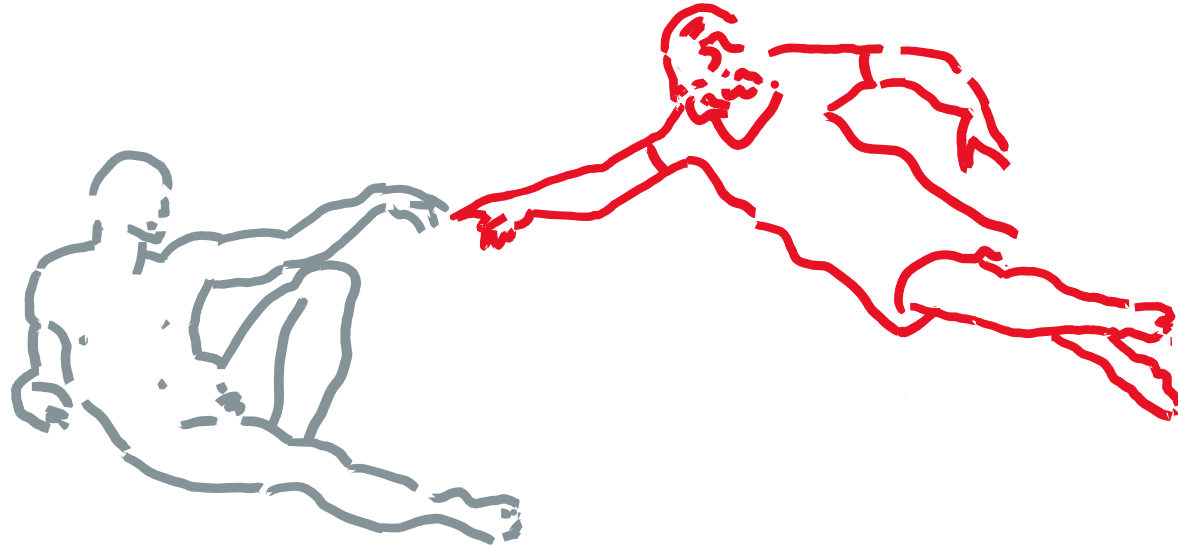


<https://isp.uv.es/code/visioncolor/vistamodels.html>
 Martinez, Malo et al. PLOS ONE 18

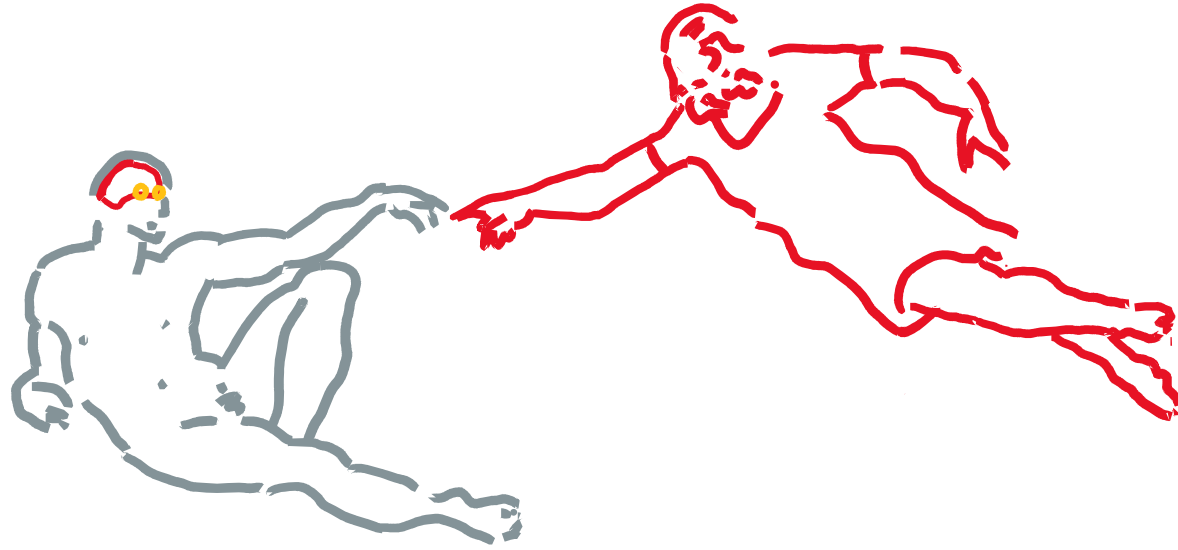
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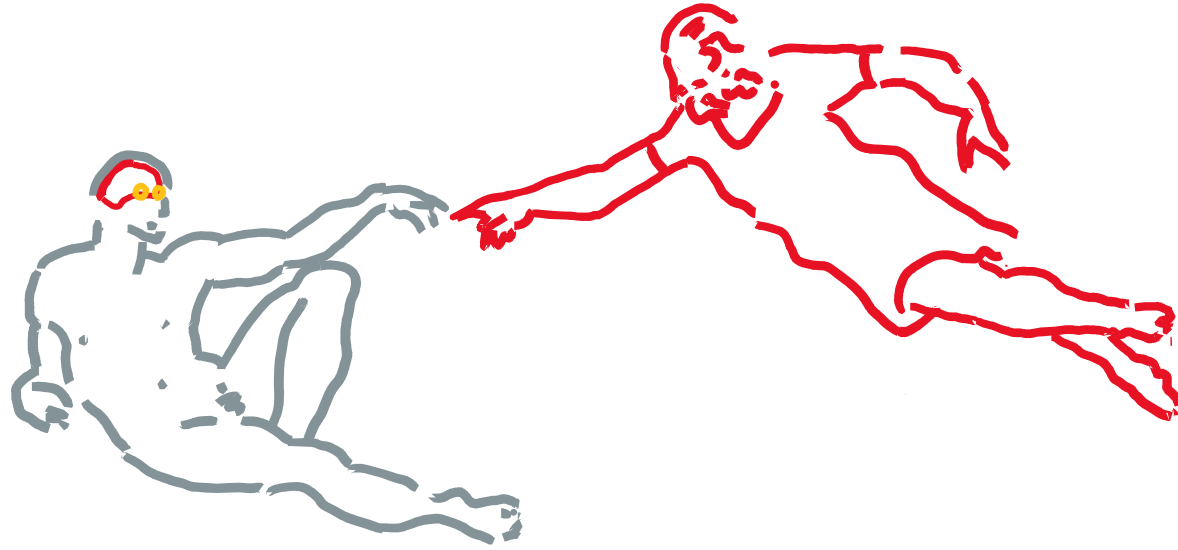
WHY?



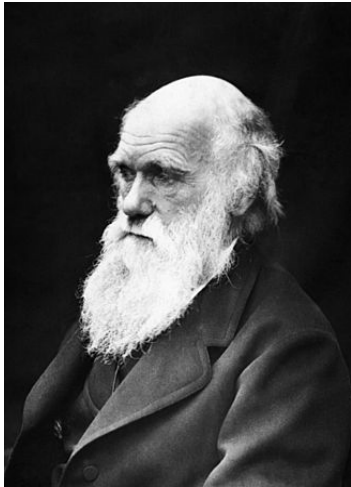
WHY?



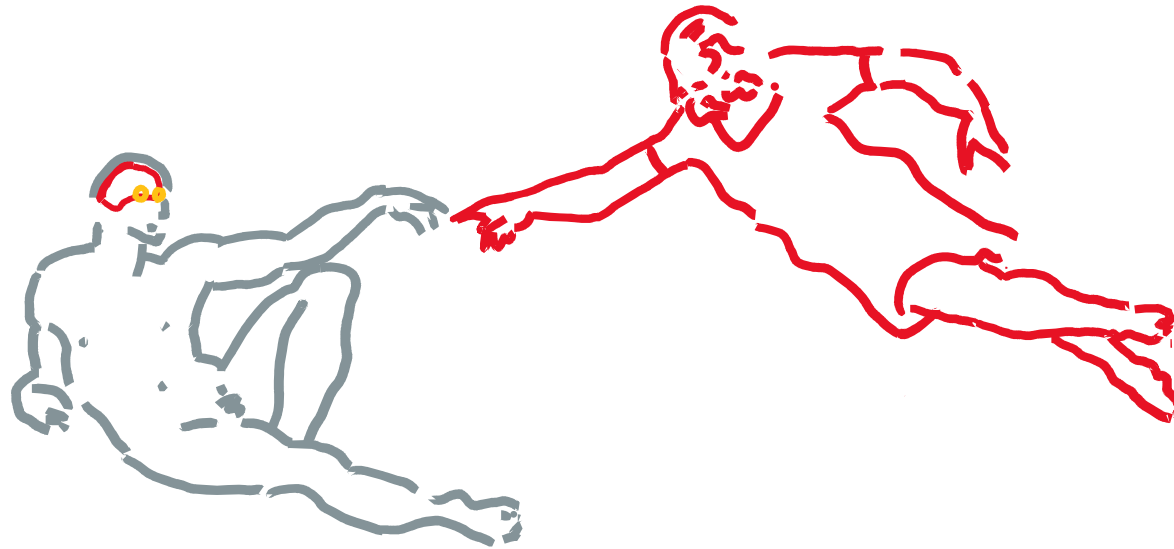
WHY?



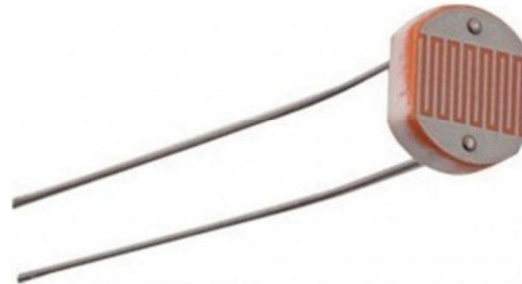
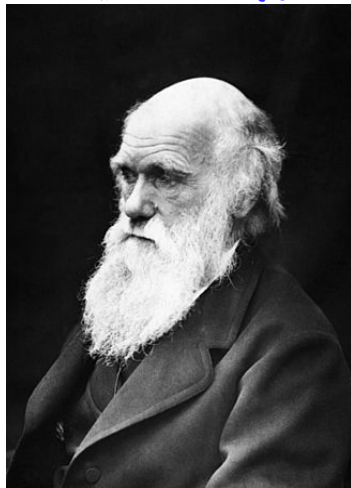
DARWIN



WHY?



DARWIN



SENSOR FOTORESISTENCIA LDR GL-5528

Fotoresistencia que permite medir niveles de luz.

0,25 €

0,21 € (IVA no incluido)

Fracciona tu pago desde 50,00 € 

— SEQUORA

Estado: Nuevo

Fabricante: tiendatec

Referencia: GL5528

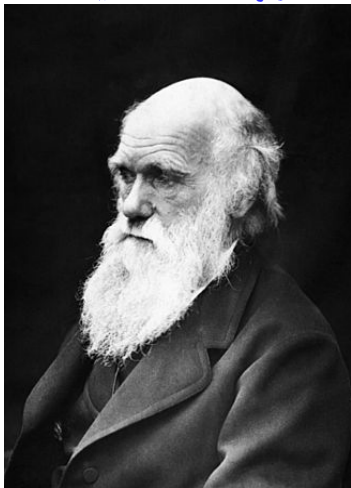
EAN: 8472496014380

 Disponible, recíbelo el lunes 4

12/4

!! WHAT WOULD YOU DO ?

DARWIN



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GL-5528

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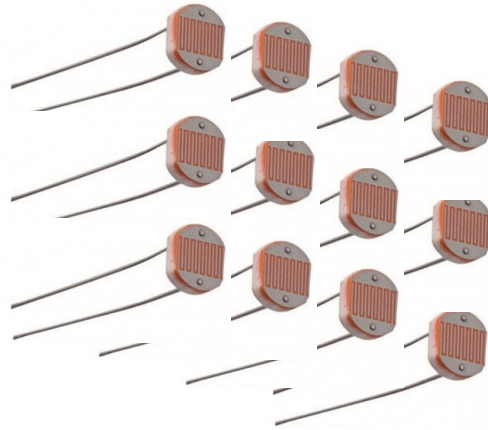
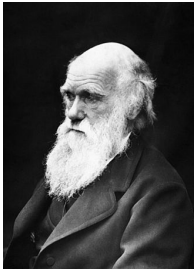
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 Disponible, recíbelo el lunes 4

12/4

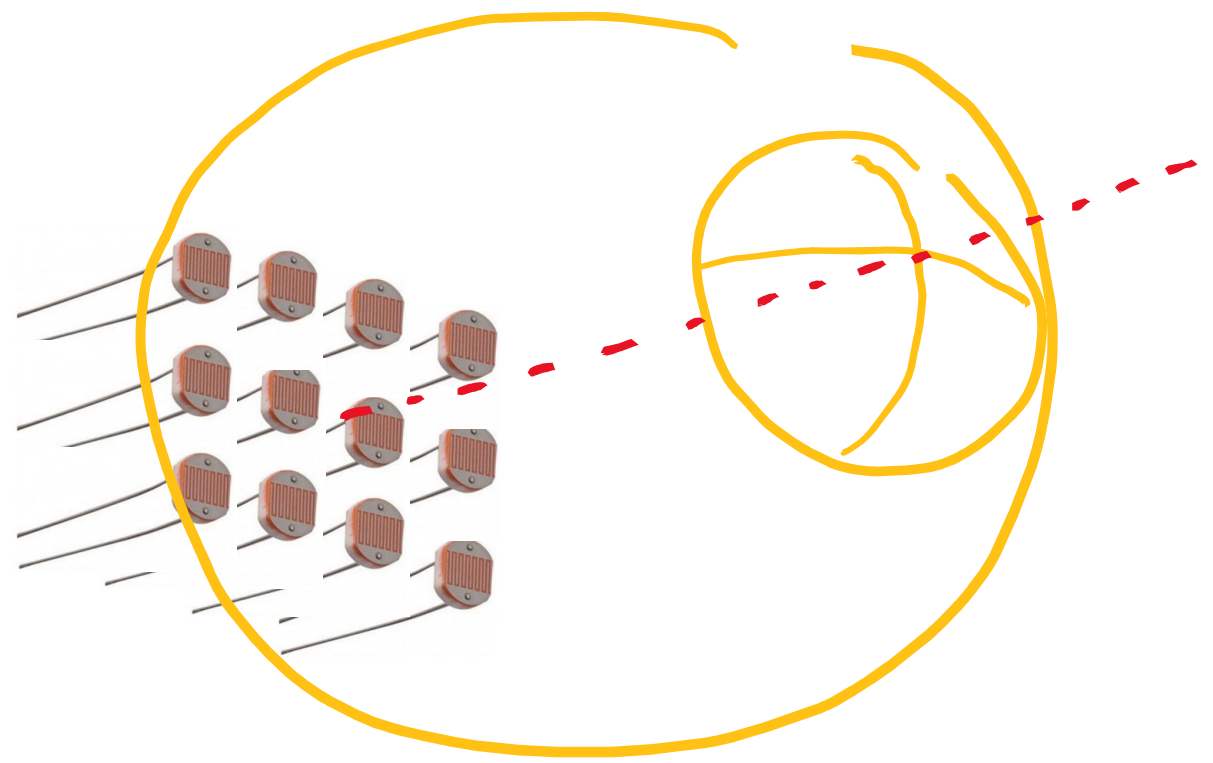
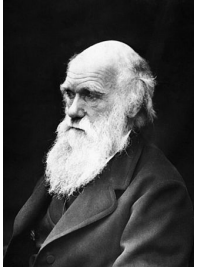
!! WHAT WOULD YOU DO?

DARWIN



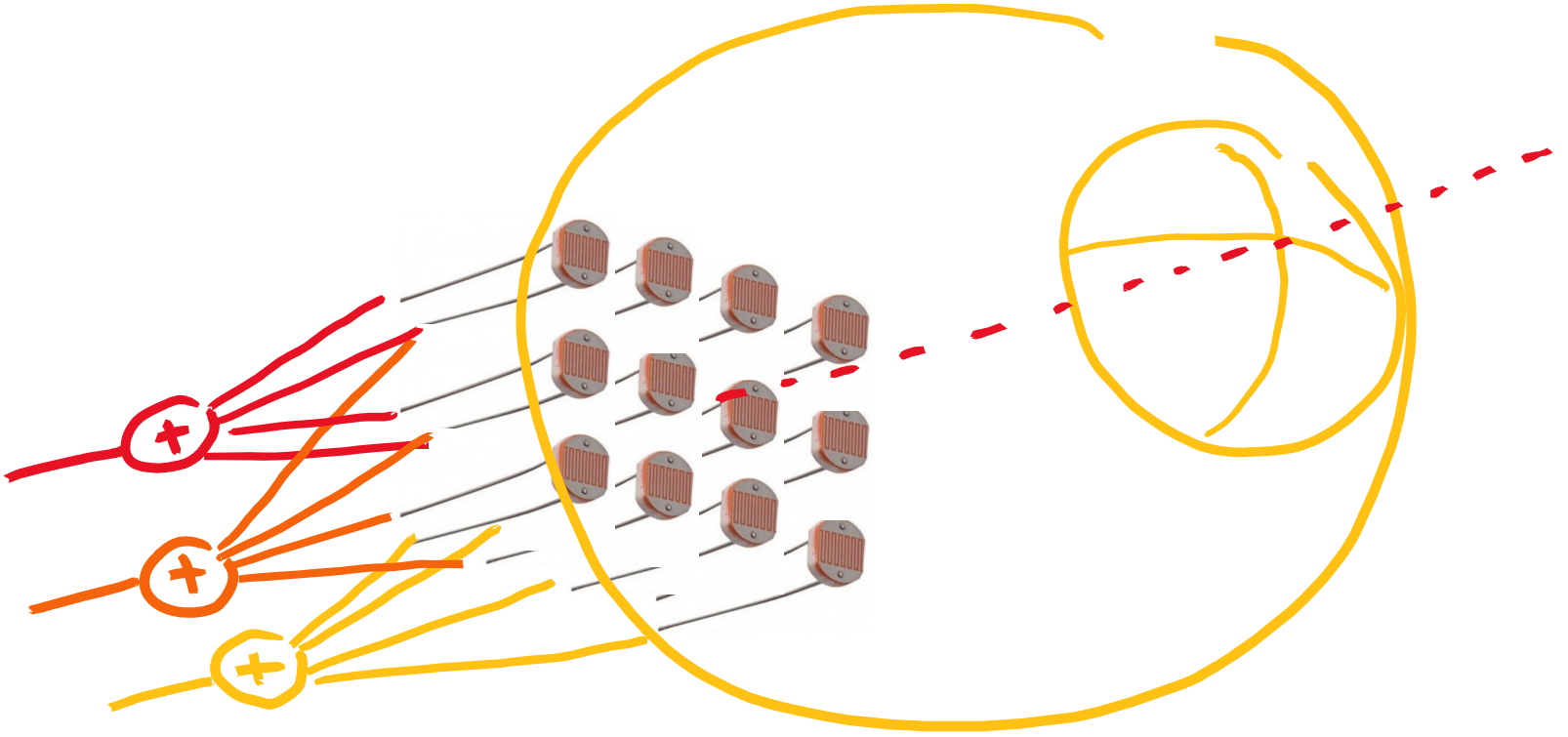
!! WHAT WOULD YOU DO?

DARWIN

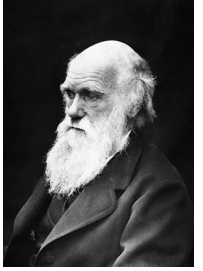


12/41

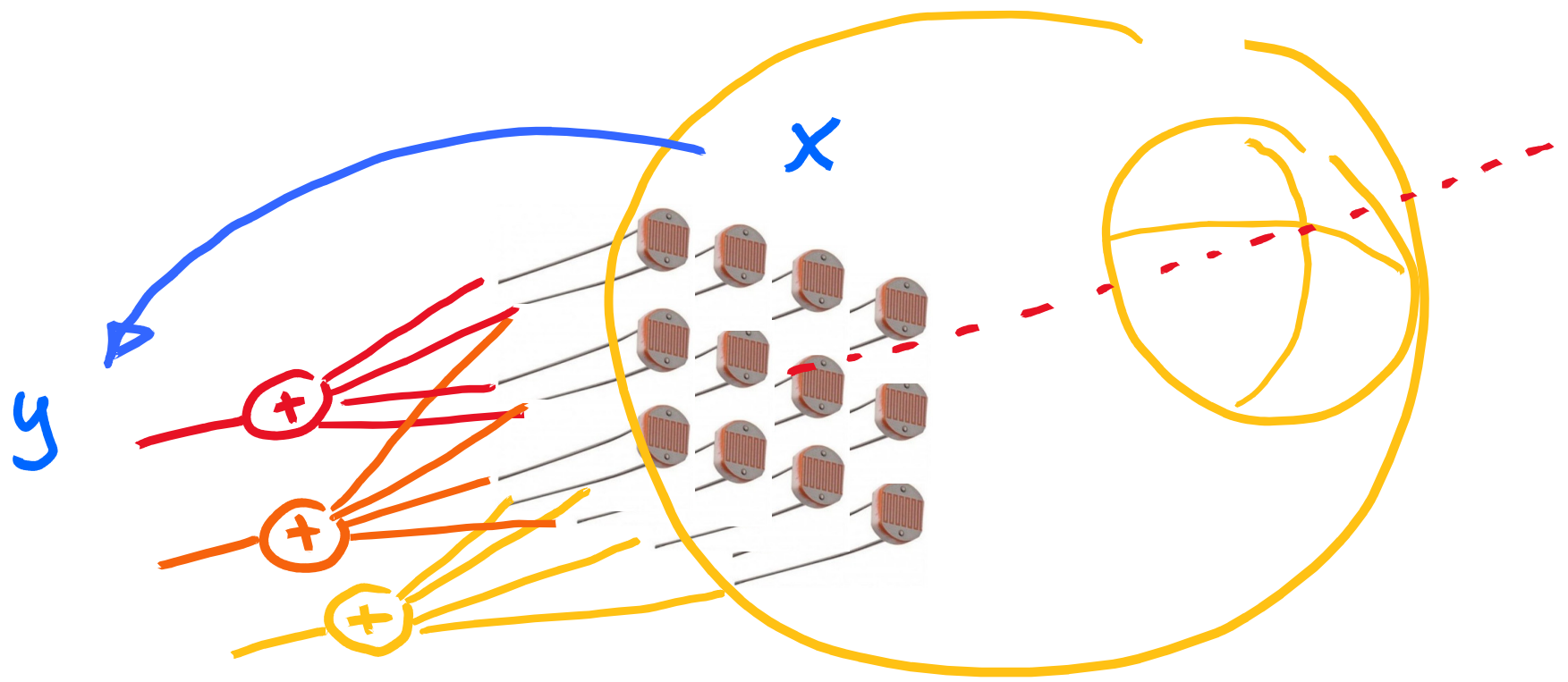
!! WHAT WOULD YOU DO?



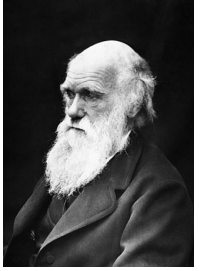
DARWIN



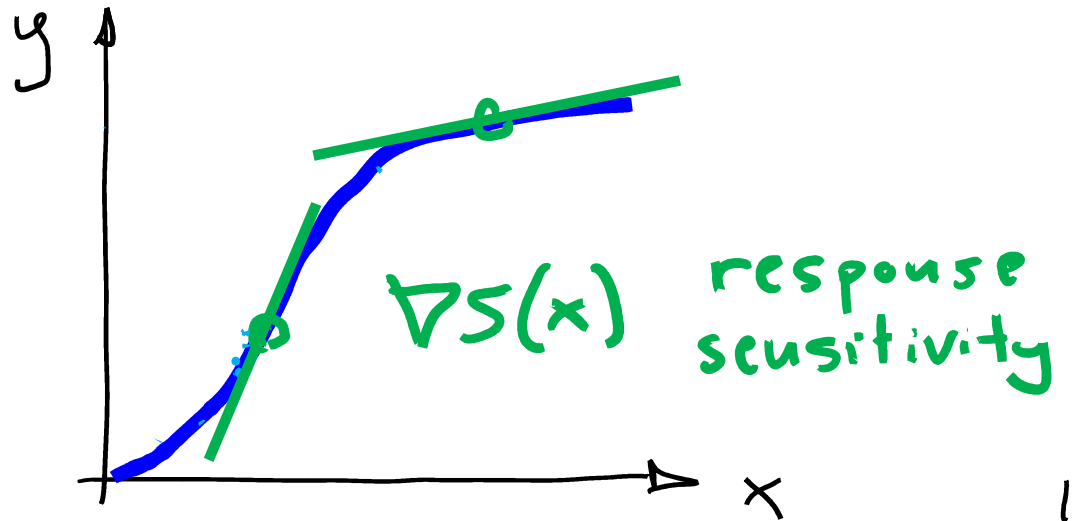
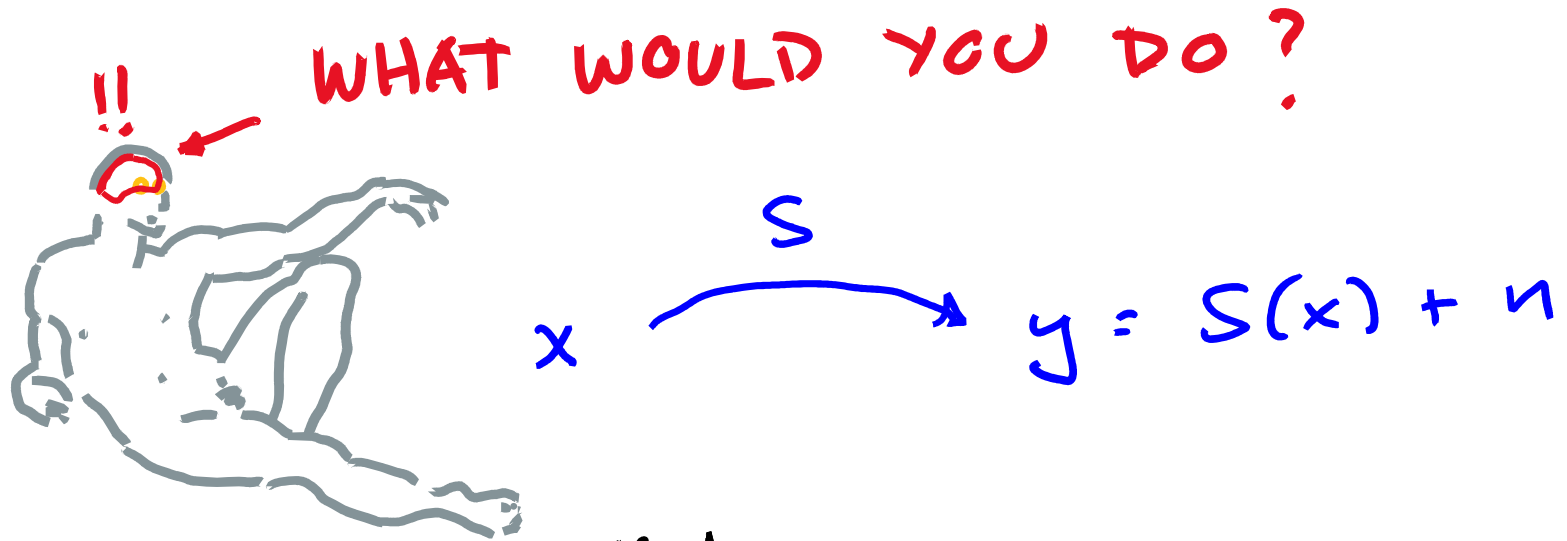
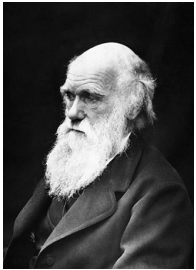
!! WHAT WOULD YOU DO?



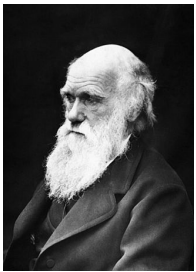
DARWIN



DARWIN



DARWIN



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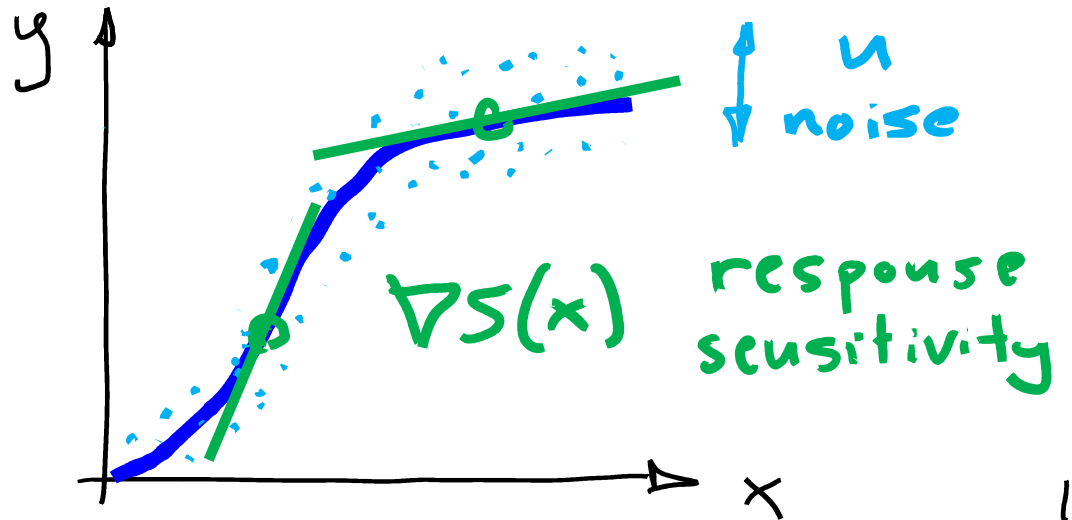
EAN: 8472496014380

Disponible, recíbelo el lunes 4

WHAT WOULD YOU DO?



$x \xrightarrow{S} y = S(x) + \eta$

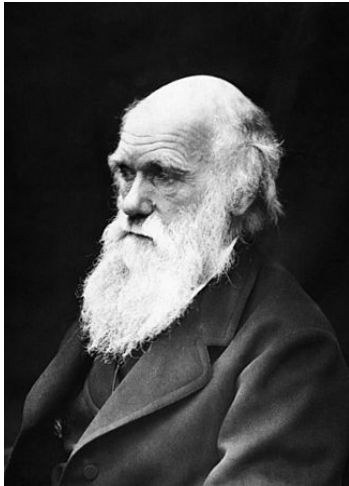


12/41

② COMPUTATIONAL TOOLS : Information theory
Uniformization & Gaussianization

- Function determines structure!!
- One example: Information transmission
 - Entropy maximization
 - Redundancy reduction
- Original tools :
 - UNIFORMIZATION
 - GAUSSIANIZATION

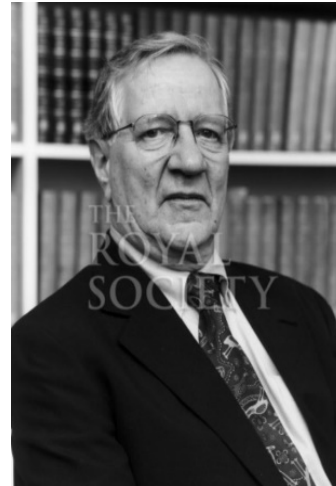
DARWIN



SHANNON



BARLOW



2

COMPUTATIONAL TOOLS : Information theory

$$x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

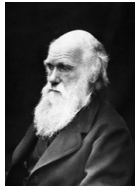
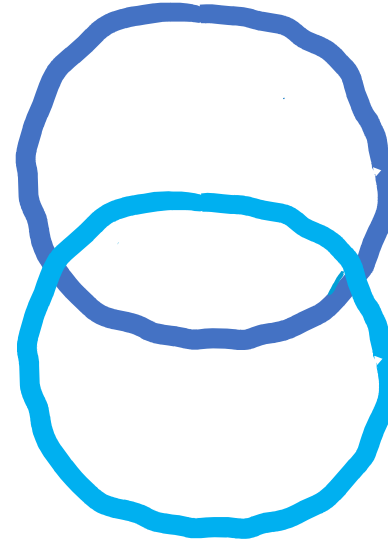
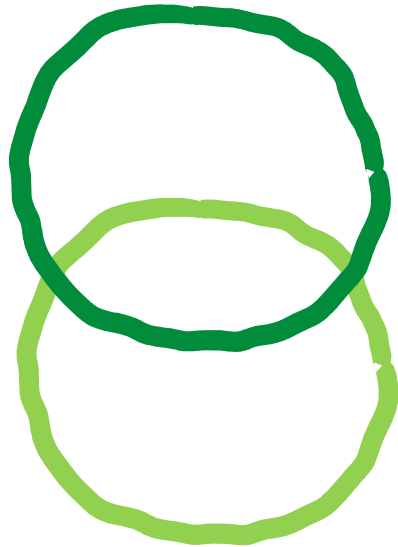
S_0



$$y = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$$

information $\propto \log\left(\frac{1}{P(x)}\right)$

Entropy = $\langle \text{inform} \rangle$



2

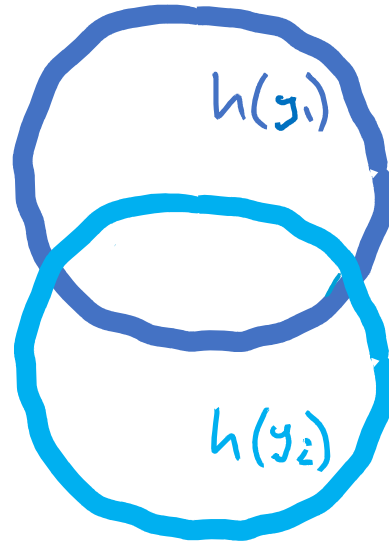
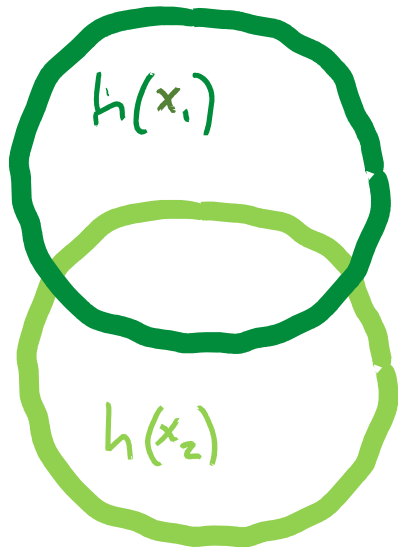
COMPUTATIONAL TOOLS : Information theory

$$x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

S_0



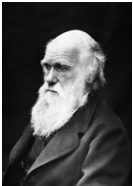
$$y = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$$



information $\propto \log\left(\frac{1}{p(x)}\right)$

Entropy = $\langle \text{inform} \rangle$

$$h(x) = - \int p(x) \log(p(x)) dx$$



2

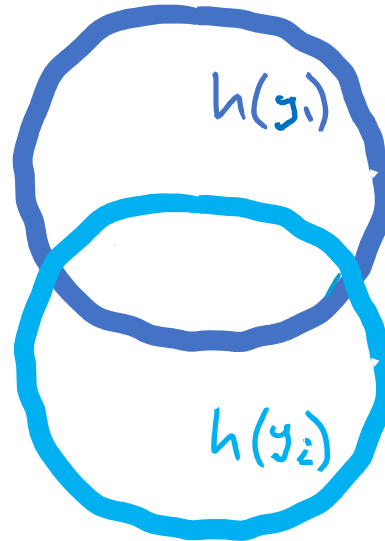
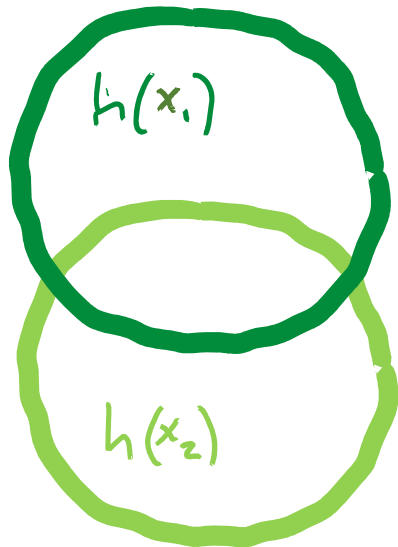
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S_0



$$y = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$$

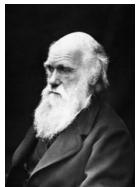


$$\text{information} \propto \log\left(\frac{1}{p(x)}\right)$$

$$\text{Entropy} = \langle \text{inform} \rangle$$

$$h(x) = - \int p(x) \log(p(x)) dx$$

$$h(y_1) + h(y_2) > h([y_1, y_2])$$



②

COMPUTATIONAL TOOLS : Information theory

$$x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

S_0



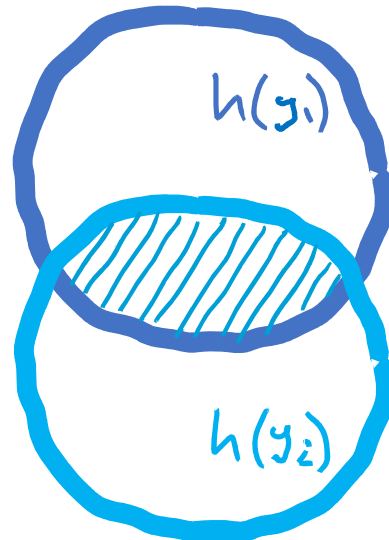
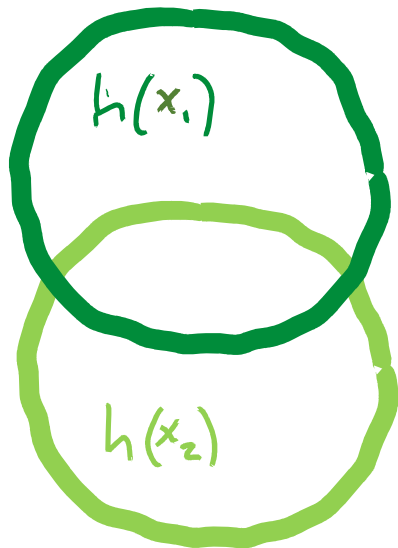
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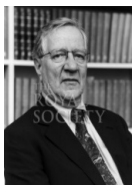
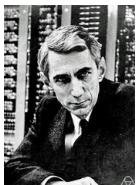
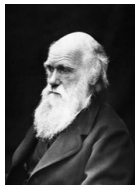
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//// TOTAL CORRELATION \equiv Redundancy within a vector $T(y) = \sum_i h(y_i) - h(y)$



②

COMPUTATIONAL TOOLS : Information theory

$$x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

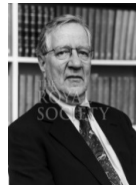
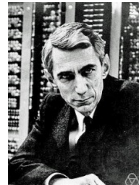
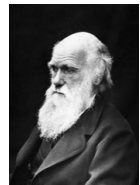
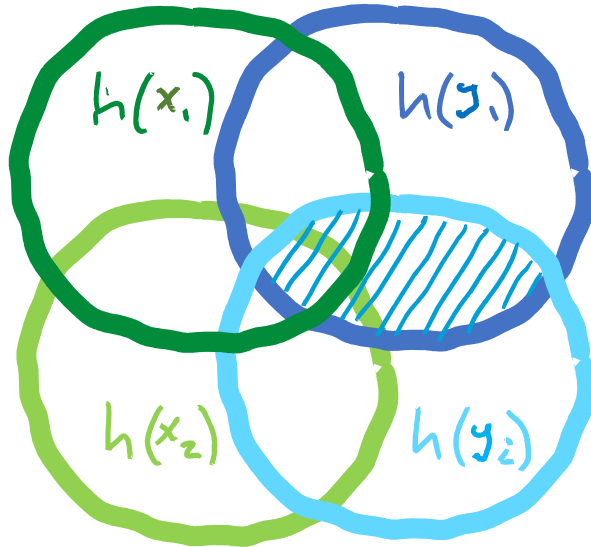


$$y = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$$

$$\text{information} \propto \log\left(\frac{1}{p(x)}\right)$$

$$\text{Entropy} = \langle \text{inform} \rangle$$

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②

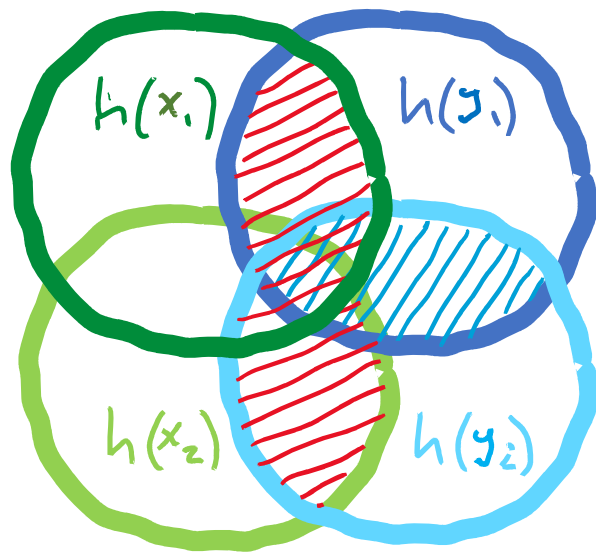
COMPUTATIONAL TOOLS : Information theory

$$x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \xrightarrow{S_0} y = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$$

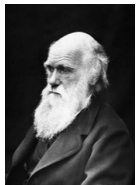
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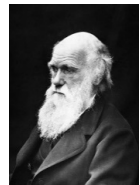
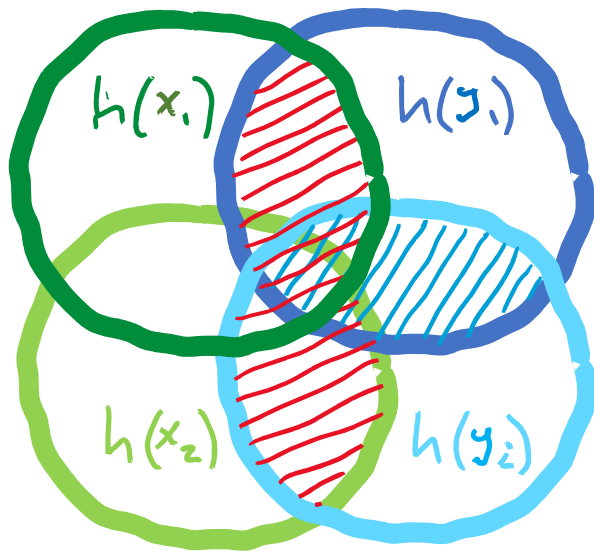


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Entropy = $\langle \text{inform} \rangle$

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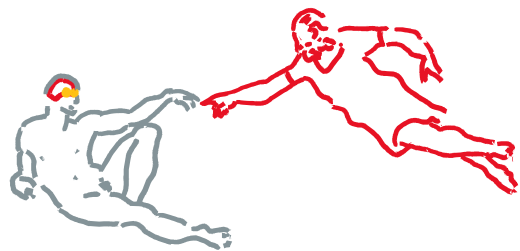
//// TOTAL CORRELATION \equiv Redundancy within a vector $T(y) = \sum_i h(y_i) - h(y)$

//// MUTUAL INFORMATION \equiv Info shared by two vectors $I(x,y) = h(x) + h(y) - h([x,y])$

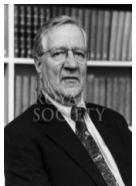
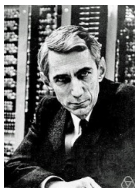
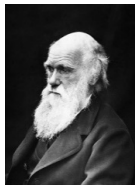
② COMPUTATIONAL TOOLS : Information theory

The "design" problem:

$$x \xrightarrow{S} y = S(x) + u$$



please maximize $I(x, y)$!

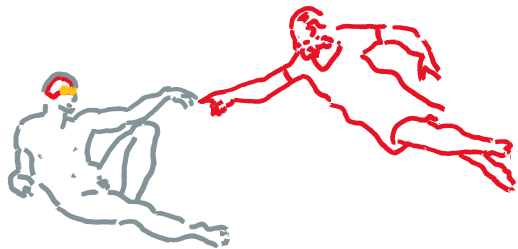


②

COMPUTATIONAL TOOLS : Information theory

The "design" problem:

$$x \xrightarrow{S} y = S(x) + n$$



please maximize $I(x, y)$!

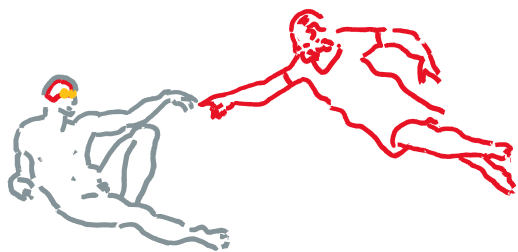
$$I(x, y) = h(x) + E_x[\log \|\nabla s\|] - \left(h(n) - E_n \left[D_{KL} \left(p(s(x)) \middle| p(s(x)+n) \right) \right] \right)$$

②

COMPUTATIONAL TOOLS : Information theory

The "design" problem:

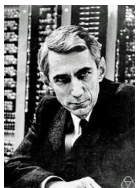
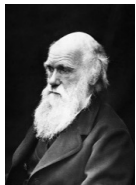
$$x \xrightarrow{S} y = S(x) + n$$



please maximize $I(x, y)$!

$$I(x, y) = h(x) + E_x[\log \|\nabla s\|] - \left(h(n) - E_n \left[D_{KL} \left(p(s(x)) \middle| p(s(x)+n) \right) \right] \right)$$

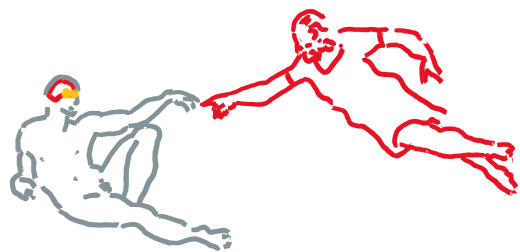
$$I(x, y) = \underbrace{\sum_i h(y_i)}_{(1)} - \underbrace{T(y)}_{(2)} - h(n) \Rightarrow \begin{cases} (1) \text{ MAXIMIZE ENTROPY} \\ (2) \text{ MINIMIZE REDUNDANCY} \end{cases}$$



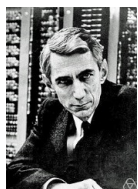
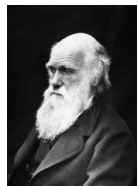
② COMPUTATIONAL TOOLS : Information theory

The "design" problem:

$$x \xrightarrow{S} y = S(x) + n$$



please maximize $I(x, y)$!



$$I(x, y) = h(x) + E_x[\log \|\mathcal{D}S\|] - \left(h(n) - E_n \left[D_{KL} \left(p(s(x)) \middle| p(s(x)+n) \right) \right] \right)$$

$$I(x, y) = \underbrace{\sum_i h(y_i)}_{(1)} - \underbrace{T(y)}_{(2)} - h(n) \Rightarrow \left. \begin{array}{l} (1) \text{ MAXIMIZE ENTROPY} \\ (2) \text{ MINIMIZE REDUNDANCY} \end{array} \right\} \Rightarrow \begin{array}{l} \text{UNIFORMIZATION} \\ \text{GAUSSIANIZATION} \end{array}$$

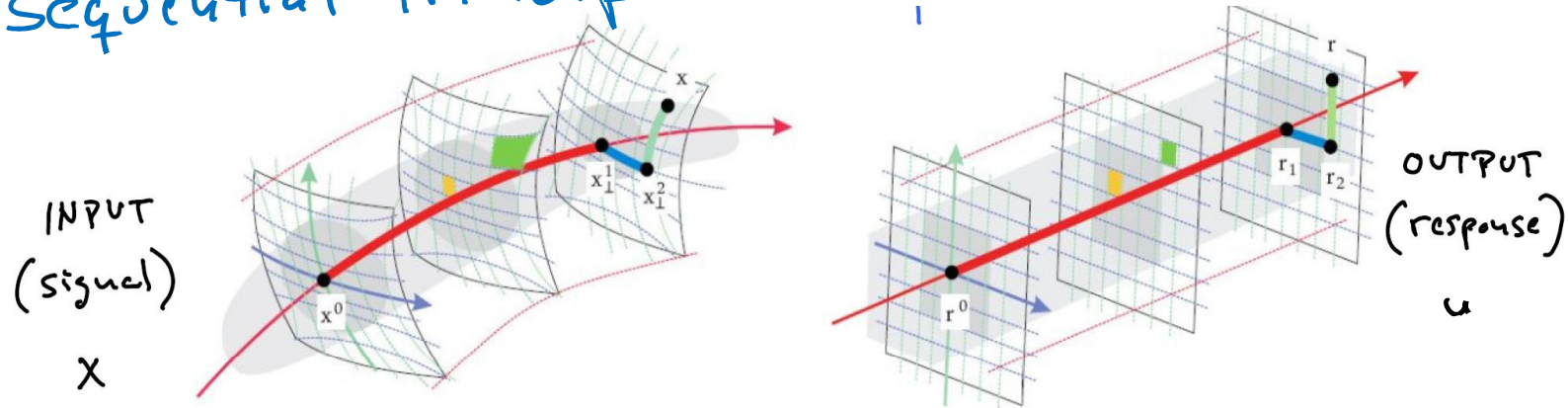
②

COMPUTATIONAL TOOLS

Information theory

UNIFORMIZATION : GAUSSIANIZATION

Sequential Principal Curves Analysis (SPCA)



$$y = S(x) = C \cdot \int_{x^0}^x \nabla U(x') \cdot dx' = C \cdot \int_{x^0}^x D(x') \cdot \nabla U(x') \cdot dx'$$

* INFOMAX
* ERROR MINIMIZATION γ

$$i = C_{ii} \cdot \int_{x_{\perp}^{i-1}}^{x_{\perp}^i} D(x') \cdot \nabla U(x') \cdot dx' = C_{ii} \int_0^{u_{\perp}^i} p_{u_i}(u'_i) \gamma du'_i$$

J. Malo & J. Gutiérrez (2006) V1-nonlinearities emerge from Local-to-Global ICA

Network: **Comp. Neur. Syst.** Vol. 17, 85–102

V. Laparra, J. Malo et al. (2012) Nonlinearities and adaptation in color vision from Sequential Principal Curves Analysis

Neural Comput. Vol. 24, 2751–2788. doi: 10.1162/NECO_a_00342

V. Laparra & J. Malo (2015) Visual aftereffects and sensory nonlinearities from a single statistical framework

Front. Hum. Neurosci., <https://doi.org/10.3389/fnhum.2015.00557>

② COMPUTATIONAL TOOLS :

Information theory

UNIFORMIZATION : GAUSSIANIZATION

$x^{(0)}$

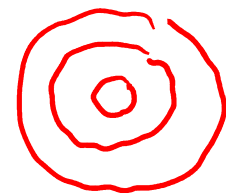


ANY PDF

$P(x^{(0)})$

$$x^{(u+1)} = \underbrace{R^{(u)}}_{\text{Rotation}} \cdot \underbrace{\psi^{(u)}(x^{(u)})}_{\text{Marginal Gaussianization}}$$

$x^{(N)}$

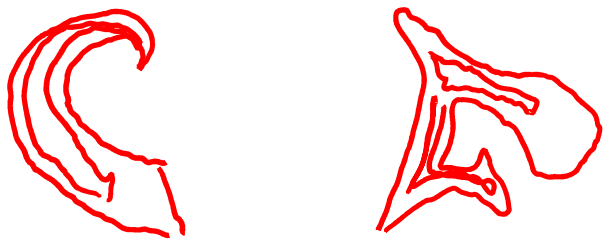


GAUSSIAN PDF

$$P(x^{(N)}) = \mathcal{N}(x^{(N)}, 0, I)$$

② COMPUTATIONAL TOOLS : Information theory : GAUSSIANIZATION

$x^{(0)} \rightarrow x^{(1)}$



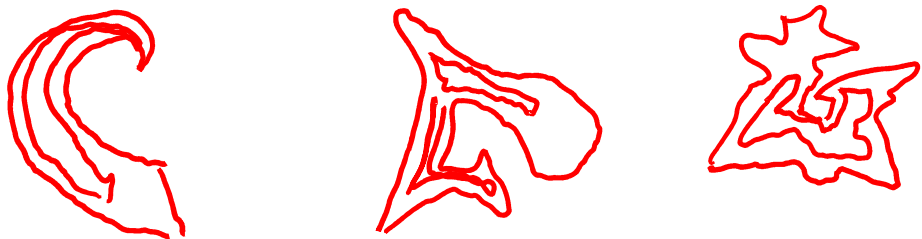
ANY PDF

$P(x^{(0)})$

$$x^{(u+1)} = \underbrace{R^{(u)}}_{\text{Rotation}} \cdot \underbrace{\psi^{(u)}(x^{(u)})}_{\text{Marginal Gaussianization}}$$

② COMPUTATIONAL TOOLS : Information theory : GAUSSIANIZATION

$x^{(0)} \rightarrow x^{(1)} \rightarrow x^{(2)}$

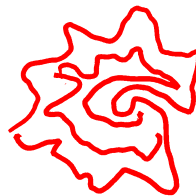
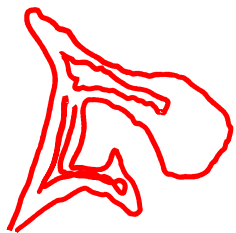


ANY PDF

$P(x^{(0)})$

$$x^{(u+1)} = \underbrace{R^{(u)}}_{\text{Rotation}} \cdot \underbrace{\psi^{(u)}(x^{(u)})}_{\text{Marginal Gaussianization}}$$

② COMPUTATIONAL TOOLS : Information theory : GAUSSIANIZATION

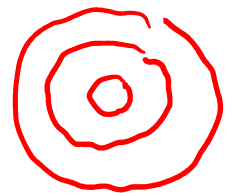
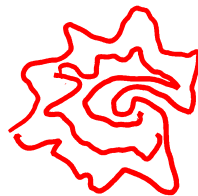
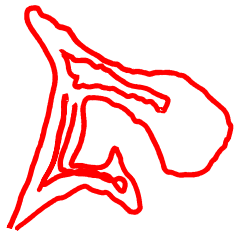


ANY PDF

$P(x^{(0)})$

$$x^{(u+1)} = \underbrace{R^{(u)}}_{\text{Rotation}} \cdot \underbrace{\psi^{(u)}(x^{(u)})}_{\text{Marginal Gaussianization}}$$

② COMPUTATIONAL TOOLS : Information theory : GAUSSIANIZATION



ANY PDF

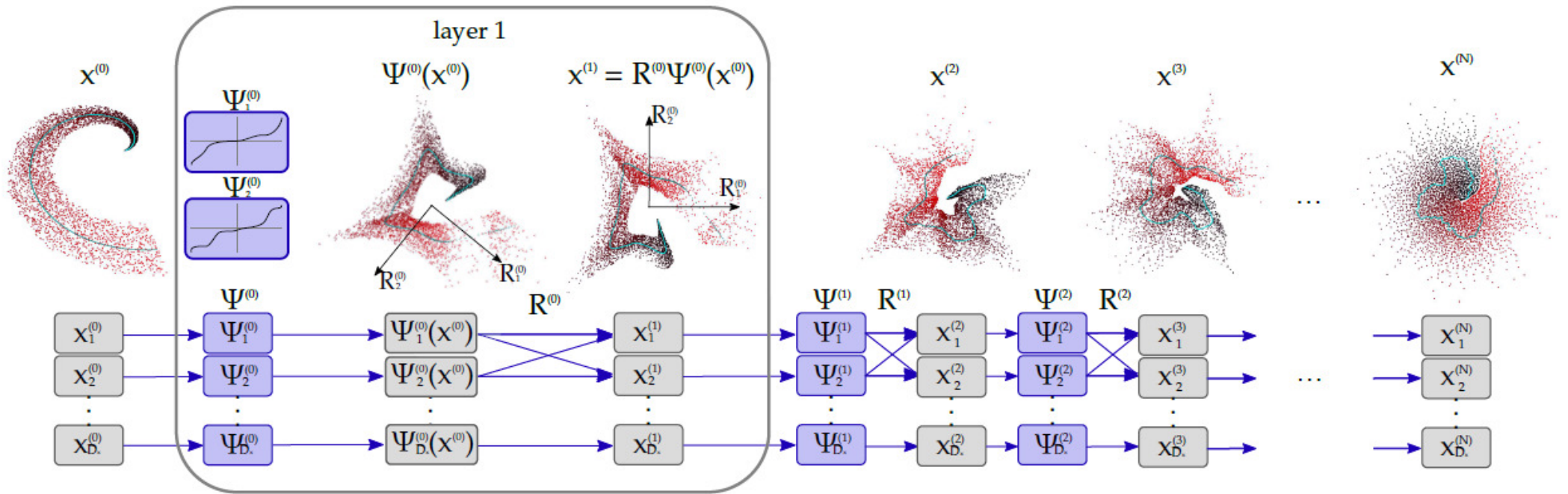
$$P(x^{(0)})$$

$$x^{(u+1)} = \underbrace{R^{(u)}}_{\text{Rotation}} \cdot \underbrace{\psi^{(u)}(x^{(u)})}_{\text{Marginal Gaussianization}}$$

GAUSSIAN PDF

$$P(x^{(N)}) = \mathcal{N}(x^{(N)}, 0, I)$$

② COMPUTATIONAL TOOLS : Information theory : GAUSSIANIZATION

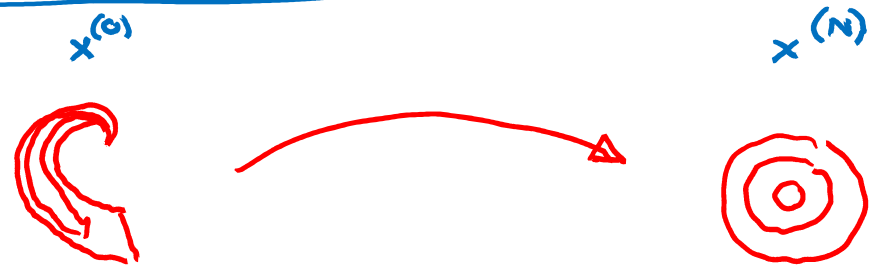


$$x^{(u+1)} = \underbrace{R^{(u)}}_{\text{Rotation}} \cdot \underbrace{\Psi^{(u)}(x^{(u)})}_{\text{Marginal Gaussianization}}$$

Rotation

Marginal
Gaussianization

② COMPUTATIONAL TOOLS : Information theory : GAUSSIANIZATION



ANY PDF
 $p(x^{(0)})$

GAUSSIAN PDF
 $p(x^{(N)}) = \mathcal{N}(x^{(N)}, 0, I)$

In ANY differentiable transform \Rightarrow In ANY Gaussianization $T(x) = 0$

$$\Delta T(x, x') = T(x) - T(x')$$

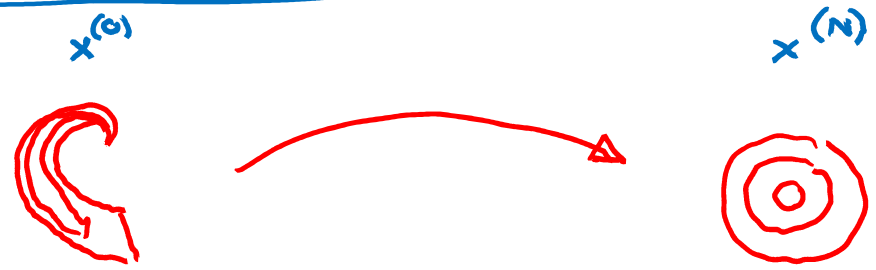
$$= \sum_{i=1}^{D_x} H(x_i) - \sum_{i=1}^{D_{x'}} H(x'_i) + \frac{1}{2} \mathbb{E}_x \left(\log |\nabla G_x(x)^\top \cdot \nabla G_x(x)| \right)$$

$$T(x) = \sum_{i=1}^{D_x} H(x_i) - \frac{D_x}{2} \log(2\pi e) + \mathbb{E}_x \left(\log |\nabla G_x(x)| \right)$$

IN RBIG \equiv ONLY UNIVARIATE OPERATIONS

$$\tilde{T}(x) = \sum_{n=0}^{N-1} \Delta \tilde{T}^{(n)} = \frac{(N-1)D_x}{2} \log(2\pi e) - \sum_{n=1}^N \sum_{i=1}^{D_x} \tilde{H}(x_i^{(n)})$$

② COMPUTATIONAL TOOLS : Information theory : GAUSSIANIZATION



ANY PDF
 $p(x^{(0)})$

GAUSSIAN PDF
 $p(x^{(N)}) = \mathcal{N}(x^{(N)}, 0, I)$

In ANY differentiable transform \Rightarrow In ANY Gaussianization $T(x) = 0$

$$\begin{aligned} \Delta T(x, x') &= T(x) - T(x') \\ &= \sum_{i=1}^{D_x} H(x_i) - \sum_{i=1}^{D_{x'}} H(x'_i) + \underbrace{\frac{1}{2} \mathbb{E}_x \left(\log |\nabla G_x(x)^\top \cdot \nabla G_x(x)| \right)} \end{aligned}$$

$$T(x) = \sum_{i=1}^{D_x} H(x_i) - \frac{D_x}{2} \log(2\pi e) + \underbrace{\mathbb{E}_x \left(\log |\nabla G_x(x)| \right)}$$

IN RBIG \equiv ONLY UNIVARIATE OPERATIONS

$$\tilde{T}(x) = \sum_{n=0}^{N-1} \Delta \tilde{T}^{(n)} = \frac{(N-1)D_x}{2} \log(2\pi e) - \sum_{n=1}^N \sum_{i=1}^{D_x} \tilde{H}(x_i^{(n)})$$

GOOD TO ESTIMATE
 INFORM. THEORY MEASURES!
 17/41

②

COMPUTATIONAL TOOLS :

Information theory

UNIFORMIZATION : GAUSSIANIZATION

Original



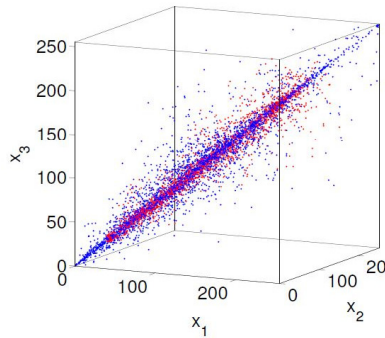
PCA



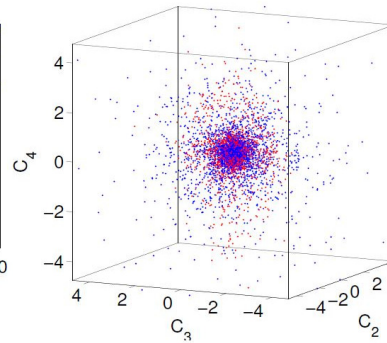
SPCA ($\gamma = 1$)



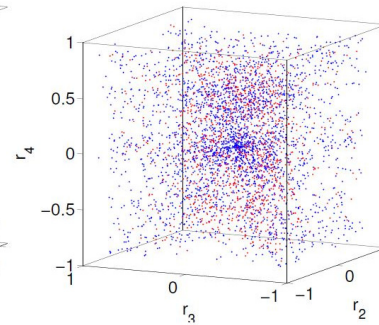
SPCA ($\gamma = 1/3$)



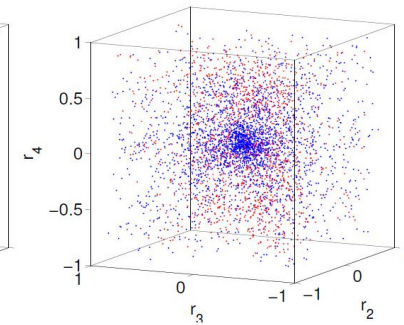
$P(x_j|x_i)$ Spatial domain
MI = 1.598 bits



$P(C_j|C_i)$ PCA domain
MI = 0.198 bits



$P(r_j|r_i)$ SPCA infomax
MI = 0.057 bits

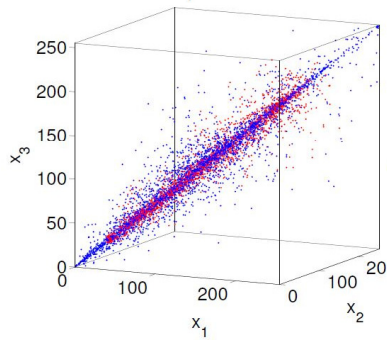
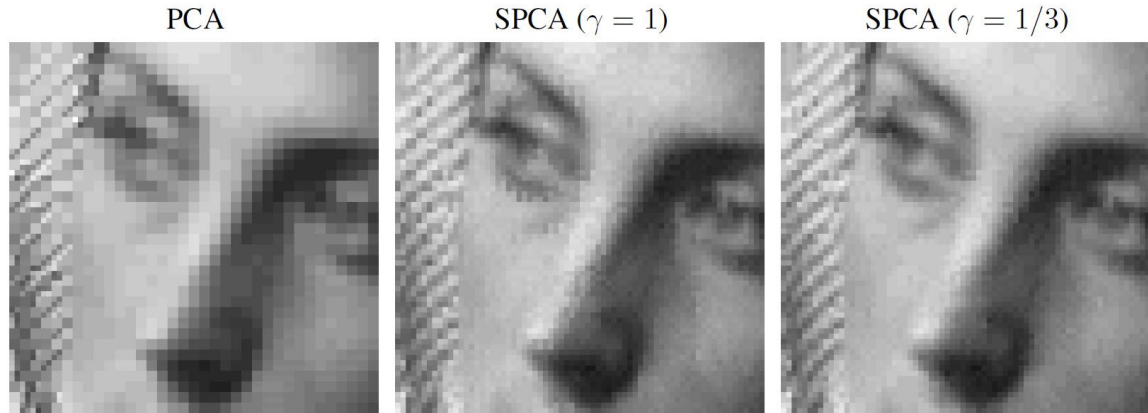
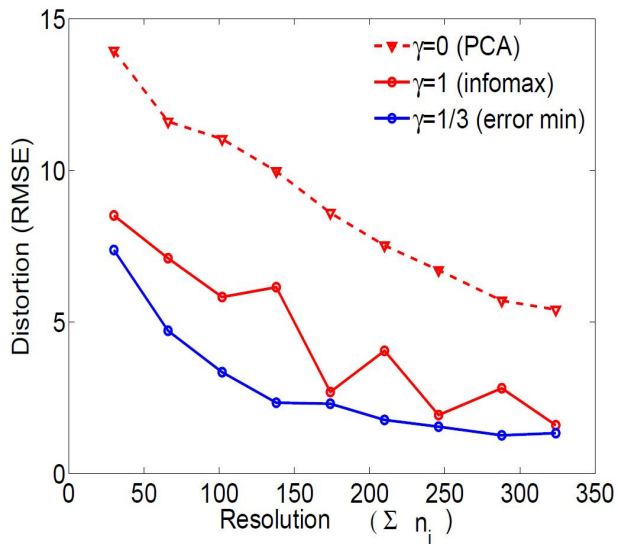


$P(r_j|r_i)$ SPCA errormin
MI = 0.075 bits

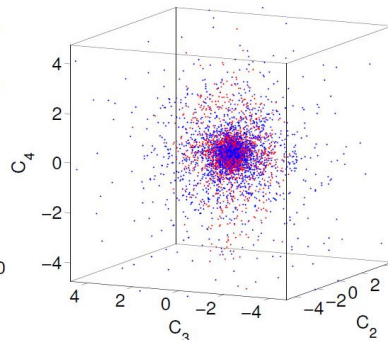
2

COMPUTATIONAL TOOLS :

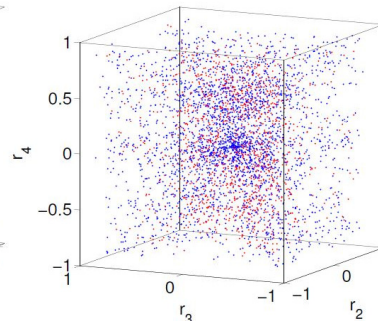
Information theory
UNIFORMIZATION : GAUSSIANIZATION



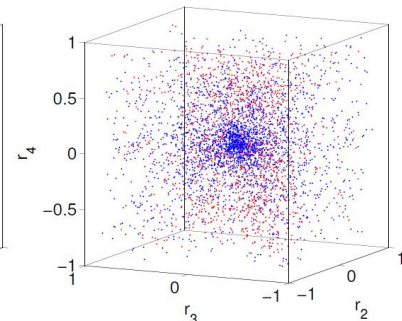
$P(x_j|x_i)$ Spatial domain
MI = 1.598 bits



$P(C_j|C_i)$ PCA domain
MI = 0.198 bits



$P(r_j|r_i)$ SPCA infomax
MI = 0.057 bits



$P(r_j|r_i)$ SPCA errormin
MI = 0.075 bits

18/41

②

COMPUTATIONAL TOOLS

Information theory

UNIFORMIZATION : GAUSSIANIZATION

Total Correlation

		D_x	RBIG	kNN	KDP	expF	vME	Ens
Gaussian	-	3	0.87	0.94	76.65	0.63	4.27	4.03
		10	0.97	23.48	>100	0.27	31.72	34.83
		50	1.45	45.77	>100	0.52	>100	54.74
		100	1.55	52.78	>100	0.41	>100	59.94
Rotated	-	3	1.70	1.80	82.90	16.80	1.90	9.40
		10	8.30	27.20	>100	11.00	24.20	38.70
		50	7.70	51.10	>100	15.10	>100	59.40
		100	7.50	57.80	>100	15.50	>100	64.50
Student	$\nu = 3$	3	7.01	13.55	>100	94.03	>100	66.59
		10	32.93	16.73	>100	67.32	>100	15.27
		50	18.18	12.02	>100	29.44	>100	24.65
		100	12.71	17.41	>100	21.12	>100	28.63
	$\nu = 5$	3	26.61	52.76	>100	89.74	81.85	133.12
		10	23.94	19.74	>100	49.60	>100	12.31
		50	10.10	16.87	>100	20.29	>100	32.14
		100	7.10	22.53	>100	15.39	>100	34.96
	$\nu = 20$	3	88.27	>100	>100	48.56	>100	>100
		10	3.05	11.86	>100	10.51	>100	19.93
		50	3.07	33.17	>100	4.54	>100	52.62
		100	1.31	35.56	>100	3.43	>100	49.46

$\tilde{T}(x)$

$\tilde{H}(x)$

$D_{KL}(y|x)$

$\tilde{I}(x, y)$

Differential Entropy

		D_x	RBIG	kNN	KDP	expF	vME	Ens
Gaussian	-	3	0.87	1.70	112.30	1.10	8.80	12.00
		10	1.20	27.90	179.80	0.10	34.70	40.30
		50	0.90	32.20	107.40	0.10	108.40	38.10
		100	0.70	30.70	89.60	0.10	94.20	34.60
Rotated	-	3	4.00	6.20	171.40	36.80	3.70	30.10
		10	12.20	38.50	241.80	17.90	31.80	53.90
		50	6.80	44.60	136.60	13.50	87.90	51.60
		100	5.50	42.50	110.70	11.50	94.30	47.20
Student	$\nu = 3$	3	0.75	0.76	34.93	11.90	3.13	1.99
		10	2.82	1.44	137.19	15.55	53.19	1.77
		50	6.03	3.47	195.30	22.11	175.94	7.09
		100	6.61	8.57	228.62	24.44	166.09	13.72
	$\nu = 5$	3	0.51	0.70	24.75	3.42	1.38	1.94
		10	1.12	1.25	96.73	5.52	59.29	1.21
		50	2.82	4.84	146.63	9.59	202.48	8.89
		100	3.11	10.67	184.02	11.36	195.17	16.24
	$\nu = 20$	3	0.54	0.71	19.19	0.76	1.32	1.56
		10	0.48	0.84	69.83	1.56	46.62	0.37
		50	0.95	6.66	107.74	3.31	219.86	11.13
		100	0.68	13.45	138.98	4.20	214.41	19.35

Kullback-Leibler Div.

		dim	RBIG	kNN	expF	vME
Gaussian, different means	$\mu_2 = 0.2$	3	15.49	16.90	10.28	92.28
		10	19.50	22.47	3.27	>1000
		50	32.04	40.85	13.34	>1000
		100	47.40	41.24	28.14	>1000
	$\mu_2 = 0.4$	3	3.55	7.98	5.57	24.22
		10	5.25	22.93	2.02	604.17
		50	8.67	40.91	3.40	>1000
		100	4.83	43.49	8.70	>1000
	$\mu_2 = 0.6$	3	3.75	6.39	3.89	12.23
		10	2.81	24.72	1.85	213.72
		50	13.83	43.11	1.83	897.65
		100	42.42	46.00	5.11	686.96
Gaussians, different covs.	$\mu_2 = 0.5$	3	24.93	27.30	4.89	63.90
		10	18.80	103.65	2.64	>1000
		50	23.62	173.62	8.42	>1000
		100	32.56	200.33	17.59	>1000
	$\mu_2 = 0.75$	3	21.04	24.77	3.72	36.64
		10	10.44	96.85	1.86	605.00
		50	10.07	159.16	5.70	>1000
		100	13.66	179.67	11.40	>1000
	$\mu_2 = 0.9$	3	17.12	25.95	3.40	26.15
		10	6.77	94.42	1.60	448.87
		50	3.40	152.46	4.81	>1000
		100	5.96	170.28	9.43	>1000
Gaussian vs. Student	$\nu = 2$	3	5.08	29.58	793.53	5.78
		10	32.72	83.51	1278.91	596.63
		50	59.37	468.33	2783.43	>1000
		100	42.11	1024.30	4330.18	>1000
	$\nu = 4$	3	17.09	95.02	148.08	22.52
		10	42.84	157.63	219.26	963.37
		50	60.53	584.46	547.48	>1000
		100	41.71	1214.61	962.45	>1000
	$\nu = 7$	3	8.34	271.61	35.78	59.69
		10	38.78	307.82	49.77	>1000
		50	48.80	713.36	145.15	>1000
		100	26.01	1399.34	278.93	>1000
Student vs. Student	$\nu = 2$	3	9.08	13.87	3442.45	>1000
		10	20.57	57.60	7462.58	346.61
		50	85.14	405.47	19991.36	>1000
		100	242.80	939.24	35064.60	>1000
	$\nu = 4$	3	9.51	47.03	1502.19	48.89
		10	36.33	139.12	2561.86	>1000
		50	37.29	656.95	7997.12	>1000
		100	60.52	1441.18	13033.03	>1000
	$\nu = 7$	3	13.13	126.41	589.47	128.84
		10	23.13	301.97	1070.70	>1000
		50	28.34	976.95	3689.57	>1000
		100	145.88	2046.95	6370.43	>10000

Szabo JMLR 2014

kNN

Partition trees

Exp. Family

Von Mises

Ensemble

<https://isp.uv.es/RBIG4IT.htm>

Mutual Information

		D_x	RBIG	kNN	KDP	expF	vME	Ens
Gaussians	-	3	10.60	26.00	149.10	9.20	13.20	48.50
		10	9.60	76.30	102.60	23.70	311.00	91.00
		50	6.80	104.70	100.70	39.50	68.00	105.50
		100	11.70	107.20	>1000	42.60	77.40	106.10
Student vs. Student	$\nu = 3$	3	35.72	95.32	>1000	63.73	>1000	86.58
		10	22.26	2.66	118.51	18.14	>1000	66.77
		50	1.51	88.38	104.50	36.10	810.02	105.83
		100	15.34	98.66	>1000	65.71	789.55	105.34
$\nu = 5$	3	18.51	118.04	>1000	96.49	>1000	96.41	
	10	3.07	24.83	113.89	5.39	>1000	101.26	
	50	10.91	102.89	105.08	25.17	849.12	117.30	
	100	24.43	105.41	101.10	42.57	805.44	110.58	
$\nu = 20$	3	73.63	194.16	>1000	14.63	>1000	15.36	
	10	40.02	108.82	110.68	29.69	>1000	208.20	
	50	29.98	149.53	102.93	36.30	946.93	154.88	
	100	37.21	128.27	101.44	43.77	844.41	127.67	

② COMPUTATIONAL TOOLS : Information theory

* Information theory gives intuition } - Criterion for $S(x)$ ($\nabla S(x)$)
- Principles } - Entropy maxime.
- Redundancy reduct.

* We have tools } - SPCA
- RBIG

<https://isp.uv.es/RBIG4IT.htm>

③ NATURAL SCENES ARE NOT ARBITRARY: Color / images / movies

* The manifold view (rediscovered in 90's)

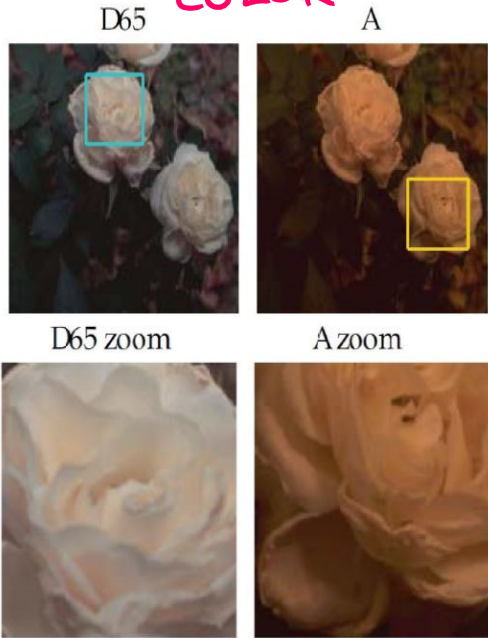
* Non uniformity

* Smoothness \rightarrow Redundancy

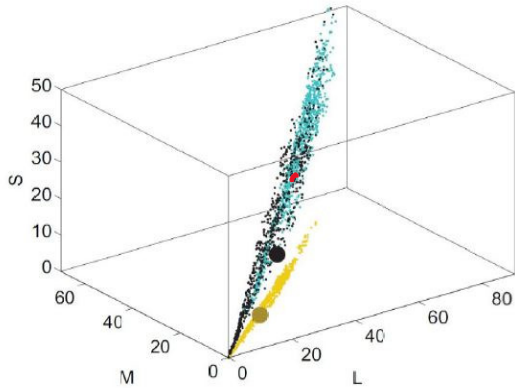
* Non Gaussianity

③ NATURAL SCENES ARE NOT ARBITRARY: Color / images / movies

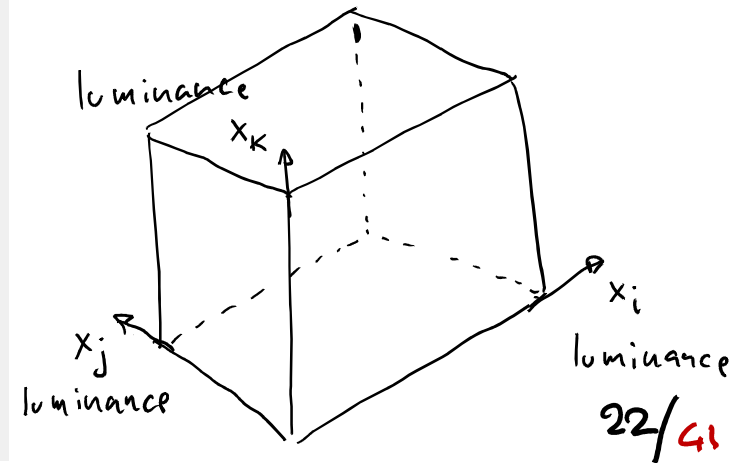
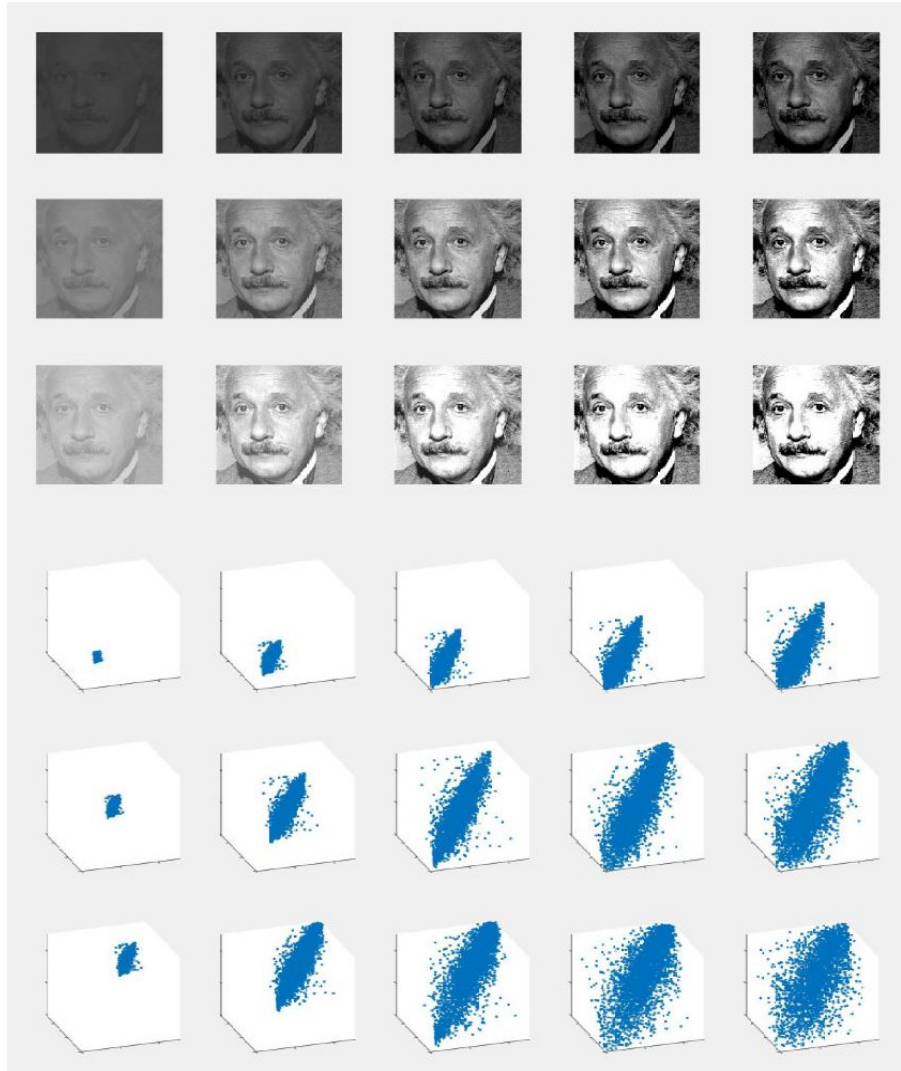
COLOR



LMS distribution

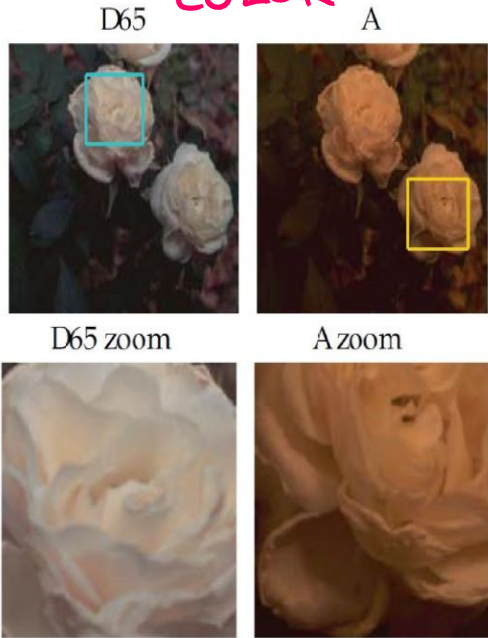


SPATIAL TEXTURE

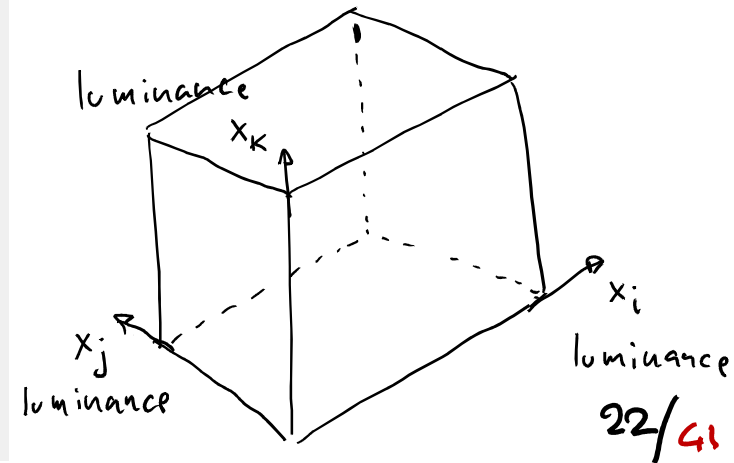
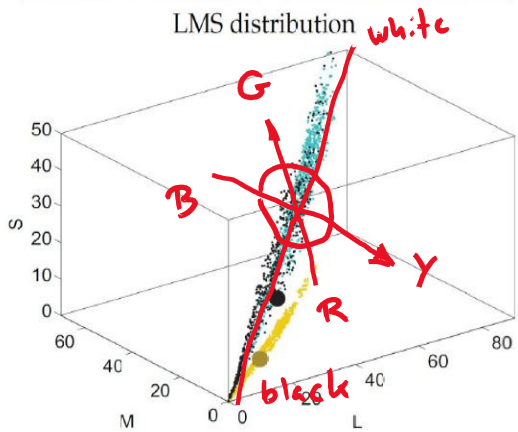
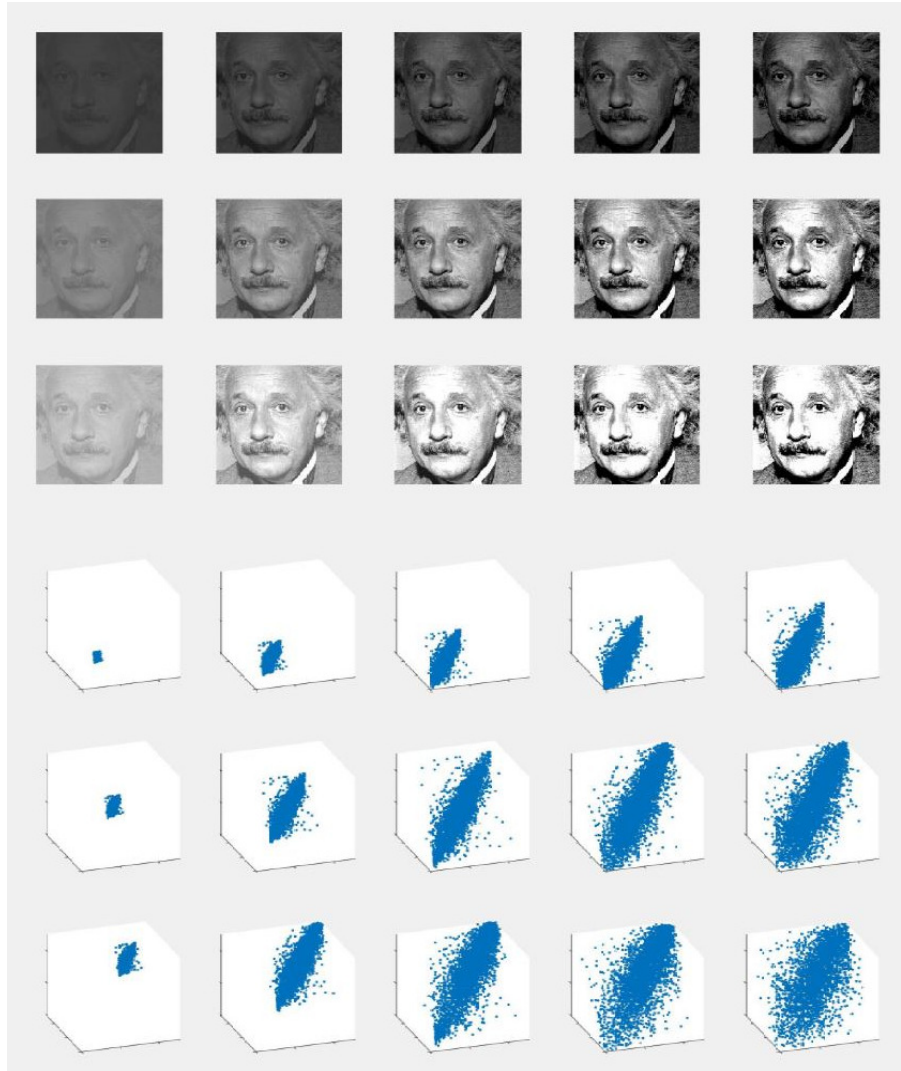


③ NATURAL SCENES ARE NOT ARBITRARY: Color / images / movies

COLOR

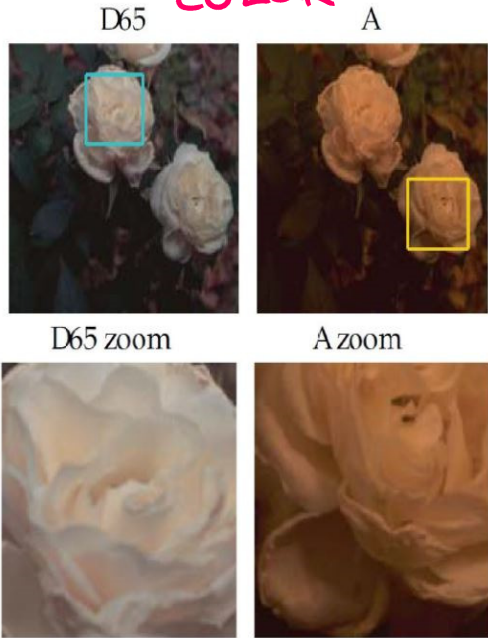


SPATIAL TEXTURE

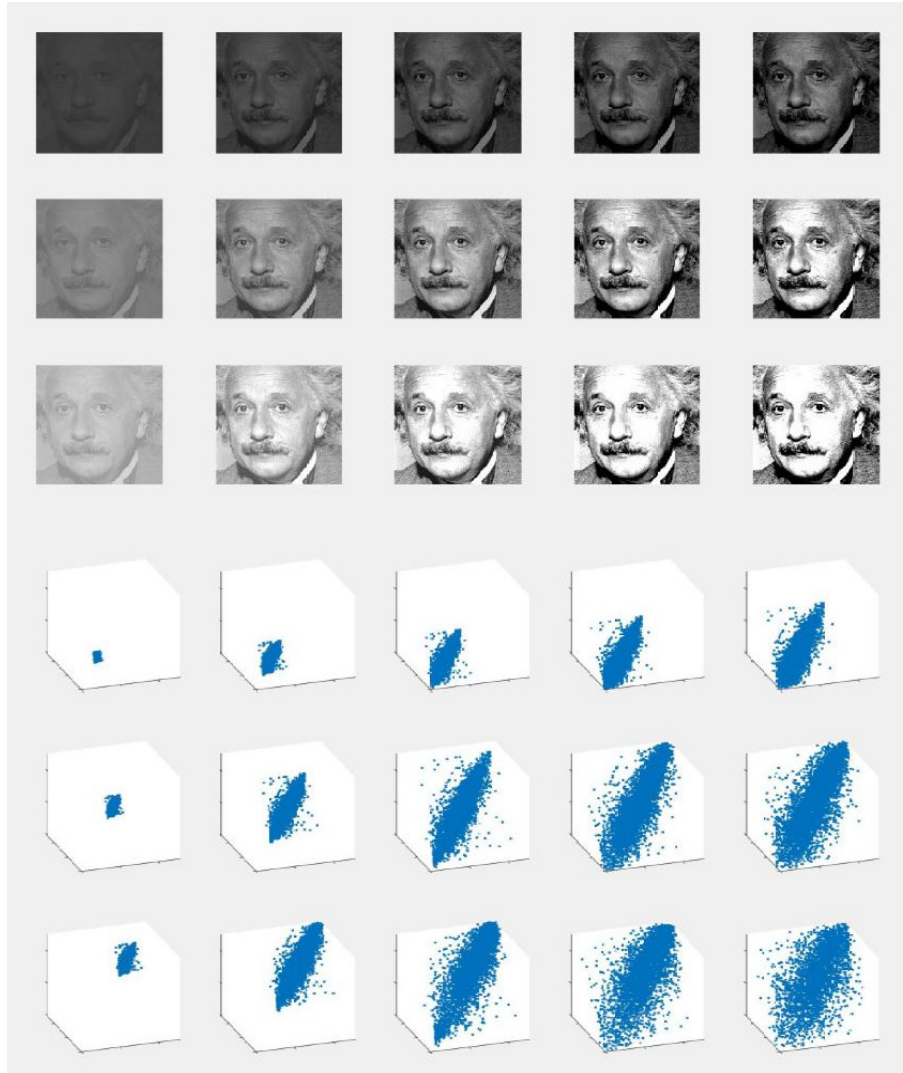


③ NATURAL SCENES ARE NOT ARBITRARY: Color / images / movies

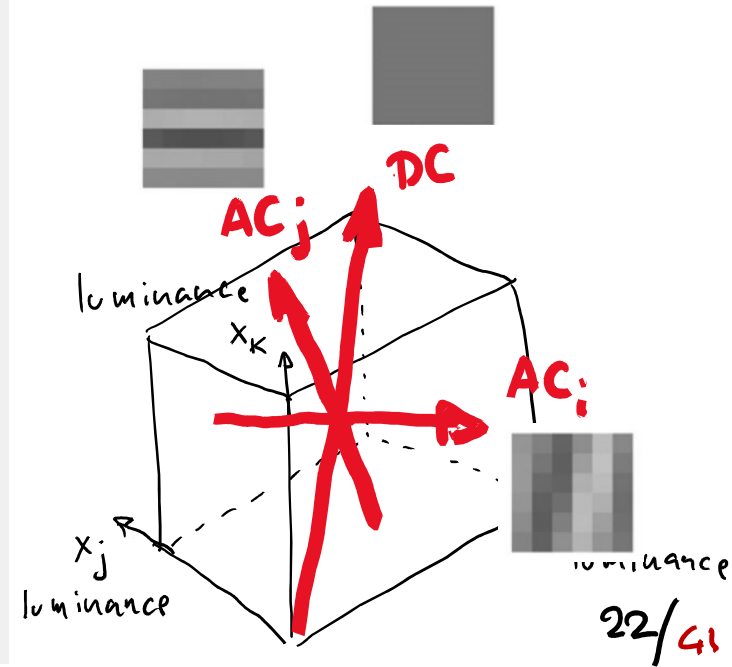
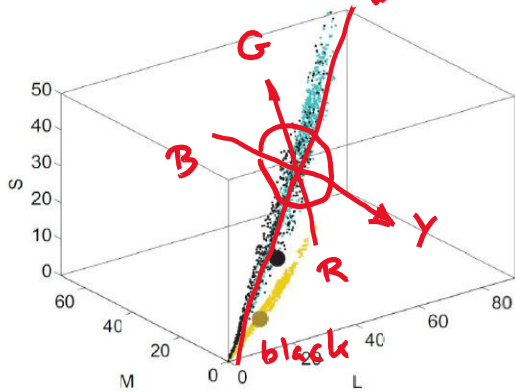
COLOR



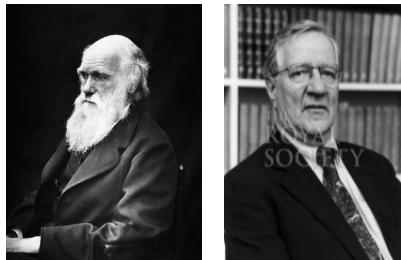
SPATIAL TEXTURE



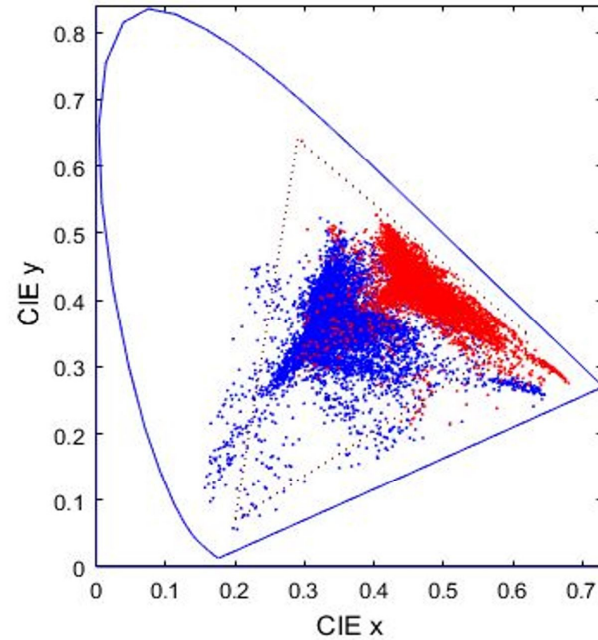
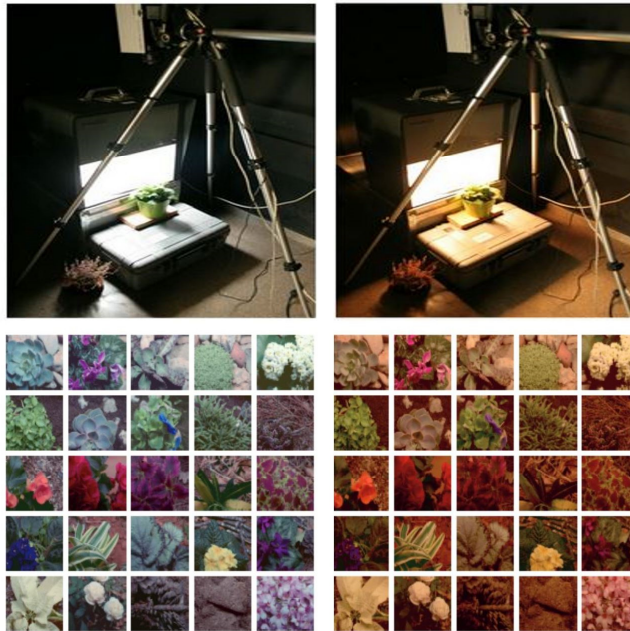
LMS distribution



③ NATURAL SCENES ARE NOT ARBITRARY: Color / images / movies



Natural Environment



Laparra & Malo *Neural Comp.* 2012, Gutmann & Malo *PLOS* 2014 https://isp.uv.es/data_color.htm

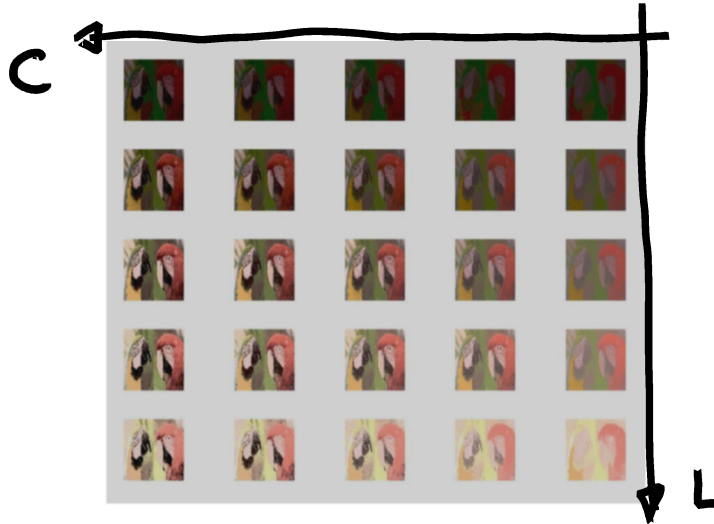
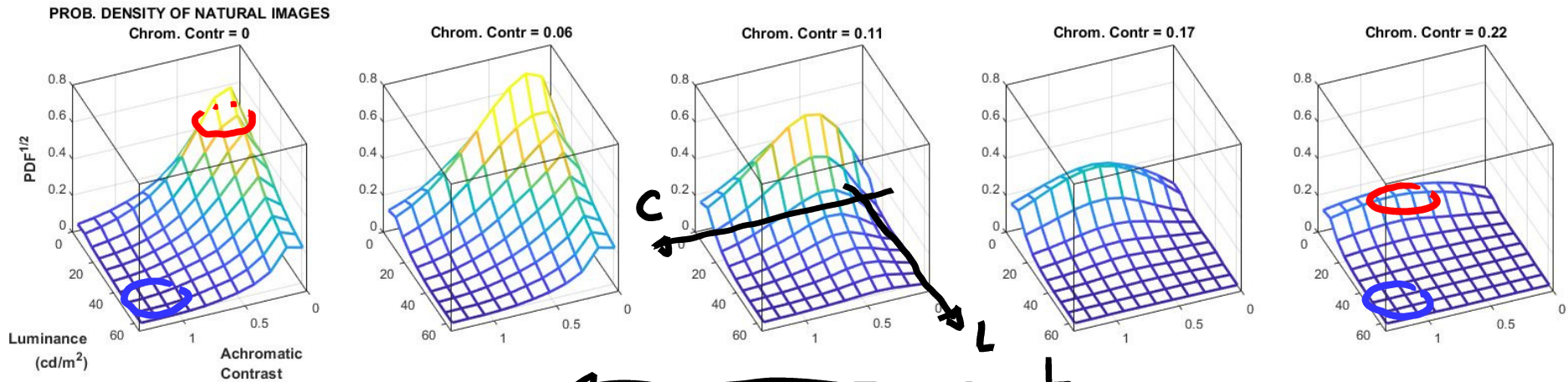


Gómez & Malo *J. Neurophysiol.* 2020 <https://isp.uv.es/code/visioncolor/infoWilsonCowan.html>

③ NATURAL SCENES ARE NOT ARBITRARY: Color / images



Probability Density Function of Natural Images



③ NATURAL SCENES ARE NOT ARBITRARY: Color / images / movies

... movies

Laparra & Malo Front. Neurosci. 2015

Li, Gomez, Bertalmio & Malo Submit. Jov. 2021

... non-gaussianity

Olschansen & Simoncelli Ann. Rev. Neurosci. 01



In summary:


- * Images have interesting regularities \Rightarrow will determine $S(x)$
- * Images are mostly achromatic & low contrast
- * Images are mostly lowpass (spatio-temporally)
- * Images are not Gaussian


https://isp.uv.es/data_color.htm

https://isp.uv.es/after_effects


④ THE TWO SIDES OF THE EFFICIENT CODING HYPOTHESIS:


Stats,  Biology


The conventional way
Stats  Biology

The alternative way
Stats  Biology

④ THE TWO SIDES OF THE EFFICIENT CODING HYPOTHESIS:

Stats,  Biology 

The conventional way
Stats  Biology

REDUNDANCY REDUCTION / INFOMAX

- Linear analysis } PCA
- } ICA

Opponent Channels Frq. Sts.
V1-like receptive fields.

Gutmann, Laparra, Hyvarinen & Malo PLOS 2014

- Non-linearities } SPCA
- } Color
- } Texture
- } Motion

Laparra & Malo Front. Neurosci. 2015

ERROR MINIMIZATION

CSTFs in Autoencoders

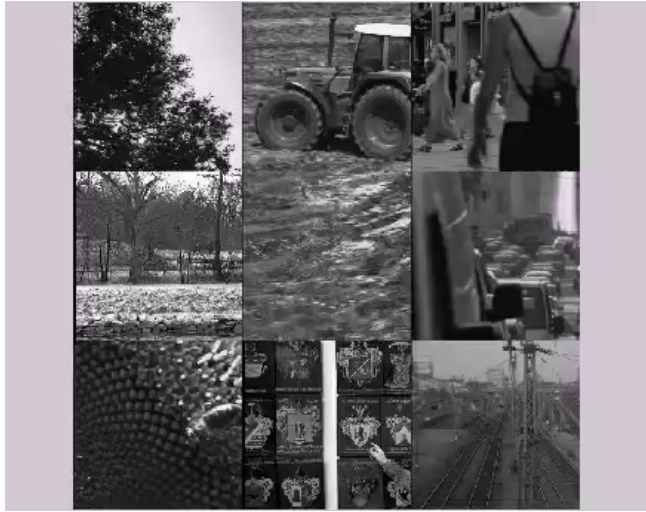
Gomez-Villa et al. Vision Res. 2020

CLASSIFICATION

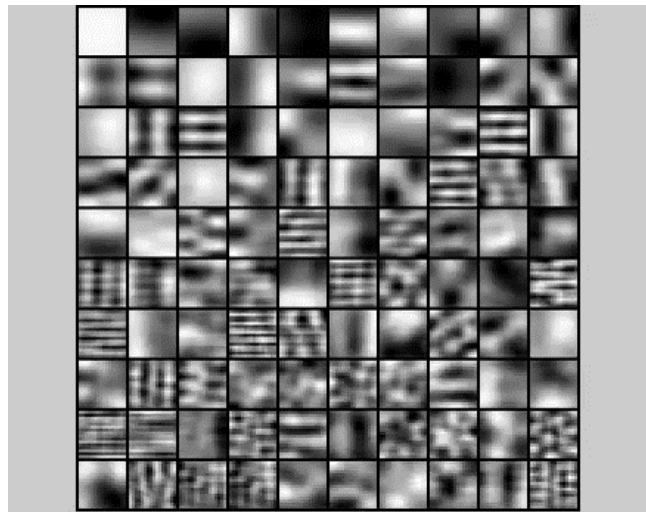
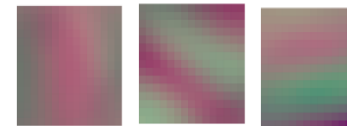
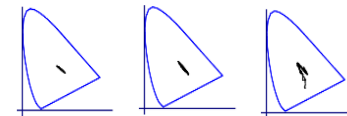
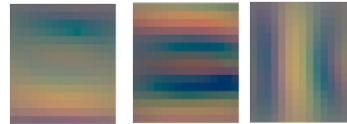
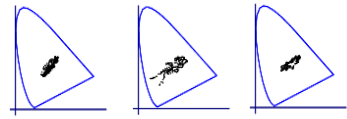
V1-like representation

④ THE TWO SIDES OF THE EFFICIENT CODING HYPOTHESIS:

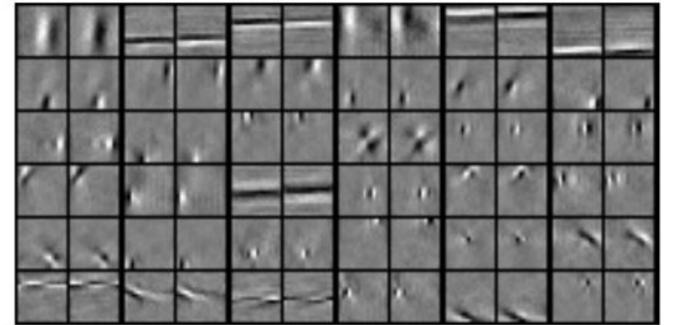
Stats, \rightleftarrows Biology



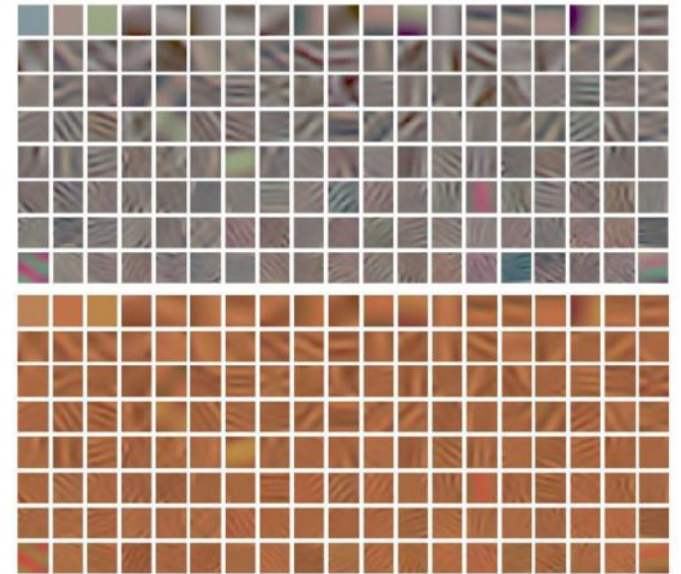
Linear analysis } PCA
ICA



Receptive fields in phase-quadrature via Complex ICA
[LNCS 11]



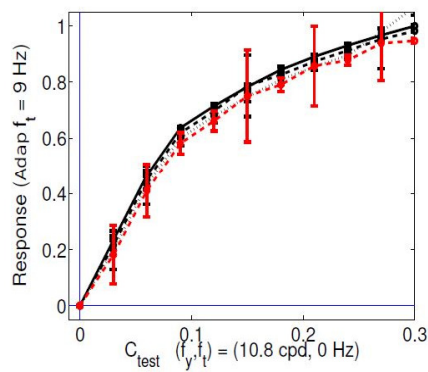
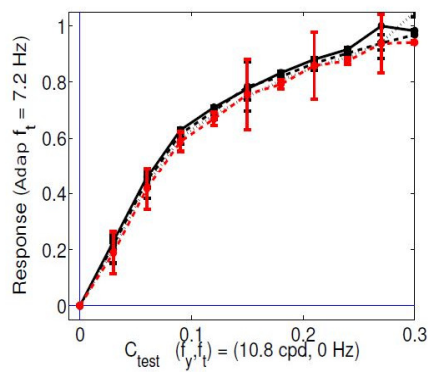
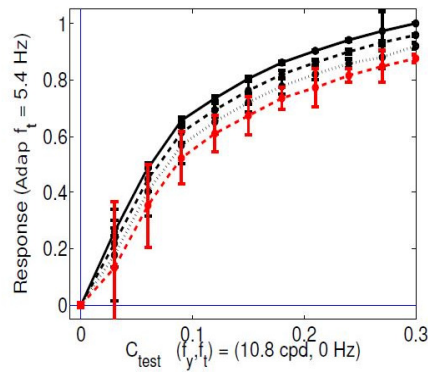
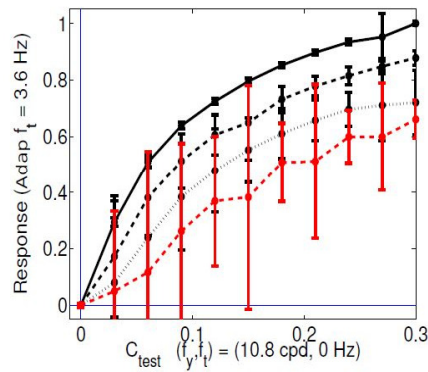
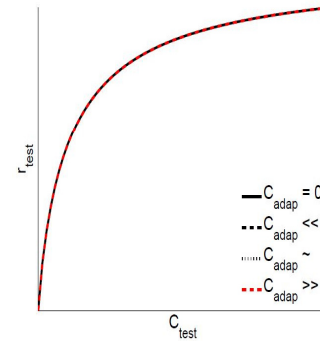
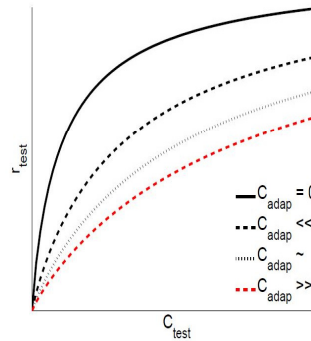
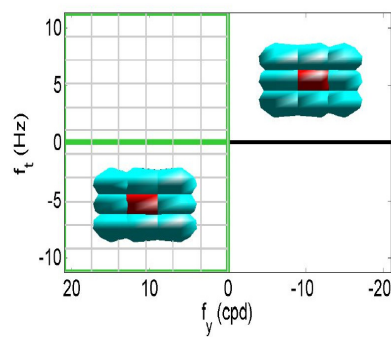
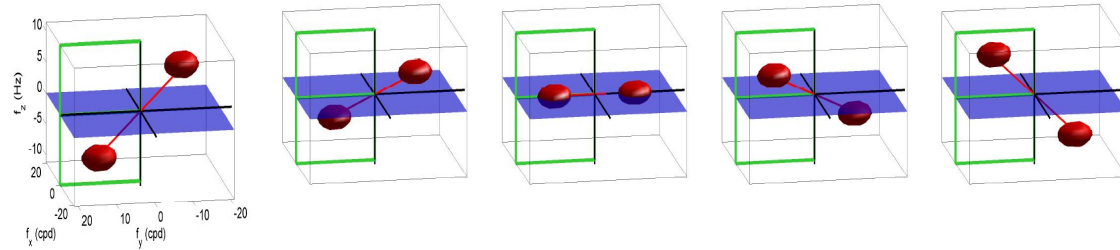
Spatio-chromatic receptive fields via Higher-Order CCA
[PLoS 14]



4

THE TWO SIDES OF THE EFFICIENT CODING HYPOTHESIS:

Stats. \rightarrow Biology

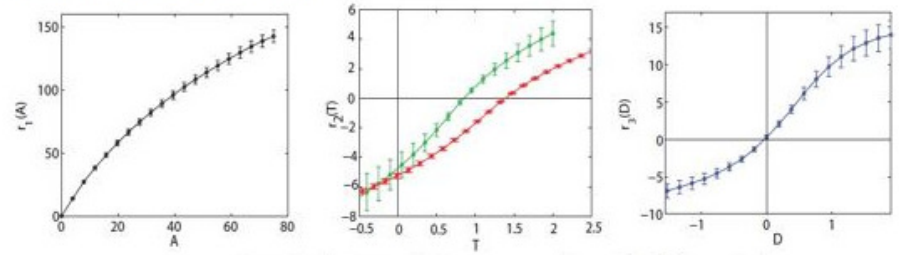
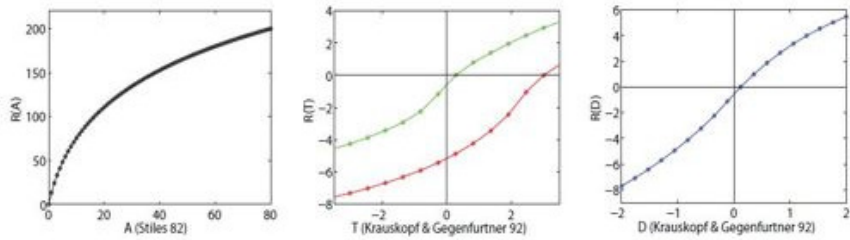
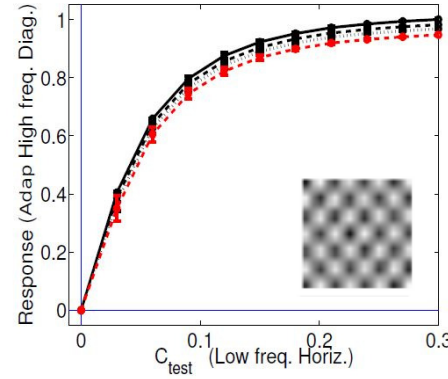
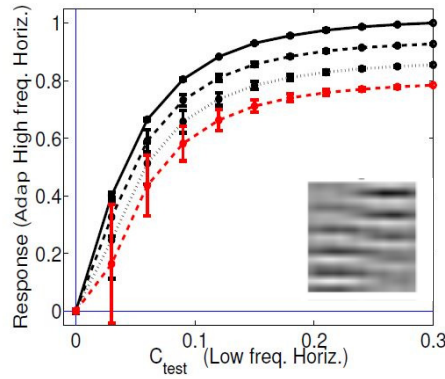
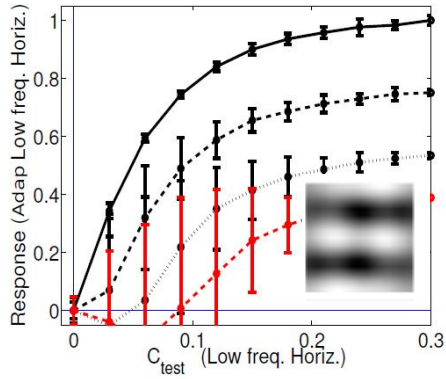


4

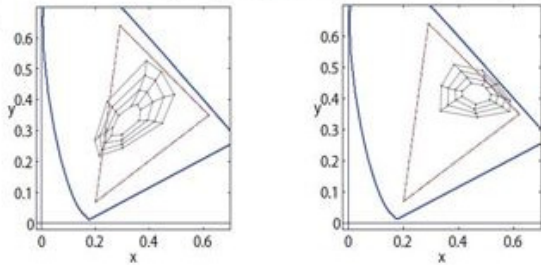
THE TWO SIDES OF THE EFFICIENT CODING HYPOTHESIS:

Stats. \rightarrow Biology

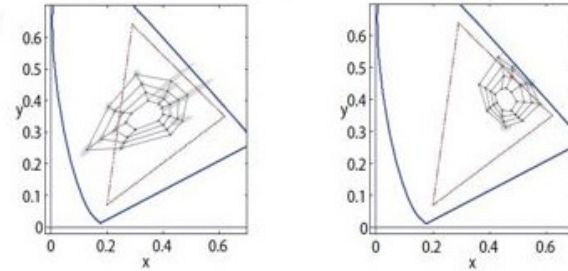
Non-linearities SPCA }
 • Color
 • Texture
 • Motion



Actual behavior



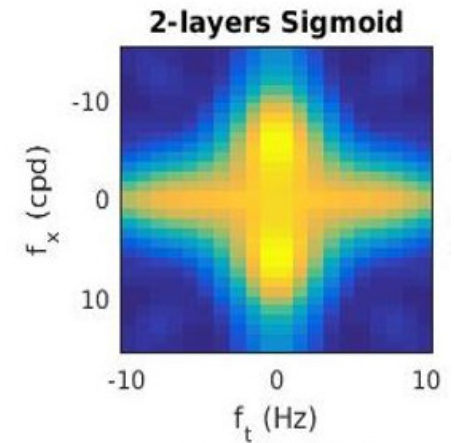
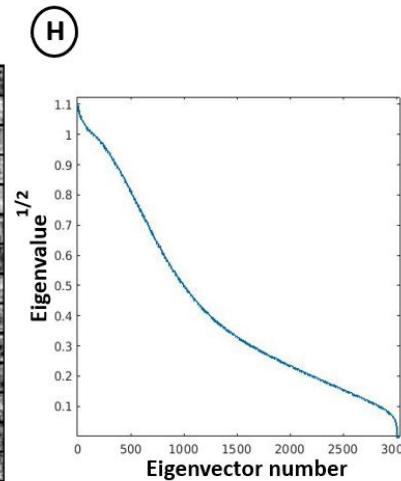
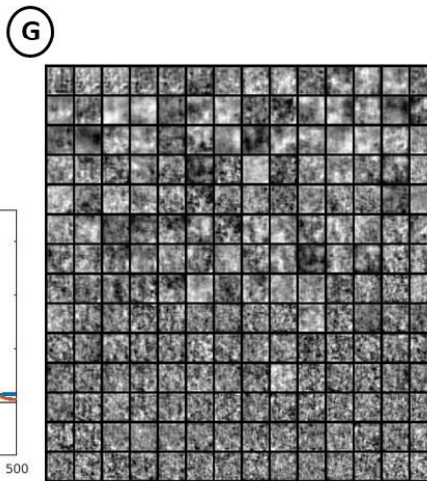
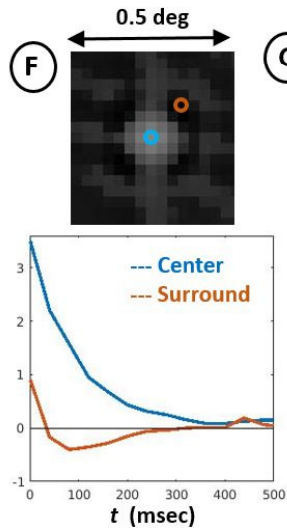
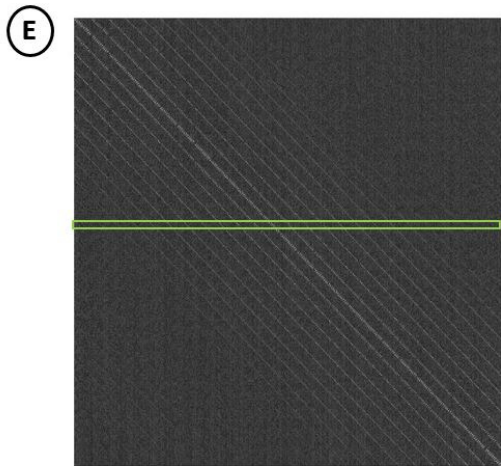
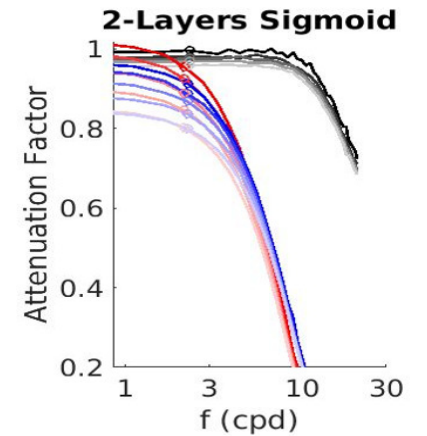
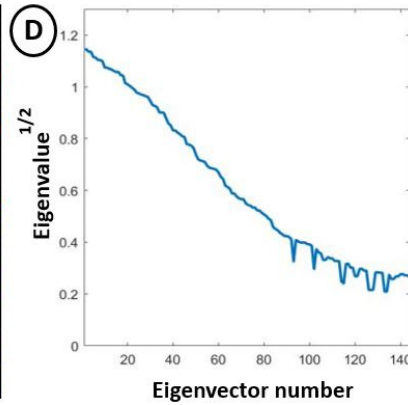
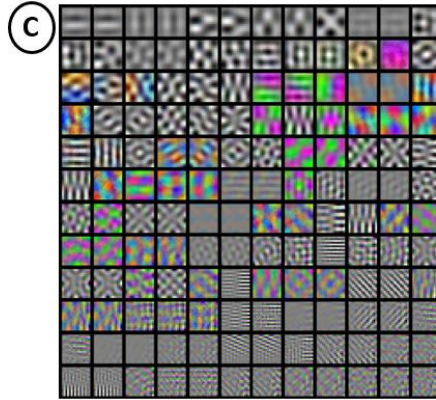
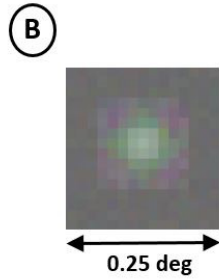
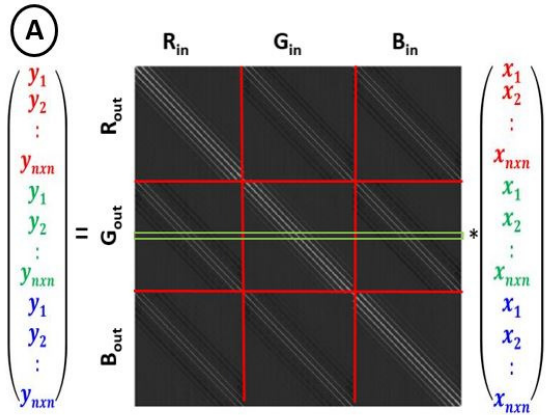
ERRORMIN



4

THE TWO SIDES OF THE EFFICIENT CODING HYPOTHESIS:

Stats, \rightarrow Biology



• Error minimization

CSTs in Autoencoders

4

THE TWO SIDES OF THE EFFICIENT CODING HYPOTHESIS:

Stats, \rightleftarrows Biology

REVIEW

doi:10.1038/nature10539

NATURE 2015

Deep learning

Yann LeCun^{1,2}, Yoshua Bengio³ & Geoffrey Hinton^{4,5}

Deep learning allows computational models that are composed of multiple processing layers to learn representations of data with multiple levels of abstraction. These methods have dramatically improved the state-of-the-art in speech recognition, visual object recognition, object detection and many other domains such as drug discovery and genomics. Deep learning discovers intricate structure in large data sets by using the backpropagation algorithm to indicate how a machine should change its internal parameters that are used to compute the representation in each layer from the representation in the previous layer. Deep convolutional nets have brought about breakthroughs in processing images, video, speech and audio, whereas recurrent nets have shone light on sequential data such as text and speech.

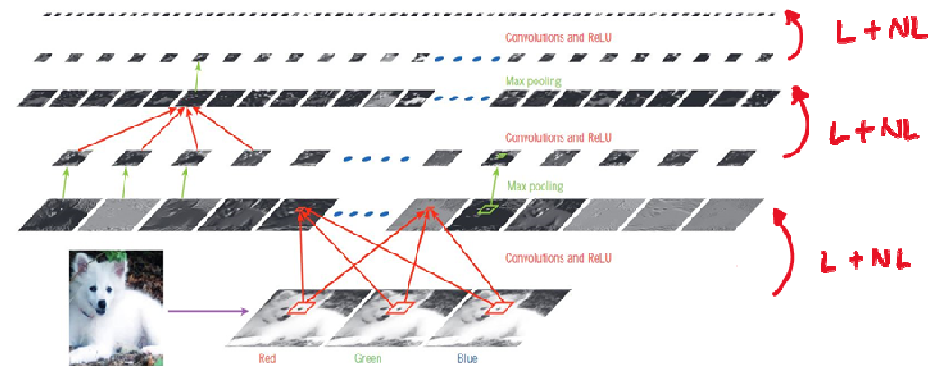


Figure 2 | Inside a convolutional network.

NIPS 2012



32/41

Classification performance \rightarrow

④ THE TWO SIDES OF THE EFFICIENT CODING HYPOTHESIS:

Stats, ~~→~~ Biology

The alternative way

Stats ← Biology

Malo & Simoncelli IEEE Trans. Im. Proc. 2006
Malo & Laparra Neural Comp. 2010

Redundancy reduction in psychophysical models } - Analytic
 } - RBG

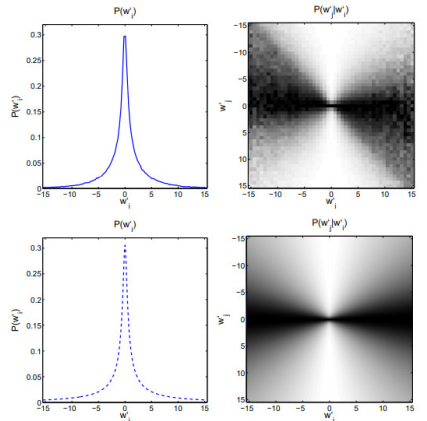
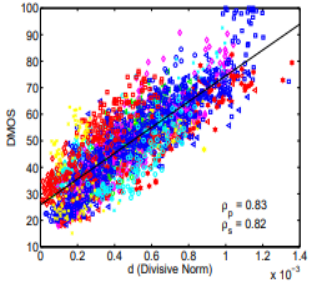
Gómez-Villa et al. J. Neurophysiol. 2020

Information transmission in psychophysical models RBG

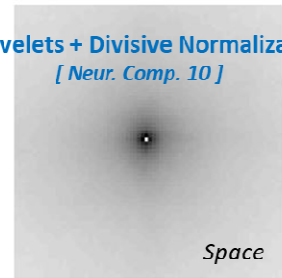
Malo J. Math. Neurosci. 2020

4 THE TWO SIDES OF THE EFFICIENT CODING HYPOTHESIS:

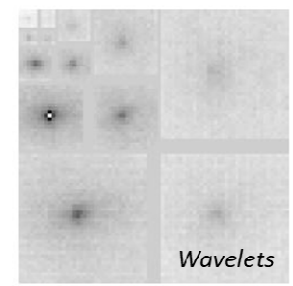
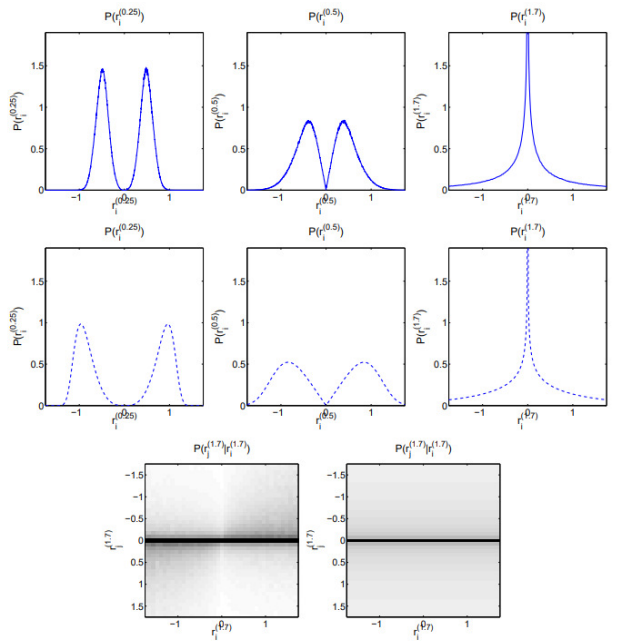
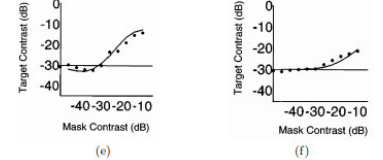
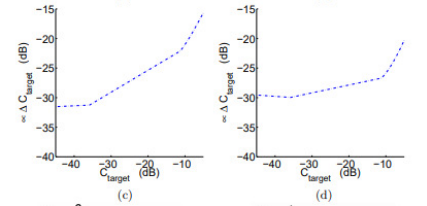
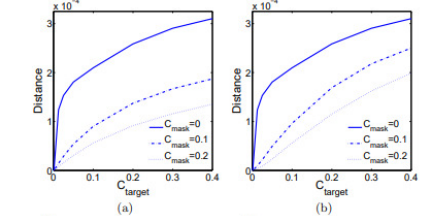
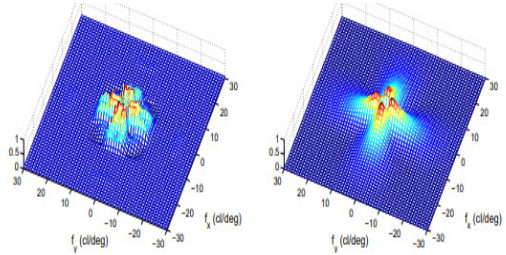
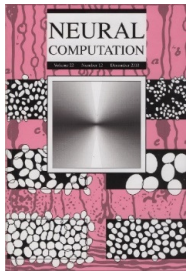
Stats, $\xrightarrow{\text{red arrow}}$ Biology



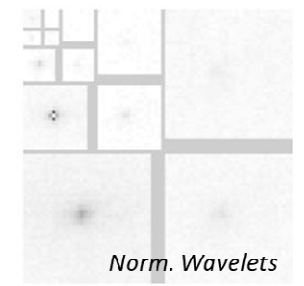
Wavelets + Divisive Normalization
[*Neur. Comp. 10*]



$MI_x: 0.38, [0.21, 1.70]$ bits



$MI_w: 0.052, [10^{-3}, 0.27]$ bits



$MI_r: 0.009, [10^{-4}, 0.15]$ bits



$MI_{R_{L_2}}: 0.003, [6 \cdot 10^{-5}, 0.06]$ bits



$MI_{R_{L_p}}: 0.002, [10^{-5}, 0.05]$ bits

Local-DCT + Divisive Normalization
[*Im.Vis.Comp.97, IEEE TIP 06*]

	pixels	local-DCT	local-PCA	normalized-DCT
\bar{I}_r	0.69	0.28	0.29	0.06

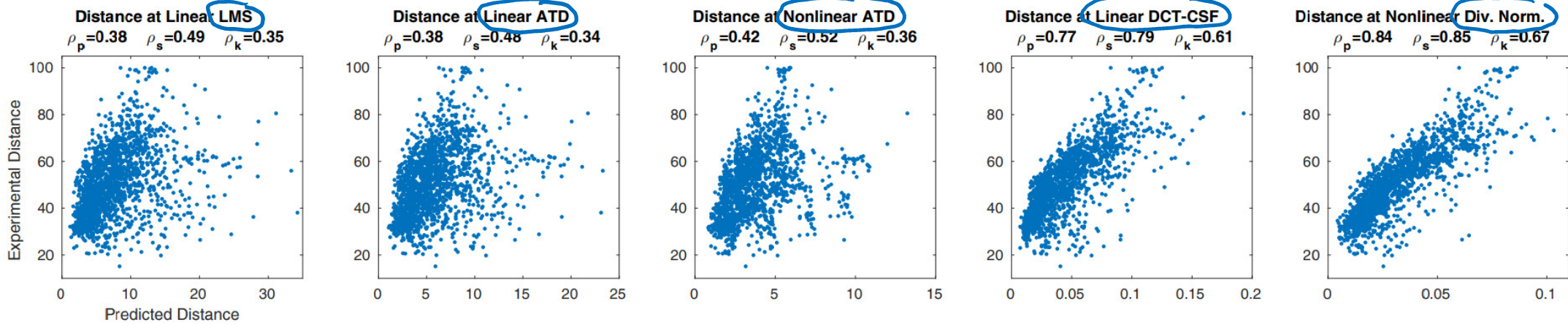
④ THE TWO SIDES OF THE EFFICIENT CODING HYPOTHESIS:

Stats.  Biology

Information transmission in psychophysical models RBG

Malo J. Math. Neurosci. 2020

4 THE TWO SIDES OF THE EFFICIENT CODING HYPOTHESIS: Stats. $\xrightarrow{\text{red arrow}}$ Biology

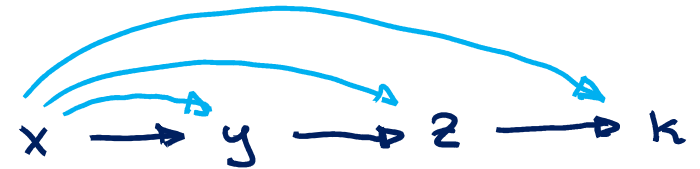


Pearson correlation with human viewers using different building blocks (or model layers)

	Spatial Extent	$r^{(1)}$	$r^{(2)}$	$x^{(2)}$	$r^{(3)}$	$x^{(3)}$
More flexible model	(0.27 deg)	0.38	0.38	0.42	0.77	0.51
Baseline model	(0.27 deg)	0.38	0.38	0.42	0.77	0.84
More rigid model	(0.27 deg)	0.38	0.38	0.42	0.77	0.79
Totally rigid model	(0.27 deg)	0.38	0.38	0.38	0.68	0.68
Baseline model	(0.05 deg)	0.26	0.27	0.31	0.37	0.40

Assumptions:

(1) single-step transforms



(2) Constant SNR (5% noise)

④ THE TWO SIDES OF THE EFFICIENT CODING HYPOTHESIS:

Stats. $\xrightarrow{\text{red arrow}}$ Biology

Redundancy
Reduction
 $\Delta T(x^{\text{input}}, x^{\text{resp.}})$

Pearson correlation with human viewers using different building blocks (or model layers).

	Spatial Extent	$r^{(1)}$	$r^{(2)}$	$x^{(2)}$	$r^{(3)}$	$x^{(3)}$
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Baseline model	(0.05 deg)	0.26	0.27	0.31	0.37	0.40

Transmitted
Information
 $I(x^{\text{in}}, x^{\text{resp}})$

4 Stats. \rightarrow Biology

Redundancy Reduction
 $\Delta T(x^{input}, x^{resp.})$

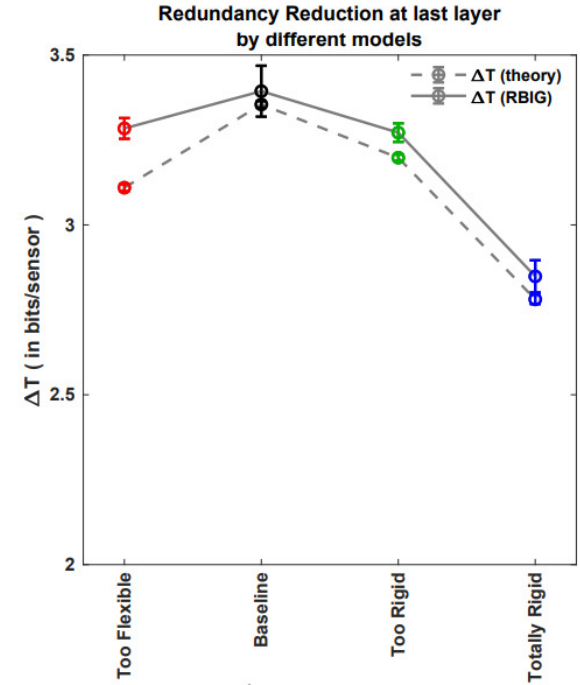
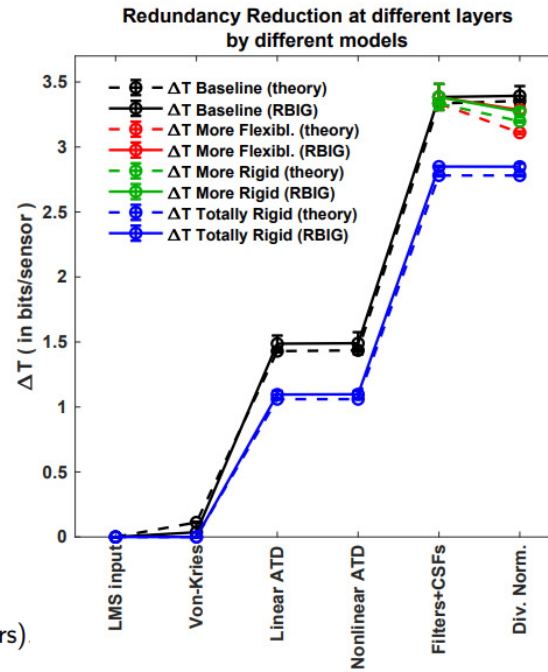
ΔT_{RBIG}

$$\Delta T_{theor} = \sum_i h(x_i^{in}) - h(x_i^{resp}) + E_x \left[\log_2 |\nabla S| \right]$$

Pearson correlation with human viewers using different building blocks (or model layers).

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Transmitted Information
 $I(x^{in}, x^{resp})$



4 Stats. \rightarrow Biology

Redundancy Reduction
 $\Delta T(x^{input}, x^{resp.})$

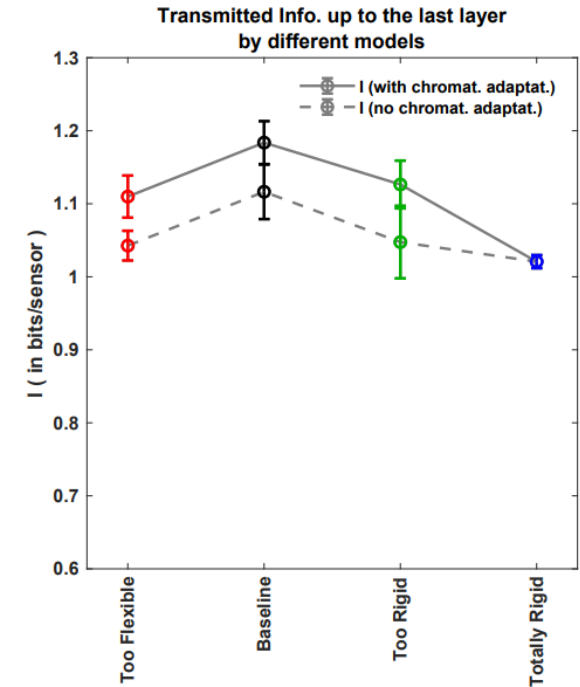
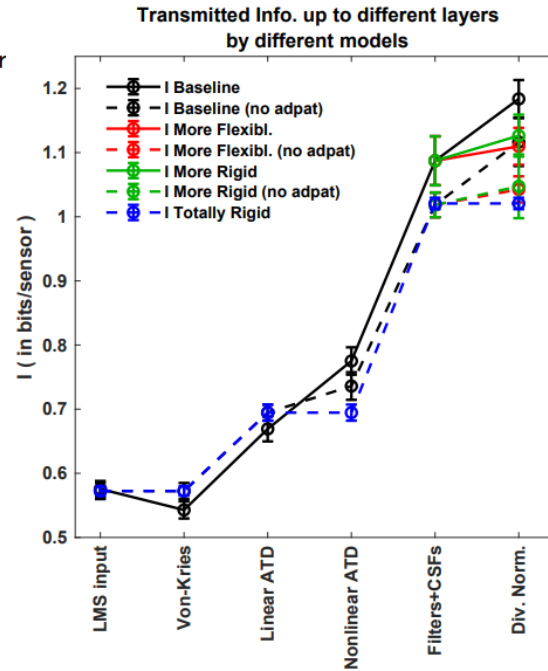
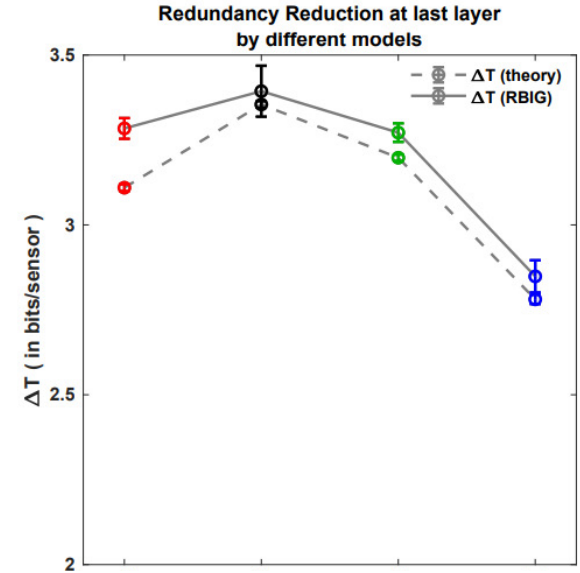
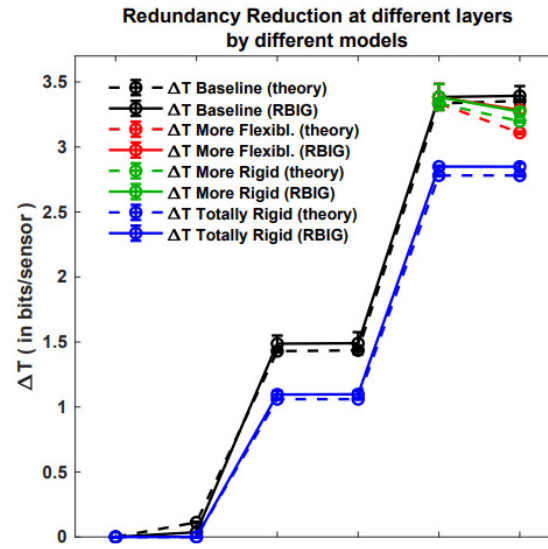
ΔT_{RBIG}

$$\Delta T_{theor} = \sum_i h(x_i^{in}) - h(x_i^{resp}) + E_x \left[\log_2 |\nabla S| \right]$$

Pearson correlation with human viewers using different building blocks (or model layer)

	Spatial Extent	$r^{(1)}$	$r^{(2)}$	$x^{(2)}$	$r^{(3)}$	$x^{(3)}$
More flexible model	(0.27 deg)	0.38	0.38	0.42	0.77	0.51
Baseline model	(0.27 deg)	0.38	0.38	0.42	0.77	0.84
More rigid model	(0.27 deg)	0.38	0.38	0.42	0.77	0.79
Totally rigid model	(0.27 deg)	0.38	0.38	0.38	0.68	0.68
Baseline model	(0.05 deg)	0.26	0.27	0.31	0.37	0.40

Transmitted Information
 $I(x^{in}, x^{resp})$



4 Stats. \rightarrow Biology

Redundancy Reduction
 $\Delta T(x^{input}, x^{resp.})$

ΔT_{RBIG}

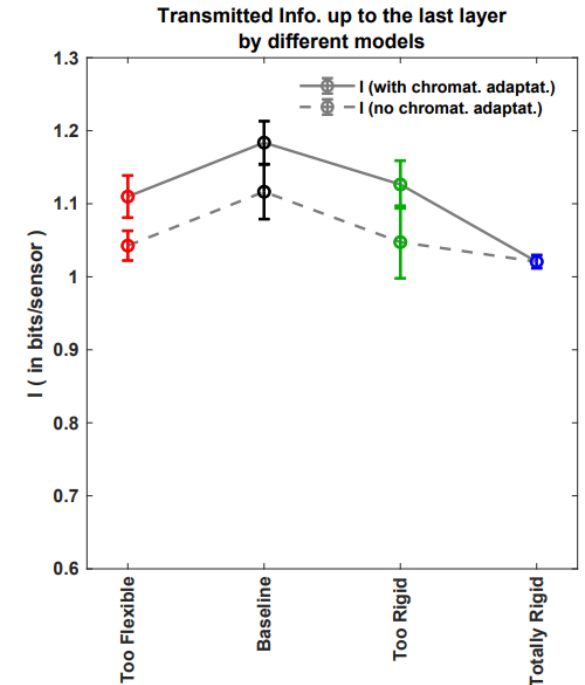
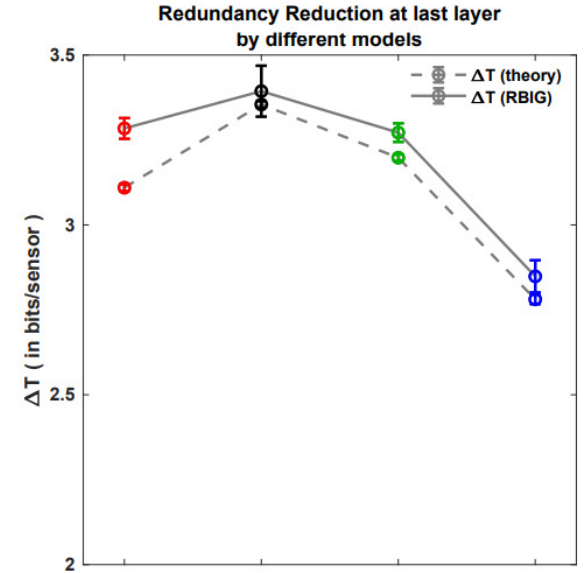
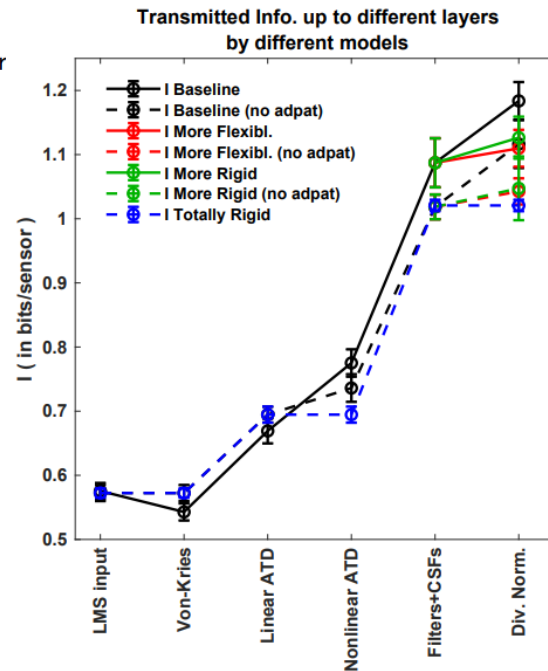
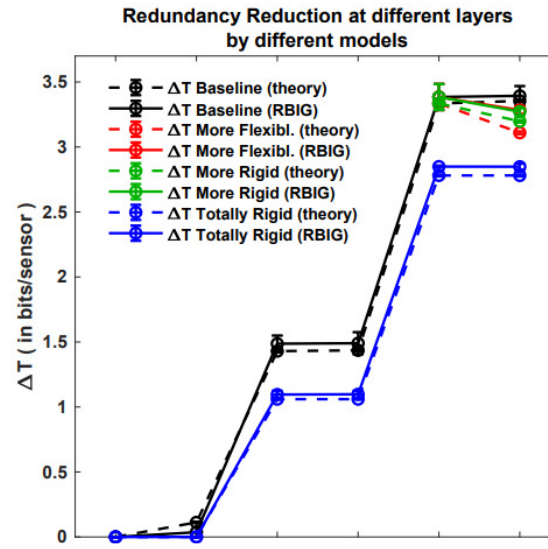
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- Deeper is better
- Baseline is better
- Space vs Color

Transmitted Information
 $I(x^{in}, x^{resp})$



4

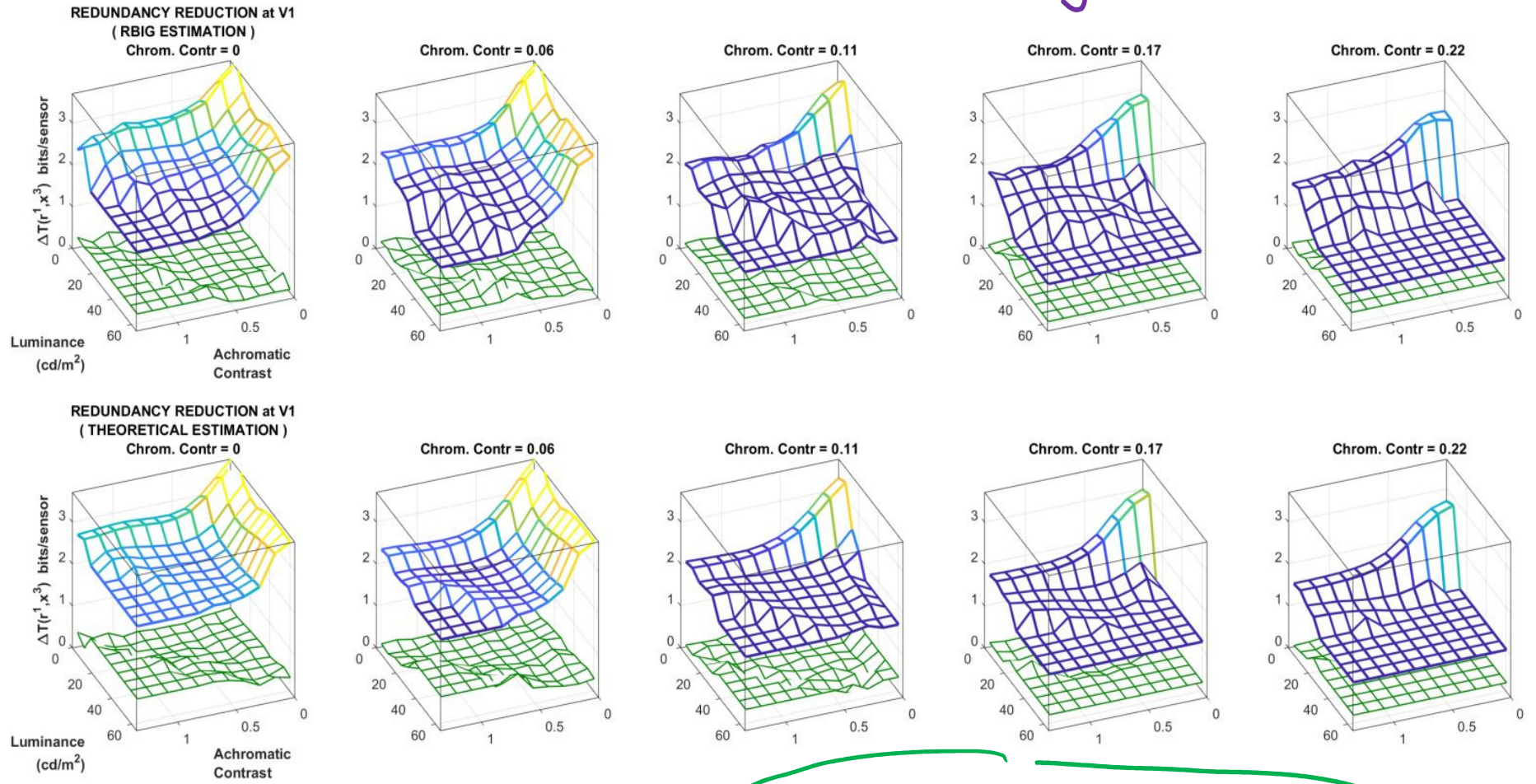
THE TWO SIDES OF THE EFFICIENT CODING HYPOTHESIS:

Stats. \longleftrightarrow Biology

Redundancy Reduction

RBIG

THEORY



RBIG estimates WORK!

37/41

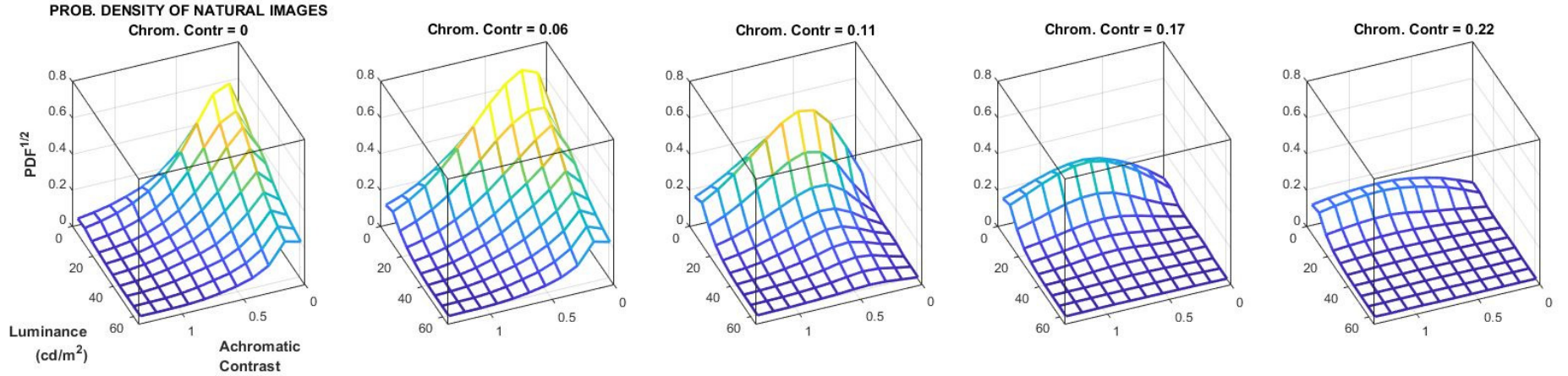
4

THE TWO SIDES OF THE EFFICIENT CODING HYPOTHESIS:

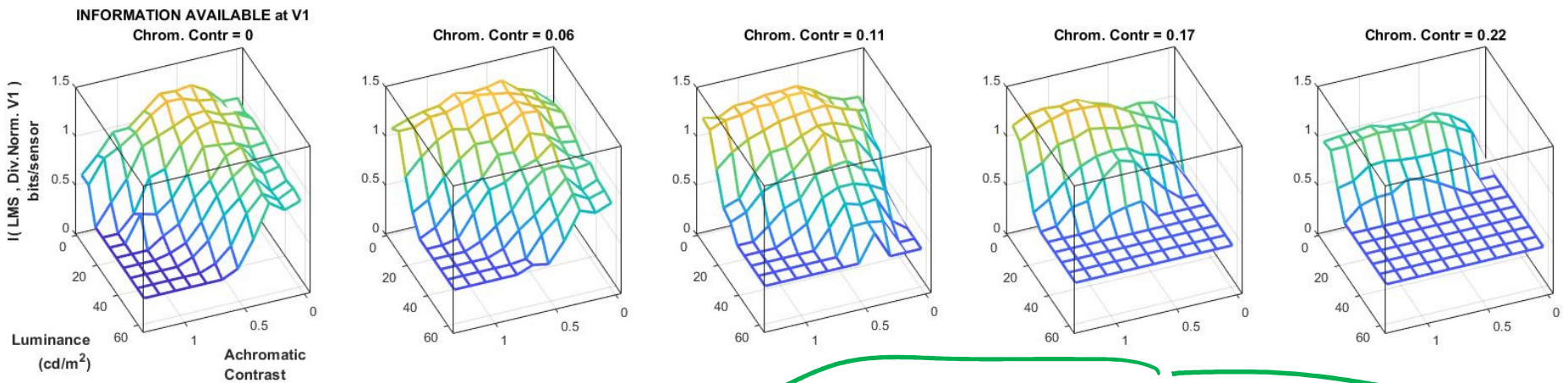
Stats, \longleftrightarrow Biology

Transmitted Information

PDF
Natural Images



$I(\bar{x}_{im}, x_{resp})$



Transmitted info matches PDF

5


CONCLUSIONS & OPEN ISSUES

5

CONCLUSIONS & OPEN ISSUES


⑤ CONCLUSIONS & OPEN ISSUES

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Statistics  Biology

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SPCA explains non-linearities in color/texture/motion

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that's
WHY!

5 CONCLUSIONS & OPEN ISSUES

STATISTICS & MODELS ← BIOLOGY

STATISTICS → BIOLOGY

5 CONCLUSIONS & OPEN ISSUES

STATISTICS & MODELS ← BIOLOGY

- Non reproducible behavior → improve models

- Stronger nonlinearities
- Resolution levels } . Physiol.
 . Psychophys.
- Fit models automatic differentiation

INRF
Wilson-Cow
Div. Neuro.

Bertalmío et al. **Sci. Rep.** 2020
Esteve, Bertalmío, Malo **arxiv** 2020

- Noise models } . Discrimination
 . Information transmission

Esteve et al. **arxiv** 2020

. Better elements for deep-learning

STATISTICS → BIOLOGY

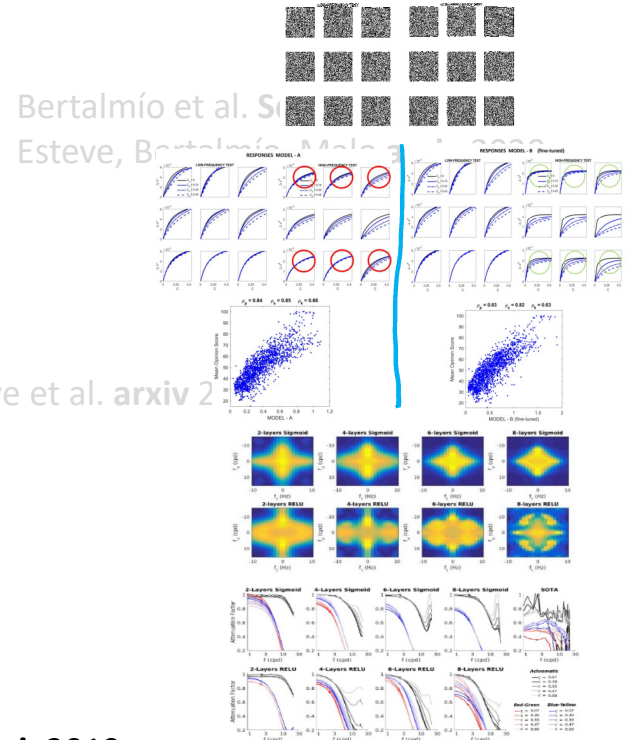
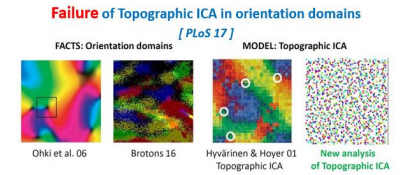
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- Better elements for deep-learning

STATISTICS → BIOLOGY

- Don't miss use deep learning!
- Model-based new psychophysics } . Geometry MAD
- } . Optim. stimuli



Geirhos et al. **Nature** 2020
 Martinez et al. **PLOS** 2017
 Martinez et al. **Front. Neurosci.** 2019
 Li, Gomez, Bertalmio & Malo, **submit. JoV.** 2021

Malo & Simoncelli **SPIE** 2015
 Martinez et al. **PLOS** 2018

